

NASA Technical Memorandum 86410

STEP AND STEPSPL - COMPUTER PROGRAMS FOR
AERODYNAMIC MODEL STRUCTURE DETERMINATION
AND PARAMETER ESTIMATION

(NASA-TM-86410) STEP AND STEPSPL: COMPUTER
PROGRAMS FOR AERODYNAMIC MODEL STRUCTURE
DETERMINATION AND PARAMETER ESTIMATION

N86-21549

(NASA) 142 p HC A07/MF A01

CSCL 01C

Unclass

G3/08 05776

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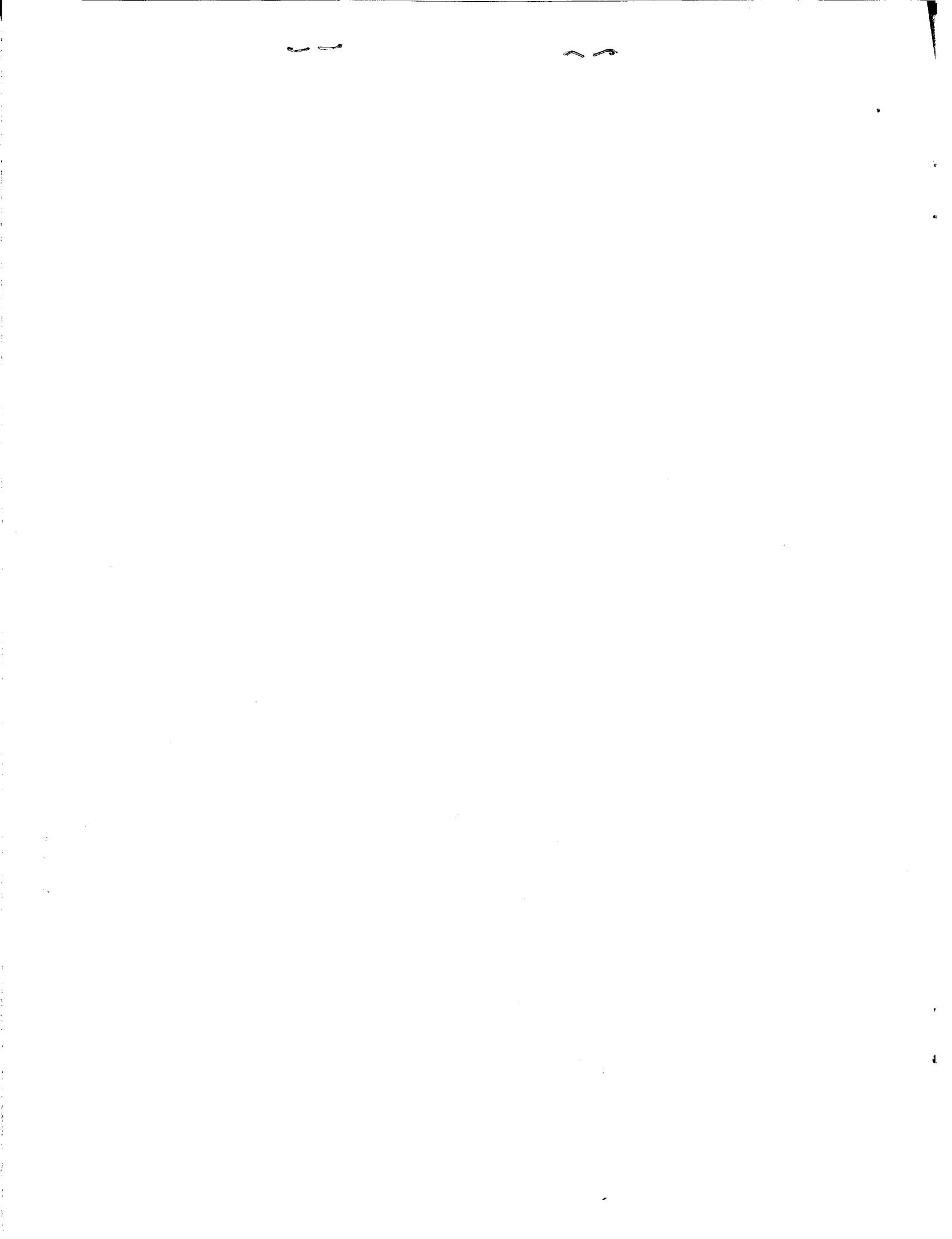
JANUARY 1986



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INTRODUCTION

The successful parametric modeling of the aerodynamics for an airplane operating at high angles of attack or sideslip is performed in two phases. First, the aerodynamic model structure must be determined and second the associated aerodynamic parameters (stability and control derivatives) must be estimated for that model. Though the aerodynamic model structure is known to be linear at low angles of attack, the appearance of nonlinearities at higher angles of attack has been a prominent feature in several recent reports of flight test results (refs. 1, 2, 3). Since a large number of possible nonlinear terms could contribute to the aerodynamic function, some method must be developed that examines only the influential terms while ignoring those that are superfluous. One possibility is to look at all combinations of linear and nonlinear terms. However, as pointed out in reference 4, the number of models to be considered grows too fast with the number of possible terms for such a technique to be practical. The use of stepwise regression was suggested in reference 5. Stepwise regression examines each term as to its usefulness in improving the model (by reducing residual variance). Candidate model terms are added one at a time and/or deleted one or more at a time until no more candidate terms can pass a given test of statistical significance. This provides a least squares equation error estimate of the model structure and associated parameters at each step of the model building.

The stepwise regression technique has been used (refs. 1, 2, 3) for analyzing flight data from high angle-of-attack and large amplitude maneuvers. The purpose of this paper is to document two versions of a stepwise regression computer program which were developed for the determination of airplane aerodynamic model structure and to provide two examples of their use. It is assumed that the reader is familiar with the airplane equations of motion. One should read references 1 and 2 for applications of the technique to actual flight data.

The two computer programs that are the subject of this report, STEP and STEPSPL, are written in FORTRAN IV (ANSI 1966) compatible with a CDC FTN4 compiler. Both programs are adaptations of a standard forward stepwise regression algorithm (ref. 6). The purpose of the adaptation is to facilitate the selection of an adequate mathematical model of the aerodynamic force and moment coefficients of an airplane from flight test data. The major difference between STEP and STEPSPL is in the basis for the model (found in SUBROUTINE DATASET). The basis for models in STEP is the standard polynomial Taylor's series expansion of the aerodynamic function about some steady-state trim condition (see refs. 1 and 3). Program STEPSPL utilizes a set of spline basis functions (refs. 3 and 7).

The paper is organized as follows. After this introduction is a section describing the approach and rationale of the program. The main program and subroutines are each described as to their respective purposes and dimensioning information. Next, a section addresses the interpretation of output based on two examples. There are seven appendices. Appendix A is the listing for STEP. Appendix B is a listing of the NAMELIST/INPUT/for the first example. Appendix C consists of the output for the first example (which demonstrates STEP). Appendix D is a sample job control deck for running the example in a batch mode at the Langley Research Center computer center. Appendix E is the STEPSPL listing. Appendix F contains the output of example 2, (which demonstrates STEPSPL). Finally, appendix G contains a sampling

of options for the spline model basis used in conjunction with STEPSPL. The interested reader can start by running the given test case and then modifying the program to fit his specific use.

STEPWISE REGRESSION

This section describes the basic principles and features of the stepwise regression which is used to determine aerodynamic model structure from flight data. It is assumed that the general structural form of the mathematical model for the aerodynamic force and moment coefficients can be written as

$$y(t) = \theta_0 + \theta_1 x_1(t) + \theta_2 x_2(t) + \dots + \theta_n x_n(t) \quad (1)$$

where

$y(t)$ aerodynamic force or moment coefficient ($C_x, C_y, C_z, C_m, C_\alpha, C_n$) at time t

$x_j(t)$ airplane state plus control variables ($\alpha, q, \beta, p, r, \delta_e, \delta_a, \delta_r$) and their combinations at time t ($j = 1, 2, \dots, n$)

θ_j airplane stability and control coefficients ($j = 1, 2, \dots, n$)

θ_0 constant reflecting and initial steady-state condition.

The forward stepwise regression described in this paper begins with the assumption that there are no variables in the postulated regression equation other than the bias term θ_0 . An effort is then made to find an optimal subset of variables by inserting independent variables into the model one at a time. The first independent variable selected for entry into the equation is the one that has the largest correlation with the dependent variable y . Suppose that this variable is x_1 . This is also the variable that produces the largest value of the F-statistic for testing the significance of regression. The variable is then entered if the partial F-statistic of its associated parameter, $\hat{\theta}_1$, exceeds a preselected critical F-value.

$$F_p = \frac{\hat{\theta}_1^2}{s^2(\hat{\theta}_1)} > F_{crit}$$

where $\hat{\theta}_1$ is the estimated parameter associated with x_1 and $s^2(\hat{\theta}_1)$ is the variance estimate of $\hat{\theta}_1$.

The second variable chosen for entry is the one that now has the largest correlation with y after adjusting for the effect on y of x_1 . These correlations are referred to as partial correlations. In general, at each step, the independent variable having the highest partial correlation with y is added to the model if the partial F-statistic of its associated parameter exceeds the preselected F_{crit} . At each step of the procedure, all variables entered into the model previously are reassessed by examining their corresponding partial F-statistics. A variable added at an earlier step may be redundant because the relationship between

it and the remaining variables now in the equation has reduced its value of F_p to less than F_{crit} . If this happens, the insignificant variable is deleted from the regression model. The procedure terminates when all significant terms have been included in the model.

Five Associated Information Criteria

At each stage of the stepwise regression, as a new variable enters the model, five useful quantities are calculated. All these quantities should be examined for the final model selection. First, the user can consider the total F-value for a given model of Q variables calculated as the ratio of the mean square due to the regression to the mean square of the residual. This ratio is given as

$$F = \frac{\frac{N}{\sum_{i=1}^N (\hat{y}(i) - \bar{y})^2}{N - Q}}{\frac{N}{\sum_{i=1}^N (y(i) - \hat{y}(i))^2}{Q - 1}}$$

where

$$\bar{y} = \frac{1}{N} \sum_{i=1}^N y(i)$$

This number usually increases to some maximum value as new variables enter the regression, but then decreases slightly as the new terms are less effective in reducing the residuals. Heuristically, the maximum F-value represents a model which best fits the data with a minimum number of parameters. Second, the squared multiple correlation coefficient R^2 is calculated. This number, expressed as a percentage, is a measure of the usefulness of the terms, other than θ_0 , in the model. The value of R^2 would be 100 percent for a model that perfectly fit the data. Third, at each stage, the partial F-values F_p for each parameter are printed. The user should look for consistency in the value of F_p . For example, if one value of F_p is only slightly greater than F_{crit} and all other values of F_p are much greater, the user may not want to include the variable with the small value of F_p in the model. The fourth aid in model selection is the estimated normalized autocorrelation function for the residuals. The estimate of the autocorrelation function at lag h is given by

$$\hat{w}(h) = \frac{1}{N-h} \sum_{i=1}^{N-h} v(i) v(i+h) \quad (h = 0, 1, \dots, M)$$

where h is the lag number and M is the maximum lag number, which is usually 10 percent of N . For data sampled each Δt second, the time separation associated with lag h is $h \cdot \Delta t$. The normalized autocorrelation function is calculated as

$\hat{W}(h)/\hat{W}(0)$. This function should approach that for white noise with a value of 1 at zero lag and values of 0 at lags of 1 to M . In applications, when the value of F_p for a parameter makes the utility of an independent variable questionable, the contribution of that variable to the actual model structure can be assessed by observing the effect of the variable on the autocorrelation function of residuals. The fifth number that is useful is the standard error in the residuals, $\hat{\sigma}$, which is printed at each stage of the regression.

One learns from experience that not all of the five criteria listed above are "optimally" satisfied for any single model. However, the stepwise regression and its associated information criteria do significantly reduce the number of possible models from which the user must choose. Moreover, as the model structure is determined, so are the parameter estimates. Finally, ambiguity in the model selection can also be resolved by requiring that the estimated parameters make sense physically and that the selected model have good prediction capability.

Selection of Candidate Model Variables

The selection of a set of candidate model variables from which the stepwise regression can build a model should rely on the user's a priori knowledge of the physical system that is to be modeled. For the airplane, assumptions as to the most influential variables and symmetry considerations have led to the following logic for selection of candidate model variables for a spline analysis of the longitudinal maneuver. The range of the independent variable which is most important in the determination of the dependent variable is partitioned into several subsets, each having support on less of the range than the previous subset. For example, the force coefficient C_Z is mainly dependent on α . Hence if $\alpha = \{z | a \leq z \leq b\}$, then the α range, $[a, b]$, is divided according to the spline basis functions as follows:

$$(\alpha - \alpha_i)_+^m \equiv \begin{cases} (\alpha - \alpha_i)^m & (\alpha \geq \alpha_i) \\ 0 & (\alpha < \alpha_i) \end{cases}$$

The values of α_i are called knots. An example of the "+" function is given in figure 1. The four knots in this figure are at $\alpha = 2^\circ, 4^\circ, 6^\circ$, and 8° . Hence,

$$(\alpha - \alpha_1)_+^0 = 1 \text{ for } \alpha \geq \alpha_1 = 2^\circ, \text{ and } (\alpha - \alpha_1)_+^0 = 0$$

for $\alpha < \alpha_1$. Similarly,

$$(\alpha - \alpha_2)_+^0 = 1 \text{ for } \alpha \geq 4^\circ, \text{ and } (\alpha - \alpha_2)_+^0 = 0 \text{ for } \alpha < 4^\circ,$$

and so forth, for the rest of the "+" functions. If the order of the "+" function, denoted by the superscript m is other than zero, say 2, then

$$(\alpha - \alpha_1)_+^2 = (\alpha - \alpha_1)_+^2 \text{ for } \alpha \geq \alpha_1 \text{ and}$$

$$(\alpha - \alpha_1)_+^2 = 0 \text{ for } \alpha < \alpha_1.$$

Hence, the vertical force coefficient C_Z can be represented as:

$$C_Z = C_{Z,0} + C_{Z,\alpha} \alpha + \sum_{i=1}^K C_{Z,\alpha_i} (\alpha - \alpha_i)_+ + C_{Z,q} \frac{q\bar{c}}{2V} + \sum_{i=1}^K C_{Z,q_i} (\alpha - \alpha_i)_+^0 \frac{q\bar{c}}{2V}$$

$$+ C_{Z,\delta_e} \delta_e + \left(C_{Z,\delta_e} \right)_7 \delta_e (\alpha - \alpha_7)_+^0 + \left(C_{Z,\delta_e} \right)_{13} \delta_e (\alpha - \alpha_{13})_+^0$$

Though it appears lengthy and awkward, the following formulation of the FORTRAN code allows for simple deletion, addition, and/or change in candidate model variables.

```

DO 910 I=1,NPTS
X(1,I)=ALPH(I)
X(2,I)=C/(2*VEL(I))*Q(I)
X(3,I)=DELE(I)
DO 911 III=4,39
911 X(III,I)=0.
IF (ALPH(I).GE.XKNOT(1)) X(4,I)=ALPH(I)-XKNOT(1)
IF (ALPH(I).GE.XKNOT(1)) X(5,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(2)) X(6,I)=ALPH(I)-XKNOT(2)
IF (ALPH(I).GE.XKNOT(2)) X(7,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(3)) X(8,I)=ALPH(I)-XKNOT(3)
IF (ALPH(I).GE.XKNOT(3)) X(9,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(4)) X(10,I)=ALPH(I)-XKNOT(4)
IF (ALPH(I).GE.XKNOT(4)) X(11,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(5)) X(12,I)=ALPH(I)-XKNOT(5)
IF (ALPH(I).GE.XKNOT(5)) X(13,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(6)) X(14,I)=ALPH(I)-XKNOT(6)
IF (ALPH(I).GE.XKNOT(6)) X(15,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(7)) X(16,I)=ALPH(I)-XKNOT(7)
IF (ALPH(I).GE.XKNOT(7)) X(17,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(8)) X(18,I)=ALPH(I)-XKNOT(8)
IF (ALPH(I).GE.XKNOT(8)) X(19,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(9)) X(20,I)=ALPH(I)-XKNOT(9)
IF (ALPH(I).GE.XKNOT(9)) X(21,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(10)) X(22,I)=ALPH(I)-XKNOT(10)
IF (ALPH(I).GE.XKNOT(10)) X(23,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(11)) X(24,I)=ALPH(I)-XKNOT(11)
IF (ALPH(I).GE.XKNOT(11)) X(25,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(12)) X(26,I)=ALPH(I)-XKNOT(12)
IF (ALPH(I).GE.XKNOT(12)) X(27,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(13)) X(28,I)=ALPH(I)-XKNOT(13)
IF (ALPH(I).GE.XKNOT(13)) X(29,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(14)) X(30,I)=ALPH(I)-XKNOT(14)
IF (ALPH(I).GE.XKNOT(14)) X(31,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(15)) X(32,I)=ALPH(I)-XKNOT(15)

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IF (ALPH(I).GE.XKNOT(15)) X(33,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(16)) X(34,I)=ALPH(I)-XKNOT(16)
IF (ALPH(I).GE.XKNOT(16)) X(35,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(17)) X(36,I)=ALPH(I)-XKNOT(17)
IF (ALPH(I).GE.XKNOT(17)) X(37,I)=X(2,I)
IF (ALPH(I).GE.XKNOT(7)) X(38,I)=X(3,I)
IF (ALPH(I).GE.XKNOT(13)) X(39,I)=X(3,I)

```

910 CONTINUE

In the preceding printout, $VEL(I)$ = airspeed V at t_i , Q = pitch rate q , $NPTS$ = number of data points N , C = wing mean aerodynamic chord c , and $X(J,I)$ = value of j th model variable at t_i . The symbols $XKNOT()$ indicate knots for specific values of α . The code above actually gives the logic for creating the $(39 \times N)$ matrix containing the time histories of each of the 39 candidate independent variables. The 17 knots in angle of attack can be set at any value the user deems adequate for the data by setting $XKNOT(I)$ in the program with $I = 1, 17$. Changing the candidate model variables can easily be accomplished by substituting the new variable for any of the 39 candidate variables listed. The number of candidate variables is limited only by the size of the computer memory.

DESCRIPTION OF PROGRAM STEP

Main Program

The main program for STEP is dimensioned to accept measurements of flight data at 500 time points. For example, at a data rate of 20 points per second, this dimensioning allows 25.0 seconds of data to be used. The main program includes all logic for the actual regression procedure as well as most of the printing logic. The namelist INPUT is read in the main program. This namelist contains data for airplane mass, geometry and inertia characteristics, initial conditions, option switches and starting time. The namelist will be discussed in detail below. The main program also does all calculations involving the correlation matrix and analysis of variance. It provides for the printing of the partial F-values for variables in the regression, the estimates of their coefficients and standard errors of those coefficients. The total F-value for the model, the percent variation from the mean explained by the regression model, and the variance of the residual sequence are also printed from the main program.

Dimensions - As mentioned, most data arrays are dimensioned 500 to accommodate a maximum of 25 seconds of data at a rate of 20 points per second. However, this and other dimensions may be adjusted by the user to conform to individual computer capability. This section is written to aid the user in such changes. Let $MAXNPTS$ be the maximum number of data points to be analyzed and $N-1$ be the maximum number of independent variables to be considered for the regression. For example $N-1$ is 24 in STEP since the lateral equations have 24 candidate model variables as seen from the X array in lines 79 through 102 of subroutine DATASET (appendix A). The dimensions for arrays in STEP are as follows:

T , Y , $YHAT$, XNU , AX , AY , AZ , $PDOT$, $QDOT$, $RDOT$, VEL , P , Q , R , and QQ are each dimensioned $MAXNPTS$

X is the two-dimensional data array and should be dimensioned $N \times MAXNPTS$

S and $XXSUM$ are two-dimensional work arrays and are dimensioned $N \times N$

ICNT, IORD, B, V, STDER, FPART, TN, PPLT, FPLT, XSUM, XBAR, SIGMA, ,
PPRT are each dimensioned N

W and XLAG are arrays for the autocorrelation function and its lag number.
They should be dimensioned at least MAXNPTS/10.

APR is used in the calculation of the PRESS (Prediction Error Sum of Squares) criterion. It is a two-dimensional array with dimensions N × (MAXNPTS + N).

RR, A, AP are two-dimensional arrays containing variance and covariance information and are dimensioned (2N-1) × (2N-1).

Namelist Input - A namelist called INPUT communicates airplane geometry, mass and inertia characteristics as well as initial conditions and logic switches for program options. The elements of INPUT and their definitions are listed alphabetically as follows:

ALPHT - angle of attack trim value (radians)

BETT - angle of sideslip trim value (radians)

BSPAN - wing span (meters)

CBAR - wing mean aerodynamic chord (meters)

DELAT - aileron displacement at trim (radians)

DELET - elevator deflection at trim (radians)

DELRT - rudder displacement at trim (radians)

FCRT - critical F-value for entry or elimination of a term in the model

A nominal value between 5 and 10 for FCRT has proven effective from experience with high angle-of-attack airplane data.

G - acceleration due to gravity (m/sec²)

IACELOP - option switch to read angular accelerations from data

0 - read from data

1 - calculate by cubic spline subroutine

IEQN - indicates which equations are to be fit:

If LATOP = 0 then IEQN = 1 for C_x
2 for C_z
3 for C_m

If LATOP = 1 then IEQN = 1 for C_y
2 for C_l
3 for C_n

IFILOP - option switch to incorporate low pass filter on lateral acceleration measurements

IFILOP = 1 for filter active

IFILOP = 0 for filter inactive

IFLAG - option switch to have first LINMAX terms considered before any other terms. LINMAX is set in the main program.
IFLAG = 1 activates the option
IFLAG = 0 all terms are searched from the first pass on

LINMAX is set to 3 in line 38 of Program STEP (appendix A) for the longitudinal option (LATOP = 0) and 5 in line 40 for the lateral option (LATOP = 1). These values allow for consideration of the first three candidate model variables α , q , and δ_e for the longitudinal equations and the first five candidate model variables β , p , r , δ_a , and δ_r for the lateral equations. To consider any J terms first, in general, Linmax should be set to J and those J terms should be the first J terms entered into the two-dimensional X array in SUBROUTINE DATASET.

IPLOT - option to activate plotting
IPLOT = 1 activates plotting
IPLOT = 0 for no plotting

IPRESOP - option to invoke PRESS calculation
IPRESOP = 1 activates option
IPRESOP = 0 for no PRESS calculation

IPSKP - For IPRESOP = 1, IPSKP selects every (IPSKP)-th point for calculation of PRESS

ITRIMOP - option switch to read trim values from first data point to be analyzed. If ITRIMOP = 1, the namelist supplied values (or default values of 0) for ALPHT, BETT, DELAT, DELET, DELRT are used. If ITRIMOP = 0, the values of angle of attack, angle of sideslip, aileron deflection, elevator deflection and rudder deflection at time TS are used for ALPHT, BETT, DELAT, DELET, DELRT, respectively.

IX - moment of inertia about longitudinal body axis (kg m^2)

IXZ - product of inertias (kg m^2)

IY - moment of inertia about lateral body axis (kg m^2)

IZ - moment of inertia about vertical body axis (kg m^2)

LATOP - option switch for lateral equations
LATOP = 1 for fitting lateral equations
LATOP = 0 for fitting longitudinal equations

M - airplane mass (kg)

NEQ - the number of equations to be fit (as opposed to IEQN which indicates which NEQ equations are to be fit). NEQ can be 1, 2, or 3.

NPTS - number of data points to be fit

PT - roll rate trim value (rad/sec)

QT - pitch rate trim value (rad/sec)

RHO - atmospheric density (kg/m^3)

RT - yaw rate trim value (rad/sec)

SAREA - wing area (m^2)

TS - starting time for data to be fit

Subroutines

SUBROUTINE DATASET - The purpose of SUBROUTINE DATASET is to read flight data from a file (TAPE 1) into the program and to set up the data array of time histories of the candidate independent model variables. The candidate variables for both the longitudinal and lateral options are given in Table 1. The user can easily change any of the candidate model variables in the table to meet his own needs. The candidate model variables presented here have proven to be useful in the work reported in reference 1.

The number of candidate model variables is limited only by the size of computer memory. Any changes in the number of candidate model variables in the X array of SUBROUTINE DATASET should be reflected in the value of N in the main program and possibly the dimensions which depend on N throughout the program.

SUBROUTINE DATASET also calls a cubic spline differentiation subroutine (SUBROUTINE SECDER AND FUNCTION DERSP) for the calculation of angular accelerations from the measured angular rates. These calls can be eliminated as can the SUBROUTINE SECDER and FUNCTION DERSP if the user has measured angular accelerations available.

SUBROUTINE AUTO - The normalized autocorrelation function for the residual sequence is calculated. XLAG and W must be dimensioned at least MAXNPTS/10.

SUBROUTINE FIL - This subroutine is a low pass filter for the smoothing of data in the time domain. The algorithm is taken from reference 8. When this filter routine is active (IFILOP = 1) the user must choose FC and FT (which define the frequency range in Hz for band pass roll off) in this subroutine so that H(I), I = 1, NPTS/2 is always defined.

Subroutines for PRESS calculation - STEP and STEPSPL programs use six subroutines for PRESS calculations. The main program calls upon three primary routines: PRESS, UPDATE, and PSET. These in turn call on three secondary routines: REDEF, INTRCHG, and RANDOM. Subroutines PRESS and UPDATE are called during each pass as model variables are added or deleted. The PRESS routine simply computes the value of PRESS associated with each candidate variable. This is done without any effect on the regular stepwise regression calculations. Subroutine UPDATE is used to modify the normal equations to reflect the change in model variables during each pass. A separate set of normal equations is used by PRESS so that the stepwise regression and PRESS calculations can proceed independently.

Subroutine PSET is called once at the start of a run to establish the dataset to be used in the PRESS computations. As described in reference 1, for a large number of data points PRESS approaches the residual sum of squares (RSS). Therefore it may be necessary when handling large datasets (number of points greater than 100) to use a reduced number of data points. The IPSKP variable controls the number of data points to be used by PRESS. The selection of 30 to 40 points has proven to be best. IRAN = 1 is the flag which indicates the reduced dataset is to be randomly selected.

The secondary routines RANDOM, REDEF, and INTRCHG provide a few simple operations. RANDOM returns a uniformly distributed random variable which is used to randomly select data when required by PSET. Subroutine INTRCHG is used by UPDATE to interchange rows and columns in the normal equation matrices. Subroutine REDEF is an initializing routine used to prepare the appropriate matrices for PRESS computations.

DESCRIPTION OF PROGRAM STEPSPL

STEPSPL differs from STEP mainly in the dimensions of arrays and in the SUBROUTINE DATASET. Program STEPSPL is dimensioned to accept data lengths of 900 points (45 seconds of data at 20 points per second). There is provision for 39 independent variables which will be spline "+" functions and for 23 spline knots. The "+" function is defined as $(\Delta\alpha)_+^m \equiv (\alpha - \alpha_k)_+^m \stackrel{\Delta}{=} (\alpha - \alpha_k)_+^m$ if $\alpha \geq \alpha_k$, $(\Delta\alpha)_+^m \stackrel{\Delta}{=} 0$, if $\alpha < \alpha_k$, where α_k is the value of the kth knot in angle of attack in radians.

Example 2 demonstrates the use of STEPSPL. Appendix E contains the STEPSPL listing.

Dimensions - Let MAXNPTS be the maximum number of points to be analyzed and let $N - 1$ be the maximum number of independent variables to be considered. The dimensions of arrays are as follows: T, Y, YHAT, XNU, AX, AY, AZ, PDOT, QDOT, RDOT, VEL, P, Q, R are each dimensioned MAXNPTS.

X is the two-dimensional data array and is dimensioned $N \times \text{MAXNPTS}$.

S and XXSUM are two-dimensional work arrays and are dimensioned $N \times N$.

ICNT, B, V, STDER, FPART, XSUM, XBAR, and SIGMA are each dimensioned N.

W and XLAG are arrays for the autocorrelation function and its lag number. They should each be dimensioned at least MAXNPTS/10.

RR, A, and AP are two-dimensional arrays containing variance and covariance information and are dimensioned $(2N - 1) \times (2N - 1)$.

Namelist Input - The namelist for STEPSPL is the same as that for STEP with the exception of the variables IPRESOP, and IPSKP which apply to PRESS subroutines not found in STEPSPL.

USING STEP AND STEPSPL

Aids in the Selection of an Adequate Model

Since there is no cost function which ensures that the best model has been found, STEP and STEPSPL provide a subset of all possible models. From this subset, one must make the selection of an adequate model for the data at hand. To assist in the selection of an adequate model, the programs provide several statistical and informational parameters at each step of the fitting process. These parameters are as follows:

1. The partial F-values for the coefficients of all variables that are currently in the model.

2. The total F-value associated with the current model.
3. The square of the correlation coefficient in percent corresponding to the percent variation from the mean of the data that is explained by the current model.
4. The Prediction Sum of Squares (PRESS) criterion - The scalar PRESS, corresponding to the ℓ th subset of model variables, is defined as

$$\text{PRESS} = \sum_{i=1}^N \{y(i) - \hat{y}[i/x(1), \dots, x(i-1), x(i+1), \dots, x(N)]_\ell\}^2$$

where $y(i)$ is the i th response of the system and $\hat{y}(i/\dots)_\ell$ is the least squares estimate of $E\{y(i)\}$ for the ℓ th subset. Note the i th observation, $x(i)$, is not used in forming the estimate $\hat{y}(i/\dots)_\ell$. The model corresponding to the smallest value of PRESS is the best predictor model. It is also a parsimonious model since PRESS reflects the added cost of redundant model variables.

5. The standard deviation of the residual. This should approach that calibrated for the instrument used to measure the dependent variable.

Also at each point in the selection process the user is provided with a synopsis of variables currently in the model as well as the estimates of the coefficients of those variables and the standard error of those estimates.

Example 1

In this example STEP is run on a simulated data set. The program listing is found in appendix A. The simulated data set to which the program STEP is applied is a subset of the time history for the mathematical model given in figure 2. The subset consists of the 43 points corresponding to an angle of attack in the range $14^\circ < \alpha < 16^\circ$. The true values for the parameters in this range are

$$C_{X_\alpha} = 0.700 \quad C_{Z_\alpha} = -3.00 \quad C_{m_\alpha} = -1.00$$

$$C_{X_q} = 0.0 \quad C_{Z_q} = -20.0 \quad C_{m_q} = +15.0$$

$$C_{X_{\delta e}} = 0.05 \quad C_{Z_{\delta e}} = -1.10 \quad C_{m_{\delta e}} = -1.00$$

The namelist/INPUT/for this example is found in appendix B and the output listing is in appendix C. In examining the namelist/INPUT/it is seen that:

1. IPRESOP = 0 - No PRESS calculation will be made; with PRESS inactive, processing time is cut by about a factor of 2.
2. TS = 0.0 - The first data point to be considered for fitting is that corresponding to time 0.0 sec on the data tape.
3. NEQ = 3 - All 3 equations corresponding to the choice of LATOP will be fit.
4. IEQN = 1, 2, 3 - The NEQ equations to be fit are 1, 2, and 3.
5. NPTS = 43 - 43 datapoints after TS are to be fit.
6. IPLOT = 1 - The program will plot the measured and computed time histories, residual sequence, and autocorrelation sequence at each step of the regression. If PRESS is active, IPLOT = 1 will also allow for the plotting of a synopsis of F-values and PRESS values after the last significant variable has been added to the model.
7. IFLAG = 1 - Selects the option whereby the first LINMAX terms are considered before any others. These terms correspond to a linear model.
8. SAREA = 13.74 - The wing area for the airplane is 13.74 m².
9. BSPAN = 9.98 - The airplane wingspan is 9.98 m.
10. CBAR = 1.40 - The airplane wing mean aerodynamic chord is 1.40 m.
11. M = 1055 - The airplane has a mass of 1055 kg.
12. RHO = 1.0272 - The mean atmospheric density during the maneuver was 1.0272 kg/m³.
13. G = 9.81 m/sec² - is the gravitational acceleration constant.
14. IX = 2357 - The moment of inertia about the longitudinal body axis is 2357 kg m².
15. IY = 3051 - The moment of inertia about the lateral body axis is 3051 kg m².
16. IZ = 4833 - The moment of inertia about the vertical body axis is 4833 kg m².
17. IXZ = 177. - The product of inertia is 177 kg m².
18. DELET = -0.08318 - The elevator displacement at trim initial conditions is -0.08318 rad.
19. ALPHT = 0.2095 - The trim angle of attack is 0.2095 rad.
20. BETT = 0 - The trim angle of sideslip is 0. rad.
21. DELAT = 0 - The aileron displacement to trim is 0. rad.

22. DELRT = 0 - The rudder displacement to trim is 0. rad.
23. QT = 0 - Trim pitch rate is 0. rad/sec.
24. PT = 0 - Trim roll rate is 0. rad/sec.
25. RT = 0 - Trim yaw rate is 0. rad/sec.
26. FCRT = 5 - The critical partial F-value for entry into the regression is 5.
27. ITRIMOP = 1 - The trim values provided in this namelist will be used as opposed to the values of the associated variables at time TS.
28. IPSKP = 10. - Indicates the the PRESS option, if activated by IPRESOP = 1, should select every 10th point for the evaluation of the PRESS.
29. LATOP = 0 - Indicates that the longitudinal equations are to be considered for the fitting.
30. IAECLOP = 0 - Indicates that angular accelerations will be read directly from the data string.
31. IFILOP = 0 - Indicates that the low pass filter will be inactive.

After the namelist, the trim values for angle of attack, angle of sideslip, aileron, elevator, and rudder are printed. The output is continued in appendix C with a line of header information and a run identifier from the data tape, the value of IEQN and the number of points to be fit printed. It is seen that for RUN 1, equation (1) (C_x since the longitudinal option is active), is to be fit for 43 data points (NPTS = 43). If an even number of points is specified for NPTS in the namelist, that number will be decreased by 1 by the program so that NPTS is always odd.

Next is a listing of the relevant data for the points being fit. Here, for the longitudinal option, time, velocity, angle of attack, pitch rate, and elevator deflection are listed. If the lateral option had been chosen (LATOP = 1), then time, velocity, angle of sideslip, roll rate, yaw rate, aileron deflection, and rudder deflection would have been printed.

The next line indicates that the highest correlation between the measured dependent variable (a_x here since LATOP = 0 and IEQN = 1) and an independent variable is for the first model variable, which is angle of attack. The partial F-value for this variable is 878, and its entry accounts for 95 percent of the variation. The standard deviation of the residual sequence ($a_{x_{\text{measured}}} - a_{x_{\text{computed from model}}}$) is 0.00139. The total F-value for this model is 857.

The next line gives the least squares estimates for parameters currently in the model. The order of the estimates is the same as the entry of data into the X array in SUBROUTINE DATASET. Below the parameter estimates is found the estimated standard error for that estimate. Here, $C_{X_\alpha} = 0.651$ with $\sigma_{C_{X_\alpha}} = 0.022$ and the model for C_X is at this stage:

$$C_X = C_{X_0} + C_{X_\alpha} (\alpha - \alpha_0)$$

$$= 0.000229 + 0.651 (\alpha - \alpha_0)$$

An optional visual aid is provided in the form of a plot. An example of the plot and its interpretation is given for the STEPSPL program in example 2.

The next variable chosen for the regression is variable 3, δ_e , with a partial F-value of 5.59×10^8 . Since the entry of this term explains essentially 100 percent of the variation, it enhances the partial F-value of variable 1 also. The standard deviation of the residual sequence is now 0.38×10^{-6} and the F-value for the model is 5.98×10^9 .

The new parameter estimates are $C_{X_\alpha} = 0.700$ and $C_{X_{\delta e}} = 0.050$. The respective standard errors are $\hat{\sigma}_{C_{X_\alpha}} = 0.61 \times 10^{-5}$ and $\hat{\sigma}_{C_{X_{\delta e}}} = 0.20 \times 10^{-5}$ and the model is

$$C_X = C_{X_0} + C_{X_\alpha} (\alpha - \alpha_0) + C_{X_{\delta e}} (\delta e - \delta e_0)$$

$$= 0.000063 + 0.700 (\alpha - \alpha_0) + 0.05 (\delta e - \delta e_0)$$

This completes the fitting of the C_X equation.

Next, RUN 1, equation (2) is to be fit. Equation (2) (for LATOP = 0) corresponds to the C_Z force coefficient. Again 43 points are to be fit. The most significant of the first three variables (since IFLAG = 1, the first LINMAX = 3 are considered) is variable 2, q. With 58.76 percent of the variation explained, the model at this point is

$$C_Z = C_{Z_0} + C_{Z_q} \frac{qc}{2V}$$

$$= -1.31 - 15.0 \frac{qc}{2V}$$

Next variable 3, δe , is added as being most highly correlated to the residual sequence of the previous model. With entry of the δe term, 72.64 percent of the variation is explained and the model is now

$$C_Z = C_{Z_0} + C_{Z_q} \frac{qc}{2V} + C_{Z_{\delta e}} (\delta e - \delta e_0)$$

$$= -1.34 - 17.8 \frac{qc}{2V} - 0.705 (\delta e - \delta e_0)$$

With the entry of the variable 1, α , 100 percent of the variation is explained and the final model is simply the complete linear model.

$$C_Z = C_{Z_0} + C_{Z_\alpha} (\alpha - \alpha_0) + C_{Z_q} \frac{qc}{2V} + C_{Z_{\delta e}} (\delta e - \delta e_0)$$

$$= -1.21 - 3.00 (\alpha - \alpha_0) - 20.0 \frac{qc}{2V} - 1.10 (\delta e - \delta e_0)$$

The third and final equation to be fit in example 1 is the pitching moment equation. The process goes as in the equations (1) and (2) with the first three terms incorporated into the model. With the linear model completed, the model equation is

$$C_m = -0.731 - 1.05\alpha + 15.3 \frac{qc}{2V} - 0.996 (\delta e - \delta e_0)$$

and explains 99.9 percent of the variation. However, the program adds, in the next step, variable 7. Note that the partial F-value of 29 for this variable is much less than and totally out of line with the first three terms (with partial F-values of 2960., 5530., and 20,300.). Hence, the user might consider this last term to be superfluous and retain the linear model from the previous step. The unexplained 0.06 percent has been contributed by the spline differentiation of q to obtain q_c . When data for accelerations were read directly from the simulation program, 100 percent of the variation was accounted for.

Example 2

This example demonstrates the use of STEPSPL. STEPSPL is the basic STEP program with some dimension changes to allow for longer data lengths and the spline basis functions incorporated into SUBROUTINE DATASET. The simulated data for this example was generated by numerically integrating a model given by:

$$C_X = -0.180 + 0.700\alpha + 0.050 (\delta e - \delta e_0)$$

$$C_Z = 0.112 - 5.00\alpha + 2.00 (\alpha - 0.2269)_+ + 1.50 (\alpha - 0.3142)_+$$

$$- 10.0 \frac{qc}{2V} - 10.0 (\alpha - 0.2269)_+^0 \frac{qc}{2V} - 10.0 (\alpha - 0.3142)_+^0 \frac{qc}{2V}$$

$$- 0.800 (\delta e - \delta e_0)$$

$$C_m = 0.105 - 0.400\alpha - 0.600 (\alpha - 0.2269)_+ - 1.00 (\alpha - 0.3142)_+$$

$$- 15.0 \frac{qc}{2V} + 10.0 (\alpha - 0.1745)_+^O \frac{qc}{2V} + 10.0 (\alpha - 0.2269)_+^O \frac{qc}{2V}$$

$$- 10.0 (\alpha - 0.3142)_+^O \frac{qc}{2V}$$

$$- 2.00 (\delta e - \delta e_o)$$

This longitudinal model is integrated using an elevator doublet input string. Random noise (with Gaussian distribution, zero mean, and $\sigma = 0.003$) was added to pitch rate q . This σ corresponds to ground calibration measurement error for the pitch rate gyro in previous flight testing. This σ should yield a σ of 0.08 for q and 0.023 for C_m .

Appendix E gives the results of applying STEPSPL to the noisy data sequence. The first information written is the namelist so that the user may quickly confirm that all elements on the list are correct. In this example, it is seen that only one equation (NEQ = 1) is to be fit. That is the third equation (IEQN = 3) which is the pitching moment equation since LATOP = 0. With IAECLOP = 1, the spline subroutines are called to numerically differentiate the angular rate in order to derive angular accelerations. Since there is no PRESS option with STEPSPL, the PRESS associated options of example 1 are absent. Otherwise all INPUT options are the same as in example 1.

After the namelist, there is a listing of the angles of attack corresponding to cardinal knot positions. Following the knot values is a listing of trim conditions that the program will be using. Next is a line of header information giving a run identification number, the equation to be fit and the number of points to be fit. Here, it is seen that RUN 1, Equation 3 (C_m) is to be fit and 239 points will be used. Next the relevant data is printed. Since the longitudinal option has been selected, these data are time, airspeed, angle of attack, pitch rate and elevator deflection.

Following the data listing is the actual fitting information. The overall listing of information is the same as described in example 1 for STEP. The major difference is in the number of candidate model variables (which is now 39 plus a bias term). The maximum partial F-value (349.) is associated with the variable number 3, elevator deflection. The percent variation explained by the addition of this variable is 59.49 percent leaving a standard deviation of the residual sequence of 0.07. The parameter $C_{m\delta e}$ is estimated as -2.31 with a standard error of 0.12. The bias term, $C_{m\delta e}^o$, is estimated to be -0.000723. The next term selected by STEPSPL is variable 1, angle of attack. The listing now shows that variables in positions 1 and 3 are in the regression (by the "1's" in those positions). The percent variation explained by this model is 89.65 percent leaving a standard deviation of the residual sequence of 0.036. The total F-value for this model is 1022. The parameter estimates are:

$$C_{m_0} = 0.246$$

$$C_{m_\alpha} = -1.05 (\pm 0.040)$$

$$C_{m_{\delta e}} = -2.09 (\pm 0.063)$$

The process continues until the entry of variable 13 corresponding to q ($\alpha = 0.1571$)⁰, the knot at $\alpha = 9^\circ$ ($9^\circ = 0.1571$ rad). The final estimated model is given in Table 2 and in figure 3, where it is compared with the true model used to generate the data. Though some of the values given in table 2 appear to be bad, it is seen from figure 3 that the overall model is very good. The program has approximated the one knot in C_{m_q} at 10° by two knots: one is at 9° and the other is at 11° . Thus, the table of values does not offer as good a feeling for the model as does the figure.

In addition to the printout that has been discussed for this example and example 1, a plotting option is available. The subroutines used in the listings provided for STEP and STEPSPL are local to the LaRC computer center, but the user may combine whatever software is at his disposal to plot the same information. Figure 4 contains the plot output for example 2. At each variable entry, three plots are generated. For example, figure 4(b) represents the entry of variable 3, δe . The bottom plot in figure 4(b) displays the measured C_m (+'s) and the C_m computed by the model (solid line) at this stage of the regression. Above that, is a plot of the residual time history and the top plot is the autocorrelation function of the residual sequence. It is seen in figure 4(b), that the one variable model leaves quite a bit of structure in the residual sequence. In figure 4(c), the model, residuals, and autocorrelation sequence for the model containing δe and α are plotted. The autocorrelation sequence and the residual sequence are improved dramatically over figure 4(b). By figure 4(f), the visual aid displays a good fit, and good autocorrelation for the residual sequence. Figure 4(f) corresponds to the model containing 5 variables plus a bias term. The remaining parts of figure 4 all indicate a good fit and acceptable autocorrelation function. In general the plots have several applications to the curve fitting problem. One application is through structure that is left in the residual sequence. The user can look for new candidate model variables that might remove that structure. Secondly, if the structure is too fine for the user's eye, the autocorrelation function may indicate that that structure is present. Third, of course, is simply a picture of how well the computed curve fits the measured data. This also demonstrates the noisiness of the data. For example, a large variance in the residual sequence may indicate some filtering is required on the measured data. The indication for filtering is especially strong when the model fits the overall trends in the measured data but the residual variance is still large.

CONCLUDING REMARKS

Two versions of a stepwise regression computer program which were developed for the determination of airplane model structure from flight data have been presented. The use of the program STEP with a Taylor's series expansion of the aerodynamic force and moment coefficients was demonstrated in example 1. It is recommended that this program be used in regions where the variations in angles of attack and sideslip are not large but nonlinearity or aerodynamic coupling is suspected. Secondly, an example employing program STEPSPL was given. This program uses spline basis functions for the aerodynamic force and moment coefficients. It is recommended that STEPSPL be used when maneuvers having large variations in angle of attack and/or angle of sideslip need to be analyzed. The appendices contain the program listings and output for the two examples.

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APPENDIX A

This appendix contains a listing of PROGRAM STEP.

PROGRAM STEP 74/74 OPT=1

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```
1      PROGRAM STEP(INPUT,OUTPUT,TAPE1,TAPE2,TAPE5=INPUT,TAPE6=OUTPUT)
REAL M,IY,IX,IZ,IXZ
DIMENSION RR(49,49),A(49,49),AP(49,49)
DIMENSION T(500),Y(500),YHAT(500),XNU(500)
5      DIMENSION S(25,25),B(25),V(25)
DIMENSION STDER(25),FPART(25)
DIMENSION W(50),XLAG(50)
DIMENSION IEON(3)
DIMENSION TN(25),PPLT(25),FPLT(25),TITLE(8)
COMMON/START/ X(25,500),XXSUM(25,25),XSUM(25),XBAR(25),SIGMA(25)
COMMON/ACDATA/ SAREA,BSPAN,CBAR,M,RHO,G,IX,IY,IZ,IXZ,DELET,ALPHT
1,BETT,DELAT,DELRT,QT,PT,RT
COMMON/AOP/ APR(25,525),OO(500),PPRT(25),PRSMIN
COMMON/FLAGS/ IPSKP,NPTS,IDIM,JDIM,NMAX,IMIN,ICNT(25),IORD(25)
15     *,IPPTS,LATOP,ITRIMOP,ICALL,IACELOP,IFILOP
COMMON/ORDER/ IEO,N
COMMON/ACCF/ AX(500),AY(500),AZ(500),PDOT(500),QDOT(500),RDOT(500)
1,VEL(500),P(500),Q(500),R(500)
EQUIVALENCE (A,RR)
20     NAMELIST /INPUT/ IPRESOP,TS,NEQ,IEQN,
*,NPTS,IPLOT,IFLAG,
*,SAREA,BSPAN,CBAR,
*,M,RHO,G,
*,IX,IY,IZ,IXZ,
*,DELET,ALPHT,BETT,DELAT,DELRT,QT,PT,RT,
*,FCRT,ITRIMOP,IPSKP,LATOP,IACELOP,IFILOP
25     ALPHT=BETT=DELET=DELAT=DELRT=QT=PT=RT=0.
CALL PSEUDO
2502 TOL=1.0E-08      ICALL=0
30     READ(5,INPUT)
      IF.EOF(5) 2501,2503
2503 WRITE(6,INPUT)
C
C     PRINT SUMMARY TITLES ON TAPE2
35
        WRITE(2,980)
980 FORMAT(10X,*STEPWISE REGRESSION SUMMARY*)
N=15  SLINMAX=3
40     IF(LATOP.EQ.1) N=25
      IF(LATOP.EQ.1) LINMAX=5
C
        DD 1000 L=1,NEQ
```

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```
IEQ=IEON(L) SNGO=0
ICALL=ICALL+1
CALL DATASET(TS,T,Y,X)
WRITE(2,985) IEO
985 FCPMAT(5X,*EQN # *,I2)
WRITE(2,981)
981 FORMAT(2X,*TOT #*,2X,*PARAM #*,2X,*% VAR#,5X,*PRESS#,9X,*TOT F*)
50 C
C SET UP DATA ARRAYS
C
IF(LATOP.EQ.1) GO TO 800
DO 804 I=1,NPTS
IF(IEQ-2) 801,802,803
801 X(N,I)=Y(I)=2*M*G/(RHO*SAREA*VEL(I)*VEL(I))*AX(I)
GO TO 804
802 X(N,I)=Y(I)=2*M*G/(RHO*SAREA*VEL(I)*VEL(I))*AZ(I)
GO TO 804
803 X(N,I)=Y(I)=2*IY/(RHO*SAREA*CBAR*VEL(I)*VEL(I))+(QDOT(I)
1-(IZ-IX)/IY*P(I)*R(I)-IXZ/IY*(R(I)*R(I)-P(I)*P(I)))
804 CONTINUE
GO TO 805
800 DO 806 I=1,NPTS
IF(IEQ-2) 807,806,809
807 X(N,I)=Y(I)=2*M*G/(RHO*SAREA*VEL(I)*VEL(I))*AY(I)
GO TO 806
808 X(N,I)=Y(I)=2*IX/(RHO*SAREA*BSPAN*VEL(I)*VEL(I))*(PDOT(I)-
1(IY-IZ)/IX*Q(I)*R(I)-(IXZ/IX)*(P(I)*Q(I)+RDOT(I)))
GO TO 806
809 X(N,I)=Y(I)=2*IZ/(RHO*SAREA*BSPAN*VEL(I)*VEL(I))*(RDOT(I)-
1(IX-IY)/IZ*P(I)*Q(I)-(IXZ/IZ)*(PDOT(I)-Q(I)*R(I)))
806 CONTINUE
805 CONTINUE
75 IANOVA=0 SNM1=N-1 SN2M1=2*N-1 SIPASS=0
N2=N2M1*N2M1 SMAXLAG=NPTS/10
LINCNT=0 SLM1=NM1
F1=F2=FCRT
IF(IFLAG .EQ. 1) LINOP=1
DO 206 I=1,MAXLAG
206 XLAG(I)=I-1
DO 51 I=1,2401
51 A(I)=0.
DO 52 I=1,NM1
```

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```
85      52 A(I,I+N)=1.  
      DO 53 I=1,NM1  
 53 A(I+N,I)=-1.  
      DO 50 I=1,N  
 XBAR(I)=XSUM(I)=ICNT(I)=0.  
 90      50 XXSUM(II,I)=0.  
      DO 100 II=1,N  
      DO 100 I=1,N  
      DO 100 J=1,NPTS  
 95      100 XXSUM(I,II)=XXSUM(I,II)+X(I,J)*X(II,J)  
      DO 101 II=1,N  
      DO 101 J=1,NPTS  
 101     XSUM(II)=XSUM(II)+X(II,J)  
      DO 201 I=1,N  
 100     DC 200 J=1,NPTS  
 200     XEAR(I)=XPAP(I)+X(I,J)  
 201     XBAR(I)=XBAP(I)/NPTS  
      DO 202 I=1,N  
      DO 202 J=1,N  
 105     S(I,J)=XXSUM(I,J)-XSUM(I)*XSUM(J)/NPTS  
 202     CONTINUE  
      DO 203 I=1,N  
 203     SIGMA(I)=SQRT(S(I,I))  
      DO 204 I=1,NM1  
 110     IP1=I+1  
      DO 204 J=IP1,N  
 RR(I,J)=S(I,J)/(SIGMA(I)*SIGMA(J))  
 204     RR(J,I)=RR(I,J)  
      DO 205 I=1,N  
 115     205 RR(I,I)=1.  
      DO 210 I=1,N  
 SIGMA(I)=SIGMA(I)/SORT(FLOAT(NPTS))  
 210     CONTINUE  
 PHI=NPTS-1  
      DO 301 I=1,NM1  
 120     301 B(I)=0.  
 SY=SIGMA(N)*SORT(RR(N,N)/PHI)  
 C      REDEFINE XXSUM,X WITH REDUCED # OF DATA PTS FOR USE BY PRESS  
 125     C      IF(IPRESOP.EQ.0) GO TO 450
```

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IF(IPSKP .GT. 0) CALL PSET
IF(IPSKP .EQ. 0) IPPTS=NPTS

130 C START LARGE LOOP
C VMAX CALCULATED

450 I=1 \$IPASS=IPASS+1
320 IF(A(I,I).GT.TOL) 250,300

250 IF(ICNT(I).EQ.1) GO TO 300
V(I)=A(I,N)*A(N,I)/A(I,I)
IF(V(I).GT.VMAX) 260,300

260 VMAX=V(I) \$NMAX=I
300 IF(LINOP.EQ.1) LM1=LINMAX

140 140 I=I+1
GO TO 320

330 CONTINUE
I=NMAX

145 * CALCULATE F
IF(VMAX.LT.TOL) 2000,443

2000 IF(LINOP.EQ.0) 1999,2111
443 F=PHI*VMAX/(A(N,N)-VMAX)

IF(F.GT.0.) GO TO 444
A(N,N)=VMAX SF=-F \$NGD=1 SPRINT 998

444 PRINT 950,F,I
IF(F.GT.F1.OR.LINOP.EQ.1) 400,1999

400 IF(IPRESOP.EQ.0) GO TO 403

155 C CALC PRESS
C

CALL PRESS

403 CONTINUE

* UPDATE THE A MATRIX
ICNT(I)=1 SPHI=PHI-1

DO 401 II=1,N2M1

DO 401 JJ=1,N2M1

IF(II.NE.I) GO TO 402

AP(II,JJ)=A(II,JJ)/A(II,II)

GO TO 401

402 AP(II,JJ)=A(II,JJ)-A(II,I)*A(I,JJ)/A(I,I)

401 CONTINUE

DO 411 I2=1,N2M1

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210	439 IV-IV+ICNT(II)	
	DO 439 II-1,N	
	IV-C	
	432 IANDVA=0	
	CALL UPDATE	
205	C	
	UPDATE A MATRIX (-APR) USED IN PRESS CALC'S	
	IF(IFPESOP.EQ.0) GO TO 432	
	431 CONTINUE	
200	GO TO 430	
	TANVVA=1	
	* NEW ANNUA SUMMARY	
	429 CONTINUE	
195	DO 426 J2=1,N2M1	
	DO 426 J2=1,N2M1	
	428 CONTINUE	
	427 AP(III,JJ)=A(III,JJ)-A(III,N+IMIN)*A(IMIN,JJ)/A(N+IMIN,N+IMIN)	
	GO TO 428	
190	AP(III,NN+IMIN) GO TO 427	
	IF(III,NN+IMIN) GO TO 427	
	DO 428 JJ=1,N2M1	
	421 IMIN=II SINCT(II)=0 SPINT 933,II	
185	420 IF(FPART(II).LT.F2.AND.LINOP.EQ.0) 421,429	
	IF(ICNT(II).EQ.1) 420,429	
	DO 429 II=1,NM1	
	* ELIMINATE VARIABLES WITH FCFZ	
	418 IF(FIANOVA.EQ.1) GO TO 431	
180	419 CCHT,INNE	
	410 FPART(II)=PHI*A(III,N)*(A(N,N)+A(II+N,II+N))	
	IF(ICNT(II).EQ.1) 410,419	
	DO 419 II=1,NM1	
	IF(NG0.EQ.1) GO TO 431	
175	IF(TPASS.EQ.1) GO TO 431	
	430 PRINT 951,(ICNT(II),II=1,NM1)	
170	* PARTIAL F TESTS	
	411 A(I2,J2)=AP(I2,J2)	
	DO 411 J2=1,N2M1	

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SSDR=1.-A(N,N) SXMSDR=SSDR/IV
SSREG=A(N,N) SXMSSREG=SSREG/PHI

215

PVAP=100*SSDR
PPINT 954,PVAR
SDRES=SQRT(A(N,N)*S(N,N)/PHI)
PPINT 955,SDRES
FTOT=XMSDR/XMSSREG
PRINT 957,FTOT

957 FCPMAT(1X,*TOTAL F VALUE IS*,E12.5)

220

C
C PPINT SUMMARY ON TAPE2
C

WPITE(2,982) IV,NMAX,PVAR,PPRT(NMAX),FTOT

982 FORMAT(1X,15,2X,I5,3X,F6.2,3X,E12.5,3X,E12.5)

225

TN(IV)=FLOAT(IV)
PPLT(IV)=PPRT(NMAX)

FPLT(IV)=FTOT

DO 449 II=1,NM1

IF(ICNT(II).NE.1) GO TO 448

230

B(II)=A(II,N)*SORT(S(N,N)/S(II,II))
STDER(II)=SDRES*SQRT(A(II,II)/S(II,II))

GO TO 449

448 B(II)=0. \$STDERR(II)=0.

449 CONTINUE

235

SUM=0.

DO 451 II=1,NM1

451 SUM=SUM+B(II)*XBAR(II)

B(N)=XBAR(N)-SUM

PRINT958

240

PPINT 956,(B(II),II=1,N)

PRINT 956,(STDERR(II),II=1,NM1)

DO 460 II=1,NPTS

YHAT(II)=B(N)

DO 461 JJ=1,NM1

461 YHAT(II)=YHAT(II)+B(JJ)*X(JJ,II)

460 YNU(II)=Y(II)-YHAT(II)

IF(IPLOT .EQ. 0) GO TO 470

CALL AUTO(XNU,MAXLAG,NPTS,W,XXSUM(N,N),IV+1,YHAT,Y)

CALL INFOPLT(0,NPTS,T,1,Y,1,0.,0.,0.,0.,1.,4,4HTIME,6,

250

16HY,YHAT,22,5.,3.5.,.75,.75)

CALL INFOPLT(9,NPTS,T,1,YHAT,1,0.,0.,0.,0.,1.,4,4HTIME,6,

16HY,YHAT,0,5.,3.5.,.75,.75)

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```
CALL INFOPLT(9,NPTS,T,1,XNU,1,0.,0.,0.,0.,0.,4,4HTIME,6,  
16HY-YHAT,22,5.,3.5,0.0,4.75)  
CALL INFOPLT(1,MAXLAG,XLAG,1,W,1,0.,0.,0.,0.,0.,0.,3,  
13HLAG,6,6HAUTO C,22,5.,3.5,0.0,4.75)  
470 CONTINUE  
IF(NGO.EQ.1) GO TO 1000  
GO TO 2112  
260 2111 LINOP=0 $LINCNT=LINMAX SLM1=N-1  
GO TO 450  
2112 LINCNT=LINCNT+1  
IF(LINCNT.GE.LINMAX) LINOP=0  
LM1=N-1  
GO TO 450  
950 FORMAT(1X,///,10X,*MAXIMUM F VALUE IS *,E10.3,* FOR VARIABLE *,I3)  
951 FORMAT(1X,*VARIABLES IN REGRESSION*,24I4)  
952 FORMAT(1X,*PARTIAL F VALUE FOR VARIABLE *,I3,* IS *,E10.3)  
953 FORMAT(1X,*VARIABLE *,I3,* ELIMINATED*)  
954 FORMAT(1X,*PERCENT VARIATION EXPLAINED IS *,F6.2)  
955 FORMAT(1X,*STD. DEVIATION OF RESIDUALS IS *,E10.3)  
958 FORMAT(1X,*NEW PARAMETER ESTIMATES AND STD. DEV. ARE*)  
956 FORMAT(1X,15E9.3,/,1X,10E9.3)  
998 FORMAT(1X,*NEGATIVE F VALUE CALCULATED*)  
270 1999 CONTINUE  
IF(IPRESNP.EQ.C) GO TO 1000  
CALL PLOT2(TN,PPLT,FPLT,IV,24HTOTAL NO. PARAM IN MODEL,24,  
* 5HPRESS,5,4HFTOT,4)  
1000 CONTINUE  
ENDFILE 2  
REWIND 2  
WRITE(6,3000)  
3000 FORMAT(1H1,2X,* *)  
DO 1500 I=1,100  
READ(2,2001) TITLE  
IF(EOF(2)) 2500,1200  
1200 CONTINUE  
WRITE(6,2001) TITLE  
1500 CONTINUE  
2001 FCPPMAT(8A10)  
2500 CONTINUE  
GO TO 2502  
2501 CALL CALPLT(0.,0.,999)  
STOP
```

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END

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```

1 SUBROUTINE DATASET(TS,T,Y,X)
2   REAL M,IY,IX,IZ,IXZ
3   DIMENSION T(500),Y(500),X(25,500)
4   DIMENSION BETA(500),ALPH(500)
5   DIMENSION DELA(500),DELR(500),DELE(500)
6   DIMENSION NAMES(50),IUNITS(50),HDR(8),DATA(50)
7   DIMENSION PDD(500),ODD(500),RDD(500),PTEM(500),QTEM(500),RTEM(500)
8   1,WRK1(500),WRK2(500),WRK3(500),WRK4(500),WRK5(500),WRK6(500)
9   COMMON/ACDATA/ S,B,C,M,RHO,G,IX,IY,IZ,IXZ,DELET,ALPHT
10  1,PETT,DELAT,DELRT,QT,PT,RT
11  COMMON/FLAGS/ IPSKP,NPTS,JDIM,NMAX,IMIN,ICNT(25),IORD(25)
12  *           ,IPPTS,LATOP,ITRIMDP,ICALL,IACELOP,IFILOP
13  COMMON/DRDEP/ IEQ,N
14  COMMON/ACCEL/ AX(500),AY(500),AZ(500),PDOT(500),QDOT(500),RDOT(500)
15  1),VEL(500),P(500),Q(500),R(500)

C
C
C

20  IF(ICALL.GT.1) GO TO 46
21  J2=NPTS/2
22  JPTS=2*J2
23  IF( (NPTS-JPTS) .EQ. 0) NPTS=JPTS-1
24  JDIM=NPTS+N
25  IDIM=N
26  REWIND 1
27  ID=1
28  NCH=20
29  *      READ(1) ID,NCH,(NAMES(I),I=1,NCH),(IUNITS(I),I=1,NCH),HDR
30  *      IF(EOF(1)) 9994,502
31  502 READ(1) (DATA(J),J=1,NCH)
32  IF(EOF(1)) 9996,8001
33  8001 IF((TS).GT.DATA(1)) 502,600
34  600 CONTINUE
35  IF(ITRIMCP.EQ.1) GO TO 602
36  BETT=DATA(3) $DELAT=DATA(13) $DELRT=DATA(15) $DELET=DATA(14)
37  ALPHT=DATA(19)
38  602 PRINT 1980,ALPHT,BETT,DELAT,DELET,DELRT
39  1980 FCRMAT(1X,///,10X,*TRIM VALUES*/,15X,
40  **ALPHT      BETT      AILT      DELET      DELRT*/
41  *10X,5E12.5)
42  DD 15 I=1,NPTS
43  READ (1) (DATA(J),J=1,NCH)

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```
IF(EOF(1)) 9996,601
601 CONTINUE
45   T(I)= DATA(1)-TS
      VEL(I)= DATA(2)
      BETA(I)= DATA(18)-BETT
      ALPH(I)= DATA(19)-ALPHT
      P(I)= DATA(5)
      Q(I)= DATA(6)
      R(I)= DATA(7)
      AX(I)=DATA(10)
      AY(I)= DATA(11)
      AZ(I)= DATA(12)
      DELA(I)= DATA(13)-DELAT
      DELR(I)= DATA(15)-DELRT
      DELE(I)=DATA(14)-DELET
      PCNT(I)=DATA(16)  SQDOT(I)=DATA(20)  SRDOT(I)=DATA(17)
15   CONTINUE
60   IF(IACELOP.EQ.0) GO TO 46
      CALL SECDER(3,3,T,P,PDD,PTEM,NPTS,P0,P3,.5,.5,WRK1,WRK2,WRK3,
1WRK4,WPK5,WRK6)
      CALL SECDER(3,3,T,Q,QDD,QTEM,NPTS,P0,P3,.5,.5,WRK1,WRK2,WRK3,
1WRK4,WPK5,WRK6)
65   CALL SECDEP(3,3,T,R,RDD,RTEM,NPTS,P0,P3,.5,.5,WRK1,WRK2,WRK3,
1WRK4,WPK5,WRK6)
      DO 45 I=1,NPTS
      PDOT(I)=DERSP(T(I),T,P,NPTS,PDD,PTEM)
      QDOT(I)=DERSP(T(I),T,Q,NPTS,QDD,QTEM)
      RDOT(I)=DEPSP(T(I),T,R,NPTS,RDD,RTEM)
70   45 CONTINUE
      46 CONTINUE
      IF(IFILOP.EQ.0) GO TO 47
      CALL FIL(T,AY,NPTS)
75   47 CONTINUE
C
      IF(LATOP.NE.1) GO TO 803
      DO 800 I=1,NPTS
      X(1,I)=BETA(I)
      X(2,I)=P(I)*B/(2.*VEL(I))
      X(3,I)=R(I)*B/(2.*VEL(I))
      X(4,I)=DELA(I)
      X(5,I)=DELR(I)
      X(6,I)=ALPH(I)*X(1,I)
800
```

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```
85      X(7,I)=ALPH(I)*X(2,I)
         X(8,I)=X(3,I)*ALPH(I)
         X(9,I)=DELA(I)*ALPH(I)
         X(10,I)=CELR(I)*ALPH(I)
         X(11,I)=ALPH(I)*ALPH(I)*X(1,I)
         X(12,I)=ALPH(I)*ALPH(I)*X(2,I)
         X(13,I)=ALPH(I)*ALPH(I)*X(3,I)
         X(14,I)=ALPH(I)*ALPH(I)*X(4,I)
         X(15,I)=ALPH(I)*ALPH(I)*X(5,I)
         X(16,I)=X(1,I)*X(1,I)
         X(17,I)=X(1,I)*X(16,I)
         X(18,I)=X(1,I)*X(17,I)
         X(19,I)=X(1,I)*X(18,I)
         X(20,I)=X(1,I)*X(11,I)
         X(21,I)=ALPH(I)*X(16,I)
         X(22,I)=ALPH(I)
         X(23,I)=ALPH(I)*ALPH(I)
         X(24,I)=ALPH(I)*X(23,I)
3      800 CONTINUE
         GO TO 804
105     803 CONTINUE
         DO 801 I=1,NPTS
         X(1,I)=ALPH(I)
         X(2,I)=C/(2*VFL(I))*O(I)
         X(3,I)=DELE(I)
         X(4,I)=X(1,I)*X(1,I)
         X(5,I)=X(1,I)*X(2,I)
         X(6,I)=X(1,I)*X(3,I)
         X(7,I)=X(4,I)*X(2,I)
         X(8,I)=X(4,I)*X(3,I)
         X(9,I)=X(4,I)*X(1,I)
         X(10,I)=X(9,I)*X(1,I)
         X(11,I)=X(10,I)*X(1,I)
         X(12,I)=X(11,I)*X(1,I)
         X(13,I)=X(12,I)*X(1,I)
         120     801 X(14,I)=X(13,I)*X(1,I)
         804 CCNTINUE
         PRINT 964, ID, IEQ, NPTS
         IF(ICALL.GT.1) GO TO 999
         IF(LATOP.EQ.0) GO TO 50
         PPINT 968
         968 FORMAT(1X,7X,*TIME*,11X,*V*,12X,*BETA*,11X,*P*,14X,*R*,11X,
```

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```
1*DELA*,11X,*DELR*)  
964 FORMAT(1H1,3X,*RUN*,I5,5X,*EQUATION *,I2,5X,*NPTS*,I5,///)  
      PRINT 962,(T(I),VEL(I),BETA(I),P(I),R(I),DELA(I),DELR(I),I=1,NPTS)  
130    962 FORMAT(7(2X,E12.4))  
      CALL INFOPLT(1,NPTS,T,1,DELA,1,0.,0.,0.,0.,0.,1,1HT,  
14,4HDELA,22,7.,5.,.75,.75)  
      CALL INFOPLT(1,NPTS,T,1,DELR,1,0.,0.,0.,0.,0.,1,1HT,  
14,4HDELR,22,7.,5.,.75,.75)  
135    GO TO 999  
50    CONTINUE  
      PRINT 998  
998    FORMAT(1X,7X,*TIME*,11X,*V*,11X,*ALPHA*,11X,*Q*,14X,*DELE*)  
      PRINT 997,(T(I),VEL(I),ALPH(I),Q(I),DELE(I),I=1,NPTS)  
140    997 FORMAT(5(2X,E12.4))  
      CALL INFOPLT(1,NPTS,T,1,DELE,1,0.,0.,0.,0.,0.,1,1HT,  
14,4HDELE,22,7.,5.,.75,.75)  
      GO TO 999  
32    9998 PRINT 9999  
145    9999 FORMAT(1X,*EOF ON DUMMY READ*)  
      GO TO 999  
9996 PRINT 9997,J,I  
9997 FORMAT(1X,*EOF ON DATA READ*,5X,*INDEX J,I= *,2I10)  
      GO TO 999  
150    9994 PRINT 9995  
9995 FORMAT(1X,*EOF ON HDR READ*)  
999    CONTINUE  
      RETURN  
      END
```

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SUBROUTINE AUTO(X,MAXLAG,N,W,YSQ,IQ,YHAT,Y)
DIMENSION X(1),A(1),YHAT(1),Y(1)
MLAGM=MAXLAG-1 SXM=FLDAT(N)
YSUM=0. SXSUM=0. YSUM=YSUM+P=PL=0.
DO 7 I=1,N
YSUM=YSUM+YHAT(I)
7 XSUM=XSUM+X(I)
YBAR=YSUM/N
YHABR=YHSUM/N
XMEAN=XSUM/N
DO 8 I=1,N
8 X(I)=X(I)-YMEAN
DO 12 I=1,N
12 XSUM=XSUM+X(I)*X(I)
YHATSD=YSD-XXSUM
PRINT 900,XMEAN,XXSUM
900 FORMAT(1X,*RESIDUAL MEAN IS*,E12.5,/1X,*SIGMA SD OF RESIDUAL IS *
1, E12.5)
NMK=N-K
SUM=C. SUM=0.
DO 2 K=1,MAXLAG
2 NMK=1-NMK
DO 3 I=1,N
3 SUM=SUM+X(I)*X(I+K)
DO 4 K=1,(N-K)*SUM
4 NMK=1-NMK
DO 5 I=1,N
5 NMK=1-NMK
DO 6 I=1,N
6 NMK=1-NMK
W=WC/N
3 W=WC+X(I)*X(I)
DO 9 I=1,MAXLAG
9 W=MAXLAG+2-I-W(MAXLAG+I-1)
DO 10 I=1,N
10 X(I)=X(I)+WMAXAN
DO 11 I=1,M
11 W(I)=W(I)/M
RETURN
END

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FUNCTION DERSP

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```
1      FUNCTION DERSP(XX,X,Y,N,P,H)
C      FUNCTION DERSP
C
C      DERSP IS USED TO OBTAIN THE FIRST DERIVATIVE OF SPLINE
C      CURVE FITTED DATA
C
C      USAGE -
C      X = DERSP(XX,X,Y,N,P,H)
C      NOTE - IF XX LESS THAN X(1) THEN DERSP = DX(1)/DY
C              IF XX GREATER THAN X(N), THEN DERSP = DX(N)/DY
C
C      WHERE -
C      XX    INDEPENDENT VARIABLE FOR WHICH INTERPOLATED SLOPE
C      IS DESIRED
C      X     N-DIMENSIONED VECTOR OF INDEPENDENT POINTS
C      Y     N-DIMENSIONED VECTOR OF DEPENDENT POINTS
C      N     NUMBER OF DATA POINTS
C      P     N-DIMENSIONED VECTOR FROM UPDATE
C      H     (N-1)-DIMENSIONED VECTOR FROM UPDATE
C
C      SUBROUTINES CALLED -
C      NONE
C
C      DIMENSION X(1),Y(1),P(1),H(1)
C      XP=XX
C      IF(XX.LT.X(1)) GO TO 1
C      K=N-1
C      DO 2 I=1,K
C      IF(XX.LT.X(I+1)) GO TO 3
C
C      2 CONTINUE
C      I=K
C      XP=X(N)
C      GO TO 3
C
C      1 XP=X(1)
C      I=1
C      3 F1=(X(I+1)-XP)**2
C      F2=(XP-X(I))**2
C      F3=H(I)/3.
C      DERSP=((F3-F1/H(I))*P(I) + (F2/H(I)-F3)*P(I+1))/2.+ (Y(I+1)-Y(I))/
C      1   H(I)
C      RETURN
C      END
```

DSCF 230
DSCF 10
DSCF 20
DSCF 30
DSCF 40
DSCF 50
DSCF 60
DSCF 70
DSCF 80
DSCF 90
DSCF 100
DSCF 110
DSCF 120
DSCF 130
DSCF 140
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DSCF 400
DSCF 410
DSCF 420

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1      SUBROUTINE SECDER(L1,L2,X,Y,P,H,N,PO,P3,XK1,XK2,A,B,C,D,GAMMA,
1      BETA)
C      SUBROUTINE SECDER
5      C      SECDER IS USED WITH FUNCTION SPLINE TO PERFORM A SPLINE
C      INTERPOLATION. IT IS USED TO GENERATE P AND H.
C      C      USAGE -
C      CALL SECDER(L1,L2,X,Y,P,H,N,PO,P3,XK1,XK2,A,B,C,D,GAMMA,BETA)
10     C      WHERE -
C      L1,L2 DETERMINE THE END CONDITIONS AT X(1) AND X(N) TO BE
C      USED. (SEE BELOW)
C      X      N-DIMENSIONED VECTOR OF INDEPENDENT POINTS
C      Y      N-DIMENSIONED VECTOR OF DEPENDENT POINTS
C      P      N-DIMENSIONED VECTOR TO BE RETURNED
C      H      (N-1)-DIMENSIONED VECTOR TO BE RETURNED
C      N      NUMBER OF DATA POINTS
C      C      SECOND DERIVATIVES ARE GIVEN AT THE END POINTS
20      C      XK1 NOT USED
C      XK2 NOT USED
C      IF L1=1 THEN
C      PO   SECOND DERIVATIVE AT X(1),Y(1)
C      IF L2=1 THEN
C      P3   SECOND DERIVATIVE AT X(N),Y(N)
25      C      FIRST DERIVATIVES ARE GIVEN AT THE END POINT
C      XK1 NOT USED
C      XK2 NOT USED
C      IF L1=2 THEN
C      PO   FIRST DERIVATIVE AT X(1),Y(1)
C      IF L2=2 THEN
C      P3   FIRST DERIVATIVE AT X(N),Y(N)
C      NO INFORMATION ABOUT THE CURVE IS KNOWN
C      PO NOT USED
C      P3 NOT USED
30      C      IF L1=3 THEN
C      XK1 P'''(3,0) = XK1*P'''(3,1), XK1 GREATER THAN 0
C      IF L2=3 THEN
C      XK2 P'''(3,N) = XK2*P'''(3,N-1), XK2 GREATER THAN 0
35      C      A      N-DIMENSIONED WORK VECTOR
C      B      N-DIMENSIONED WORK VECTOR
C      C      N-DIMENSIONED WORK VECTOR
40      C

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C      D      N-DIMENSIONED WORK VECTOR          UPD  410
C      BETA   N-DIMENSIONED WORK VECTOR          UPD  420
45     C      GAMMA   N-DIMENSIONED WORK VECTOR    UPD  430
C      SUBROUTINES CALL -                      UPD  440
C      NONE                                UPD  450
C      UPD  460
C      UPD  470
50     DIMENSION X(N),Y(N),A(N),B(N),C(N),D(N),GAMMA(N),BETA(N),H(N),P(N)
K=N-1
DO 1 J=1,K
1 H(J)=X(J+1)-X(J)
DO 2 J=2,K
2 A(J) = H(J-1)/H(J)
      B(J) = 2.*(H(J)+H(J-1))/H(J)
      C(J) = 1.
      D(J) = 6./H(J)*((Y(J+1)-Y(J))/H(J)-(Y(J)-Y(J-1))/H(J-1))
      IF(L1.E0.2) GO TO 20
      IF(L1.E0.3) GO TO 10
      60     B(1)=1.
      C(1)=0.
      D(1)=P0
      GO TO 30
      65     20 B(1)=1.
      C(1)=-XK1
      D(1)=0.
      GO TO 30
      70     20 B(1)=H(1)/3.
      C(1)=H(1)/6.
      D(1)=(Y(2)-Y(1))/H(1)-P0
      30 IF(L2.E0.2) GO TO 21
      IF(L2.E0.3) GOTO 11
      A(N)=0.
      B(N)=1.
      D(N)=P3
      GO TO 40
      75     11 A(N)=-XK2
      B(N)=1.
      D(N)=0.
      GO TO 40
      80     21 A(N)=H(K)/6.
      B(N)=H(K)/3.
      D(N)=P3-(Y(N)-Y(K))/H(K)

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0 BETTA(1)=B(1)
1 GAMMA(1)=D(1)/BETTA(1)
2 DO 6 J=2,N
3   BETTA(J)=B(J)-A(J)*C(J-1)/BETTA(J-1)
4   GAMMA(J)=B(J)-A(J)*C(J-1)/BETTA(J-1)
5   P(N) = GAMMA(N)
6   GAMMA(J)=C(J)*GAMMA(J-1)+B(J)*GAMMA(J-1)/BETTA(J)
7   P(M)=GAMMA(M)-C(M)*P(M+1)/BETTA(M)
8   M=N-1
9   UPD 910
10  UPD 920
11  UPD 930
12  UPD 940
13  UPD 950
14  RETURN
15 END

```

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SUBROUTINE SECDEF 74/74 DFT=1 82/10/25. OT-4.1.22 PAGE 3

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SUBROUTINE FIL

74/74 OPT-1

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```
1 SUBROUTINE FIL(T,P,NPTS)
2 DIMENSION PF(500),H(500),P(500),T(500)
3 PI=3.14159 SFC=2.5 SFT=2.51 SWC=2*PI*FC SWT=2*PI*FT
4 NMID=NPTS/2 SDT=.05
5 W2=(WT-WC)*(WT-WC)
6 DO 3 I=1,NMID
7 K=I
8 3 H(I)=PI/(2*K*DT)*(SIN(WT*K*DT)+SIN(WC*K*DT))/(PI*PI-W2*K*DT
9 1*K*DT)
10 HO=FC+FT
11 NPMI=NPTS-1
12 HNORM=HO
13 DO 1 I=1,NMID
14 1 HNORM=HNORM+H(I)*2.
15 DO 2 I=1,NMID .
16 2 H(I)=H(I)/HNORM
17 HC=HO/HNORM
18 DO 5 I=2,NMID
19 IM1=I-1
20 PF(I)=HC*P(I)
21 DO 51 J=1,IM1
22 PF(I)=PF(I)+H(J)*(P(I+J)+P(I-J))
23 DO 52 J=1,NMID
24 52 PF(I)=PF(I)+2*H(J)*P(I+J)
25 5 CONTINUE
26 NP2=NMID+2
27 DO 4 I=NP2,NPMI
28 NPMI=NPTS-I
29 PF(I)=HO*P(I)
30 DO 41 J=1,NPMI
31 PF(I)=PF(I)+H(J)*(P(I-J)+P(I+J))
32 NPMIP1=NPMI+1
33 DO 42 J=NPMIP1,NMID
34 PF(I)=PF(I)+2*H(J)*P(I-J)
35 4 CONTINUE
36 PF(1)=HO*P(1) SPF(NPTS)=HO*P(NPTS) SPF(NMID+1)=HO*P(NMID+1)
37 DO 10 J=1,NMID
38 PF(1)=PF(1)+2*H(J)*P(1+J)
39 PF(NMID+1)=PF(NMID+1)+H(J)*(P(NMID+1+J)+P(NMID+1-J))
40 10 PF(NPTS)=PF(NPTS)+2*H(J)*P(NPTS-J)
41 DO 6 I=1,NPTS
42 6 P(I)=PF(I)
```

ORIGINAL PAGE IS
OF POOR QUALITY

END
RETURN

SUBROUTINE FIL 74/74 DPT-2
FTN 4.8+328 82/10/28. 07.41.22 PAGE 2

SUBROUTINE PLOT2

74/74 OPT=1

FTN 4.8+528

82/10/28. 07.41.22

PAGE 1

1 SUBROUTINE PLOT2(T,X,Y,N,LABT,LT,LABX,LX,LABY,LY)
DIMENSION T(1),X(1),Y(1)
N1=N+1
N2=N+2
5 CALL ASCALE(T,4.,N,1,10.)
CALL ASCALE(X,2.,N,1,10.)
CALL ASCALE(Y,2.,N,1,10.)
CALL CALPLT(1.,1.,-3)
CALL AXES(0.,0.,0.,4.,T(N1),T(N2),1.,5.,LABT,.15,LT,2)
CALL CALPLT(0.,1.,-3)
CALL AXES(0.,0.,90.,2.,Y(N1),Y(N2),1.,5.,LABY,.15,LY,2)
CALL LINPLT(T,X,N,1,0,0,1)
CALL CALPLT(0.,2.5,-3)
CALL AXES(0.,0.,90.,2.,Y(N1),Y(N2),1.,5.,LABY,.15,LY,2)
CALL LINPLT(T,Y,N,1,0,0,1)
CALL NFRAME
RETURN
END

04

```

297 VMAX=A(T) $MAX=I
298 I=(V(1)*OUT*VMAX) 280,300
299 V(I)=V(I+1)+A(N,I)/A(I,I)
300 Z=0 DO (I,J)=50,100 60,10,300
301 DO (I,J)=50,100 250,500
302 DO I=1 NMAX=0 EPASS=IPASS+1
303 C
304 STMT L498E L498P
305 MAXWAVELEN
306 SY=SYNTHEN*SQRT(P(R,N)/P(I))
307 R(T)=0
308 DO 309 T=1,PI/2
309 PI=NP-1
310 CONTINUE
311 S16MA(T)=S16MA(I)/SQRT(FELAT(NPTS))
312 DO 313 I=1,100
313 R(I)=0.5C2
314 NFT=I 492 0
315 R(I)=R(I)*4.44*(I-1)
316 R(I)=S(I,J)/(S16MA(I)*S16MA(J))
317 NFT=I=IPIN
318 T+PI
319 DO 320 T=1,PI/2
320 S16SA(T)=S16SA(I)
321 NFT=I 492 0
322 DO 323 T=1,PI/2
323 S16SA(T)=S16SA(I)
324 S16SA(T)=S16SA(I)
325 NFT=I 492 0
326 DO 327 T=1,PI/2
327 S16SA(T)=S16SA(I)
328 NFT=I=IPIN
329 T+PI
330 DO 331 T=1,PI/2
331 S16SA(T)=S16SA(I)
332 NFT=I 492 0
333 DO 334 T=1,PI/2
334 S16SA(T)=S16SA(I)
335 NFT=I 492 0
336 DO 337 T=1,PI/2
337 S16SA(T)=S16SA(I)
338 NFT=I 492 0
339 DO 340 T=1,PI/2
340 S16SA(T)=S16SA(I)
341 NFT=I 492 0
342 DO 343 T=1,PI/2
343 S16SA(T)=S16SA(I)
344 NFT=I 492 0
345 DO 346 T=1,PI/2
346 S16SA(T)=S16SA(I)
347 NFT=I 492 0
348 DO 349 T=1,PI/2
349 S16SA(T)=S16SA(I)
350 NFT=I 492 0
351 DO 352 T=1,PI/2
352 S16SA(T)=S16SA(I)
353 NFT=I 492 0
354 DO 355 T=1,PI/2
355 S16SA(T)=S16SA(I)
356 NFT=I 492 0
357 DO 358 T=1,PI/2
358 S16SA(T)=S16SA(I)
359 NFT=I 492 0
360 DO 361 T=1,PI/2
361 S16SA(T)=S16SA(I)
362 NFT=I 492 0
363 DO 364 T=1,PI/2
364 S16SA(T)=S16SA(I)
365 NFT=I 492 0
366 DO 367 T=1,PI/2
367 S16SA(T)=S16SA(I)
368 NFT=I 492 0
369 DO 370 T=1,PI/2
370 S16SA(T)=S16SA(I)
371 NFT=I 492 0
372 DO 373 T=1,PI/2
373 S16SA(T)=S16SA(I)
374 NFT=I 492 0
375 DO 376 T=1,PI/2
376 S16SA(T)=S16SA(I)
377 NFT=I 492 0
378 DO 379 T=1,PI/2
379 S16SA(T)=S16SA(I)
380 NFT=I 492 0
381 DO 382 T=1,PI/2
382 S16SA(T)=S16SA(I)
383 NFT=I 492 0
384 DO 385 T=1,PI/2
385 S16SA(T)=S16SA(I)
386 NFT=I 492 0
387 DO 388 T=1,PI/2
388 S16SA(T)=S16SA(I)
389 NFT=I 492 0
390 DO 391 T=1,PI/2
391 S16SA(T)=S16SA(I)
392 NFT=I 492 0
393 DO 394 T=1,PI/2
394 S16SA(T)=S16SA(I)
395 NFT=I 492 0
396 DO 397 T=1,PI/2
397 S16SA(T)=S16SA(I)
398 NFT=I 492 0
399 DO 400 T=1,PI/2
400 S16SA(T)=S16SA(I)
401 NFT=I 492 0
402 DO 403 T=1,PI/2
403 S16SA(T)=S16SA(I)
404 NFT=I 492 0
405 DO 406 T=1,PI/2
406 S16SA(T)=S16SA(I)
407 NFT=I 492 0
408 DO 409 T=1,PI/2
409 S16SA(T)=S16SA(I)
410 NFT=I 492 0
411 DO 412 T=1,PI/2
412 S16SA(T)=S16SA(I)
413 NFT=I 492 0
414 DO 415 T=1,PI/2
415 S16SA(T)=S16SA(I)
416 NFT=I 492 0
417 DO 418 T=1,PI/2
418 S16SA(T)=S16SA(I)
419 NFT=I 492 0
420 DO 421 T=1,PI/2
421 S16SA(T)=S16SA(I)
422 NFT=I 492 0
423 DO 424 T=1,PI/2
424 S16SA(T)=S16SA(I)
425 NFT=I 492 0
426 DO 427 T=1,PI/2
427 S16SA(T)=S16SA(I)
428 NFT=I 492 0
429 DO 430 T=1,PI/2
430 S16SA(T)=S16SA(I)
431 NFT=I 492 0
432 DO 433 T=1,PI/2
433 S16SA(T)=S16SA(I)
434 NFT=I 492 0
435 DO 436 T=1,PI/2
436 S16SA(T)=S16SA(I)
437 NFT=I 492 0
438 DO 439 T=1,PI/2
439 S16SA(T)=S16SA(I)
440 NFT=I 492 0
441 DO 442 T=1,PI/2
442 S16SA(T)=S16SA(I)
443 NFT=I 492 0
444 DO 445 T=1,PI/2
445 S16SA(T)=S16SA(I)
446 NFT=I 492 0
447 DO 448 T=1,PI/2
448 S16SA(T)=S16SA(I)
449 NFT=I 492 0
450 DO 451 T=1,PI/2
451 S16SA(T)=S16SA(I)
452 NFT=I 492 0
453 DO 454 T=1,PI/2
454 S16SA(T)=S16SA(I)
455 NFT=I 492 0
456 DO 457 T=1,PI/2
457 S16SA(T)=S16SA(I)
458 NFT=I 492 0
459 DO 460 T=1,PI/2
460 S16SA(T)=S16SA(I)
461 NFT=I 492 0
462 DO 463 T=1,PI/2
463 S16SA(T)=S16SA(I)
464 NFT=I 492 0
465 DO 466 T=1,PI/2
466 S16SA(T)=S16SA(I)
467 NFT=I 492 0
468 DO 469 T=1,PI/2
469 S16SA(T)=S16SA(I)
470 NFT=I 492 0
471 DO 472 T=1,PI/2
472 S16SA(T)=S16SA(I)
473 NFT=I 492 0
474 DO 475 T=1,PI/2
475 S16SA(T)=S16SA(I)
476 NFT=I 492 0
477 DO 478 T=1,PI/2
478 S16SA(T)=S16SA(I)
479 NFT=I 492 0
480 DO 481 T=1,PI/2
481 S16SA(T)=S16SA(I)
482 NFT=I 492 0
483 DO 484 T=1,PI/2
484 S16SA(T)=S16SA(I)
485 NFT=I 492 0
486 DO 487 T=1,PI/2
487 S16SA(T)=S16SA(I)
488 NFT=I 492 0
489 DO 490 T=1,PI/2
490 S16SA(T)=S16SA(I)
491 NFT=I 492 0
492 DO 493 T=1,PI/2
493 S16SA(T)=S16SA(I)
494 NFT=I 492 0
495 DO 496 T=1,PI/2
496 S16SA(T)=S16SA(I)
497 NFT=I 492 0
498 DO 499 T=1,PI/2
499 S16SA(T)=S16SA(I)
500 NFT=I 492 0
501 DO 502 T=1,PI/2
502 S16SA(T)=S16SA(I)
503 NFT=I 492 0
504 DO 505 T=1,PI/2
505 S16SA(T)=S16SA(I)
506 NFT=I 492 0
507 DO 508 T=1,PI/2
508 S16SA(T)=S16SA(I)
509 NFT=I 492 0
510 DO 511 T=1,PI/2
511 S16SA(T)=S16SA(I)
512 NFT=I 492 0
513 DO 514 T=1,PI/2
514 S16SA(T)=S16SA(I)
515 NFT=I 492 0
516 DO 517 T=1,PI/2
517 S16SA(T)=S16SA(I)
518 NFT=I 492 0
519 DO 520 T=1,PI/2
520 S16SA(T)=S16SA(I)
521 NFT=I 492 0
522 DO 523 T=1,PI/2
523 S16SA(T)=S16SA(I)
524 NFT=I 492 0
525 DO 526 T=1,PI/2
526 S16SA(T)=S16SA(I)
527 NFT=I 492 0
528 DO 529 T=1,PI/2
529 S16SA(T)=S16SA(I)
530 NFT=I 492 0
531 DO 532 T=1,PI/2
532 S16SA(T)=S16SA(I)
533 NFT=I 492 0
534 DO 535 T=1,PI/2
535 S16SA(T)=S16SA(I)
536 NFT=I 492 0
537 DO 538 T=1,PI/2
538 S16SA(T)=S16SA(I)
539 NFT=I 492 0
540 DO 541 T=1,PI/2
541 S16SA(T)=S16SA(I)
542 NFT=I 492 0
543 DO 544 T=1,PI/2
544 S16SA(T)=S16SA(I)
545 NFT=I 492 0
546 DO 547 T=1,PI/2
547 S16SA(T)=S16SA(I)
548 NFT=I 492 0
549 DO 550 T=1,PI/2
550 S16SA(T)=S16SA(I)
551 NFT=I 492 0
552 DO 553 T=1,PI/2
553 S16SA(T)=S16SA(I)
554 NFT=I 492 0
555 DO 556 T=1,PI/2
556 S16SA(T)=S16SA(I)
557 NFT=I 492 0
558 DO 559 T=1,PI/2
559 S16SA(T)=S16SA(I)
560 NFT=I 492 0
561 DO 562 T=1,PI/2
562 S16SA(T)=S16SA(I)
563 NFT=I 492 0
564 DO 565 T=1,PI/2
565 S16SA(T)=S16SA(I)
566 NFT=I 492 0
567 DO 568 T=1,PI/2
568 S16SA(T)=S16SA(I)
569 NFT=I 492 0
570 DO 571 T=1,PI/2
571 S16SA(T)=S16SA(I)
572 NFT=I 492 0
573 DO 574 T=1,PI/2
574 S16SA(T)=S16SA(I)
575 NFT=I 492 0
576 DO 577 T=1,PI/2
577 S16SA(T)=S16SA(I)
578 NFT=I 492 0
579 DO 580 T=1,PI/2
580 S16SA(T)=S16SA(I)
581 NFT=I 492 0
582 DO 583 T=1,PI/2
583 S16SA(T)=S16SA(I)
584 NFT=I 492 0
585 DO 586 T=1,PI/2
586 S16SA(T)=S16SA(I)
587 NFT=I 492 0
588 DO 589 T=1,PI/2
589 S16SA(T)=S16SA(I)
590 NFT=I 492 0
591 DO 592 T=1,PI/2
592 S16SA(T)=S16SA(I)
593 NFT=I 492 0
594 DO 595 T=1,PI/2
595 S16SA(T)=S16SA(I)
596 NFT=I 492 0
597 DO 598 T=1,PI/2
598 S16SA(T)=S16SA(I)
599 NFT=I 492 0
600 DO 601 T=1,PI/2
601 S16SA(T)=S16SA(I)
602 NFT=I 492 0
603 DO 604 T=1,PI/2
604 S16SA(T)=S16SA(I)
605 NFT=I 492 0
606 DO 607 T=1,PI/2
607 S16SA(T)=S16SA(I)
608 NFT=I 492 0
609 DO 610 T=1,PI/2
610 S16SA(T)=S16SA(I)
611 NFT=I 492 0
612 DO 613 T=1,PI/2
613 S16SA(T)=S16SA(I)
614 NFT=I 492 0
615 DO 616 T=1,PI/2
616 S16SA(T)=S16SA(I)
617 NFT=I 492 0
618 DO 619 T=1,PI/2
619 S16SA(T)=S16SA(I)
620 NFT=I 492 0
621 DO 622 T=1,PI/2
622 S16SA(T)=S16SA(I)
623 NFT=I 492 0
624 DO 625 T=1,PI/2
625 S16SA(T)=S16SA(I)
626 NFT=I 492 0
627 DO 628 T=1,PI/2
628 S16SA(T)=S16SA(I)
629 NFT=I 492 0
630 DO 631 T=1,PI/2
631 S16SA(T)=S16SA(I)
632 NFT=I 492 0
633 DO 634 T=1,PI/2
634 S16SA(T)=S16SA(I)
635 NFT=I 492 0
636 DO 637 T=1,PI/2
637 S16SA(T)=S16SA(I)
638 NFT=I 492 0
639 DO 640 T=1,PI/2
640 S16SA(T)=S16SA(I)
641 NFT=I 492 0
642 DO 643 T=1,PI/2
643 S16SA(T)=S16SA(I)
644 NFT=I 492 0
645 DO 646 T=1,PI/2
646 S16SA(T)=S16SA(I)
647 NFT=I 492 0
648 DO 649 T=1,PI/2
649 S16SA(T)=S16SA(I)
650 NFT=I 492 0
651 DO 652 T=1,PI/2
652 S16SA(T)=S16SA(I)
653 NFT=I 492 0
654 DO 655 T=1,PI/2
655 S16SA(T)=S16SA(I)
656 NFT=I 492 0
657 DO 658 T=1,PI/2
658 S16SA(T)=S16SA(I)
659 NFT=I 492 0
660 DO 661 T=1,PI/2
661 S16SA(T)=S16SA(I)
662 NFT=I 492 0
663 DO 664 T=1,PI/2
664 S16SA(T)=S16SA(I)
665 NFT=I 492 0
666 DO 667 T=1,PI/2
667 S16SA(T)=S16SA(I)
668 NFT=I 492 0
669 DO 670 T=1,PI/2
670 S16SA(T)=S16SA(I)
671 NFT=I 492 0
672 DO 673 T=1,PI/2
673 S16SA(T)=S16SA(I)
674 NFT=I 492 0
675 DO 676 T=1,PI/2
676 S16SA(T)=S16SA(I)
677 NFT=I 492 0
678 DO 679 T=1,PI/2
679 S16SA(T)=S16SA(I)
680 NFT=I 492 0
681 DO 682 T=1,PI/2
682 S16SA(T)=S16SA(I)
683 NFT=I 492 0
684 DO 685 T=1,PI/2
685 S16SA(T)=S16SA(I)
686 NFT=I 492 0
687 DO 688 T=1,PI/2
688 S16SA(T)=S16SA(I)
689 NFT=I 492 0
690 DO 691 T=1,PI/2
691 S16SA(T)=S16SA(I)
692 NFT=I 492 0
693 DO 694 T=1,PI/2
694 S16SA(T)=S16SA(I)
695 NFT=I 492 0
696 DO 697 T=1,PI/2
697 S16SA(T)=S16SA(I)
698 NFT=I 492 0
699 DO 700 T=1,PI/2
700 S16SA(T)=S16SA(I)
701 NFT=I 492 0
702 DO 703 T=1,PI/2
703 S16SA(T)=S16SA(I)
704 NFT=I 492 0
705 DO 706 T=1,PI/2
706 S16SA(T)=S16SA(I)
707 NFT=I 492 0
708 DO 709 T=1,PI/2
709 S16SA(T)=S16SA(I)
710 NFT=I 492 0
711 DO 712 T=1,PI/2
712 S16SA(T)=S16SA(I)
713 NFT=I 492 0
714 DO 715 T=1,PI/2
715 S16SA(T)=S16SA(I)
716 NFT=I 492 0
717 DO 718 T=1,PI/2
718 S16SA(T)=S16SA(I)
719 NFT=I 492 0
720 DO 721 T=1,PI/2
721 S16SA(T)=S16SA(I)
722 NFT=I 492 0
723 DO 724 T=1,PI/2
724 S16SA(T)=S16SA(I)
725 NFT=I 492 0
726 DO 727 T=1,PI/2
727 S16SA(T)=S16SA(I)
728 NFT=I 492 0
729 DO 730 T=1,PI/2
730 S16SA(T)=S16SA(I)
731 NFT=I 492 0
732 DO 733 T=1,PI/2
733 S16SA(T)=S16SA(I)
734 NFT=I 492 0
735 DO 736 T=1,PI/2
736 S16SA(T)=S16SA(I)
737 NFT=I 492 0
738 DO 739 T=1,PI/2
739 S16SA(T)=S16SA(I)
740 NFT=I 492 0
741 DO 742 T=1,PI/2
742 S16SA(T)=S16SA(I)
743 NFT=I 492 0
744 DO 745 T=1,PI/2
745 S16SA(T)=S16SA(I)
746 NFT=I 492 0
747 DO 748 T=1,PI/2
748 S16SA(T)=S16SA(I)
749 NFT=I 492 0
750 DO 751 T=1,PI/2
751 S16SA(T)=S16SA(I)
752 NFT=I 492 0
753 DO 754 T=1,PI/2
754 S16SA(T)=S16SA(I)
755 NFT=I 492 0
756 DO 757 T=1,PI/2
757 S16SA(T)=S16SA(I)
758 NFT=I 492 0
759 DO 760 T=1,PI/2
760 S16SA(T)=S16SA(I)
761 NFT=I 492 0
762 DO 763 T=1,PI/2
763 S16SA(T)=S16SA(I)
764 NFT=I 492 0
765 DO 766 T=1,PI/2
766 S16SA(T)=S16SA(I)
767 NFT=I 492 0
768 DO 769 T=1,PI/2
769 S16SA(T)=S16SA(I)
770 NFT=I 492 0
771 DO 772 T=1,PI/2
772 S16SA(T)=S16SA(I)
773 NFT=I 492 0
774 DO 775 T=1,PI/2
775 S16SA(T)=S16SA(I)
776 NFT=I 492 0
777 DO 778 T=1,PI/2
778 S16SA(T)=S16SA(I)
779 NFT=I 492 0
780 DO 781 T=1,PI/2
781 S16SA(T)=S16SA(I)
782 NFT=I 492 0
783 DO 784 T=1,PI/2
784 S16SA(T)=S16SA(I)
785 NFT=I 492 0
786 DO 787 T=1,PI/2
787 S16SA(T)=S16SA(I)
788 NFT=I 492 0
789 DO 790 T=1,PI/2
790 S16SA(T)=S16SA(I)
791 NFT=I 492 0
792 DO 793 T=1,PI/2
793 S16SA(T)=S16SA(I)
794 NFT=I 492 0
795 DO 796 T=1,PI/2
796 S16SA(T)=S16SA(I)
797 NFT=I 492 0
798 DO 799 T=1,PI/2
799 S16SA(T)=S16SA(I)
800 NFT=I 492 0
801 DO 802 T=1,PI/2
802 S16SA(T)=S16SA(I)
803 NFT=I 492 0
804 DO 805 T=1,PI/2
805 S16SA(T)=S16SA(I)
806 NFT=I 492 0
807 DO 808 T=1,PI/2
808 S16SA(T)=S16SA(I)
809 NFT=I 492 0
810 DO 811 T=1,PI/2
811 S16SA(T)=S16SA(I)
812 NFT=I 492 0
813 DO 814 T=1,PI/2
814 S16SA(T)=S16SA(I)
815 NFT=I 492 0
816 DO 817 T=1,PI/2
817 S16SA(T)=S16SA(I)
818 NFT=I 492 0
819 DO 820 T=1,PI/2
820 S16SA(T)=S16SA(I)
821 NFT=I 492 0
822 DO 823 T=1,PI/2
823 S16SA(T)=S16SA(I)
824 NFT=I 492 0
825 DO 826 T=1,PI/2
826 S16SA(T)=S16SA(I)
827 NFT=I 492 0
828 DO 829 T=1,PI/2
829 S16SA(T)=S16SA(I)
830 NFT=I 492 0
831 DO 832 T=1,PI/2
832 S16SA(T)=S16SA(I)
833 NFT=I 492 0
834 DO 835 T=1,PI/2
835 S16SA(T)=S16SA(I)
836 NFT=I 492 0
837 DO 838 T=1,PI/2
838 S16SA(T)=S16SA(I)
839 NFT=I 492 0
840 DO 841 T=1,PI/2
841 S16SA(T)=S16SA(I)
842 NFT=I 492 0
843 DO 844 T=1,PI/2
844 S16SA(T)=S16SA(I)
845 NFT=I 492 0
846 DO 847 T=1,PI/2
847 S16SA(T)=S16SA(I)
848 NFT=I 492 0
849 DO 850 T=1,PI/2
850 S16SA(T)=S16SA(I)
851 NFT=I 492 0
852 DO 853 T=1,PI/2
853 S16SA(T)=S16SA(I)
854 NFT=I 492 0
855 DO 856 T=1,PI/2
856 S16SA(T)=S16SA(I)
857 NFT=I 492 0
858 DO 859 T=1,PI/2
859 S16SA(T)=S16SA(I)
860 NFT=I 492 0
861 DO 862 T=1,PI/2
862 S16SA(T)=S16SA(I)
863 NFT=I 492 0
864 DO 865 T=1,PI/2
865 S16SA(T)=S16SA(I)
866 NFT=I 492 0
867 DO 868 T=1,PI/2
868 S16SA(T)=S16SA(I)
869 NFT=I 492 0
870 DO 871 T=1,PI/2
871 S16SA(T)=S16SA(I)
872 NFT=I 492 0
873 DO 874 T=1,PI/2
874 S16SA(T)=S16SA(I)
875 NFT=I 492 0
876 DO 877 T=1,PI/2
877 S16SA(T)=S16SA(I)
878 NFT=I 492 0
879 DO 880 T=1,PI/2
880 S16SA(T)=S16SA(I)
881 NFT=I 492 0
882 DO 883 T=1,PI/2
883 S16SA(T)=S16SA(I)
884 NFT=I 492 0
885 DO 886 T=1,PI/2
886 S16SA(T)=S16SA(I)
887 NFT=I 492 0
888 DO 889 T=1,PI/2
889 S16SA(T)=S16SA(I)
890 NFT=I 492 0
891 DO 892 T=1,PI/2
892 S16SA(T)=S16SA(I)
893 NFT=I 492 0
894 DO 895 T=1,PI/2
895 S16SA(T)=S16SA(I)
896 NFT=I 492 0
897 DO 898 T=1,PI/2
898 S16SA(T)=S16SA(I)
899 NFT=I 492 0
900 DO 901 T=1,PI/2
901 S16SA(T)=S16SA(I)
902 NFT=I 492 0
903 DO 904 T=1,PI/2
904 S16SA(T)=S16SA(I)
905 NFT=I 492 0
906 DO 907 T=1,PI/2
907 S16SA(T)=S16SA(I)
908 NFT=I 492 0
909 DO 910 T=1,PI/2
910 S16SA(T)=S16SA(I)
911 NFT=I 492 0
912 DO 913 T=1,PI/2
913 S16SA(T)=S16SA(I)
914 NFT=I 492 0
915 DO 916 T=1,PI/2
916 S16SA(T)=S16SA(I)
917 NFT=I 492 0
918 DO 919 T=1,PI/2
919 S16SA(T)=S16SA(I)
920 NFT=I 492 0
921 DO 922 T=1,PI/2
922 S16SA(T)=S16SA(I)
923 NFT=I 492 0
924 DO 925 T=1,PI/2
925 S16SA(T)=S16SA(I)
926 NFT=I 492 0
927 DO 928 T=1,PI/2
928 S16SA(T)=S16SA(I)
929 NFT=I 492 0
930 DO 931 T=1,PI/2
931 S16SA(T)=S16SA(I)
932 NFT=I 492 0
933 DO 934 T=1,PI/2
934 S16SA(T)=S16SA(I)
935 NFT=I 492 0
936 DO 937 T=1,PI/2
937 S16SA(T)=S16SA(I)
938 NFT=I 492 0
939 DO 940 T=1,PI/2
940 S16SA(T)=S16SA(I)
941 NFT=I 492 0
942 DO 943 T=1,PI/2
943 S16SA(T)=S16SA(I)
944 NFT=I 492 0
945 DO 946 T=1,PI/2
946 S16SA(T)=S16SA(I)
947 NFT=I 492 0
948 DO 949 T=1,PI/2
949 S16SA(T)=S16SA(I)
950 NFT=I 492 0
951 DO 952 T=1,PI/2
952 S16SA(T)=S16SA(I)
953 NFT=I 492 0
954 DO 955 T=1,PI/2
955 S16SA(T)=S16SA(I)
956 NFT=I 492 0
957 DO 958 T=1,PI/2
958 S16SA(T)=S16SA(I)
959 NFT=I 492 0
960 DO 961 T=1,PI/2
961 S16SA(T)=S16SA(I)
962 NFT=I 492 0
963 DO 964 T=1,PI/2
964 S16SA(T)=S16SA(I)
965 NFT=I 492 0
966 DO 967 T=1,PI/2
967 S16SA(T)=S16SA(I)
968 NFT=I 492 0
969 DO 970 T=1,PI/2
970 S16SA(T)=S16SA(I)
971 NFT=I 492 0
972 DO 973 T=1,PI/2
973 S16SA(T)=S16SA(I)
974 NFT=I 492 0
975 DO 976 T=1,PI/2
976 S16SA(T)=S16SA(I)
977 NFT=I 492 0
978 DO 979 T=1,PI/2
979 S16SA(T)=S16SA(I)
980 NFT=I 492 0
981 DO 982 T=1,PI/2
982 S16SA(T)=S16SA(I)
983 NFT=I 492 0
984 DO 985 T=1,PI/2
985 S16SA(T)=S16SA(I)
986 NFT=I 492 0
987 DO 988 T=1,PI/2
988 S16SA(T)=S16SA(I)
989 NFT=I 492 0
990 DO 991 T=1,PI/2
991 S16SA(T)=S16SA(I)
992 NFT=I 492 0
993 DO 994 T=1,PI/2
994 S16SA(T)=S16SA(I)
995 NFT=I 492 0
996 DO 997 T=1,PI/2
997 S16SA(T)=S16SA(I)
998 NFT=I 492 0
999 DO 999 T=1,PI/2
999 S16SA(T)=S16SA(I)
1000 NFT=I 492 0

```

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RE36274 ST.PSP1 73774 CPT=1 47/09/02, 13:03:28 PAGE 2

CALL PATASIT(TS,T,Y,X)

SI T UP DATA MISCAT5

IF(LA10P,0,0) 30 TO 00

01 804 1#LNPTS

1#(111,-1) 801,802,803

00 10 04

1-P(I)*K(I)*(J-L-X)/L-Y-(K(I)*K(I)-P(I)*P(I)*L(I)*(Q(I))

03 00 600 1#NPTS

00 10 00

824 COUNTING

00 10 06

2*(Y-I)/X*(Q(I)-(XZ/IY)*(P(I))+(Q(I)+P(I))

03 00 COUNTING

00 10 00

1-(X-IY)/IZ+P(I)*Q(I)-(IXZ/IY)*(P(I))-(Q(I)*P(I))

00 10 06

EL=FE=FCFT

00 200 1#MAXLEN

25 XLM3(1)=I-1

00 34 I=L,N

03 A(I+N,I)=I-1

00 53 T=L,N

2 A(I,I+N,I)=I-1

00 92 I=L,N

1 A(I)=I-1

00 34 I=L,N

XDMR(I)=A50UW(I)*LCNT(I)

00 53 I=L,N

03 A(I+N,I)=I-1

00 53 T=L,N

2 A(I,I+N,I)=I-1

00 92 I=L,N

1 A(I)=I-1

69

72

70

69

69

69

69

49

For $\lambda_{\text{min}}(L) = 1 - \sqrt{2}/2$, we have $L^{\dagger} L \geq 1/2$ and $L^{\dagger} L \in \mathbb{R}$.

F 114 4.84027

2025 RELEASE UNDER E.O. 14176

ESTATE PLANNING

```

1      PRINT(UNIT=1,INPUT,OUTPUT,TAPE1,TAPES=1,END,TAPE6=OUTPUT)
2      EQUAL=1,Y1,X9242,IX4
3      DIMS=1,IR(74,74),A(74,74),AP(72,72)
4      DIMS=1,IT(400),Y(400),YIAT(400),XNUT(400)
5      DIMS=1,IR(540,400),A(540,400),AP(400,400)
6      DIMS=1,IR(40),IPLAT(40)
7      DIMS=1,W(3),XLAB(3)
8      DIMS=1,ON(3),KNT(23)
9      CMMMD/START/X(40,400),XXSUM(40,40),XSUM(4,1),XBAR(40),SIGMA(40)
10     CMMMD/CREATE/SAREA,ISPAH,CBAK,MNUD,G,1X9242,1Z,2XZ,DELT,ALPHT
11     L,LT,D,LAT,DELT,QT,PT,RT
12     CMMMD/LAGS/NPTS,IAT(40),LATIP,ITRIMOP,ICALL,IACELIP,IFLOP
13     CMMMD/END,P/I,Q,N
14     CMMMD/ACCL/AX(400),AY(400),AZ(400),PRUT(400),QUT(400),POUT(400)
15     VELL(400),P(400),Q(400),R(400)
16     CMMMD/KNT/XNLT(23)
17     EQUIVALENCE(A,FF)
18     NAMELIST//INPUT/ TS,N_Q,I_ION,
19     *          NPTS,IPLT,IFLAG,
20     *          SAREA,ISPAH,CBAK,
21     *          MNUD,G,
22     *          1X9242,1Z,1XZ,
23     *          DELT,ALPHT,B_LTT,D_LAT,D_LFT,QT,PT,RT,
24     *          FC,T,ITP1MUPSLATIP,IACELIP,IFLOP
25     ALPHT=0 TT=1-LLET=LLET-DELT-QI=PT=FT=0.
26     CALL PSUBU
27     TFL=1,DL=2,d      B1CALL=v
28     OF=49 11=1,23
29     XNUT(1)=.0M7265+(11-1)*.017423
30     RTAB(1,INPUT)
31     IF(I:OF(5))=2501,2503
32     2503 W=ITL(5,INPUT)
33     OF=30 I=1,23
34     KNT(1)=1+X(XNUT(1)*57.3)
35     PRINT(959,(1,I=1,17),(KNT(1),I=1,17))
36     N=40  DL=4,MAX=3
37     IF(LATIP,EQ,0) D=25
38     IF(LATOP,NE,0) D=25
39     IF(LATOP,NE,0) LINMAX=5
40
41     1000 L=1,NE0
42     1001 L=ON(L)      BNGU=
43     ICALL=ICALL+1

```

APPENDIX 5

This appendix contains the listing for PROGRAM STEPSPL (as used in example 2).

A2VIPJP. 82/10/28.NASA/LRC CY175-R NOS 1.4 (R23) NOS 1.4 531 R CPFS

R2142 B

09
07.41.20.STEPJ,T3000.
07.41.20.BATTERSON
07.41.20.USER,043450N.
07.41.21.CHARGE,101218,LRC.
07.41.21.GET,STEP1.
07.41.22.FTN(I=STEP1,R=0,A,PL=15000)
07.41.32. 13.535 CP SECONDS COMPILATION TIME
07.41.32.GET,DUM.
07.41.33.GET,BINVDP.
07.41.34.SKIPR,BINVDP,7,,B.
07.41.34.COPYRR,BINVDP,TAPE1,1.
07.41.34. COPY COMPLETE.
07.41.34.REWIND,TAPE1.
07.41.34.ATTACH,FTNMLIB/UN=LIBRARY.
07.41.34.ATTACH,AKCLIB/UN=LIBRARY.
07.41.35.ATTACH,LPCGOSF/UN=LIBRARY.
07.41.35.GET,ISSILIB/UN=474750C.
07.41.36.LDSET(LIB=FTNMLIB/AKCLIB/LRCGOSF/ISSILIB,PRESETA=NGINF,MAP=SBEX)
07.41.36.LGO,DUM.
07.41.42. STOP
07.41.42. 251100 MAXIMUM EXECUTION FL.
07.41.42. 8.700 CP SECONDS EXECUTION TIME.
07.41.42.PLOT.VARIAN(FRAMCNT=30,EDIT(1,30))
07.41.44.V001
07.41.53. 10 FRAMES / 2.31 METEPS GENERATED.
07.41.53.PICTURE IMAGE FILE WILL BE SAVED ON DISK
07.41.56. ***** PLOT OUTPUT COMPLETED *****
07.41.56.PLOT.VARIAN(FRAMCNT=30,EDIT(31,60))
07.41.58.VC02
07.42.04. NO PLOTTING ATTEMPTED
07.42.05.PLOT.VARIAN(FRAMCNT=30,EDIT(61,90))
07.42.07.V002
07.42.13. NO PLOTTING ATTEMPTED
07.42.13.PLOT.VARIAN(FRAMCNT=30,EDIT(91,120))
07.42.15.V002
07.42.21. NO PLOTTING ATTEMPTED
07.42.22.PLOT.VARIAN(FRAMCNT=30,EDIT(121,150))
07.42.24.V002
07.42.30. NO PLOTTING ATTEMPTED
07.42.30.EXIT.
07.42.30.UEAD, 0.002KUNS.
07.42.30.UEPF, 1.426KUNS.
07.42.30.UEMS, 21.462KUNS.
07.42.30. 175 CPU SEC = UECP/5.0.
07.42.30.UECP, 43.379SECS.
07.42.30.AESR, 192.282INTS.
07.42.30.APPROXIMATE JOB EXECUTION COST = \$ 3

APPENDIX 4

This appendix contains a sample procedure file (JCL deck) for running example 1 at the Langley Research Center computer complex.

STEPWISE REGRESSION SUMMARY

TOT #	PARAM #	% VAR	PRESS	TOT F
1	1	95.43	-R	.85710E+03
2	3	100.00	-R	.59773E+10

TOT #	PARAM #	% VAR	PRESS	TOT F
1	2	58.76	-R	.58427E+02
2	3	72.64	-R	.53111E+02
3	1	100.00	-R	.28453E+11

TOT #	PARAM #	% VAR	PRESS	TOT F
1	2	80.54	-R	.16970E+03
2	3	97.22	-R	.69937E+03
3	1	99.94	-R	.20966E+05
4	7	99.97	-R	.27162E+05

PERCENT VARIATION EXPLAINED IS 99.94
STD. DEVIATION OF RESIDUALS IS .148E-02
TOTAL F VALUE IS .20666E+05
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
-.105E+01 .153E+02-.996E+000. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. -.731E-01
.236E-01 .866E-01 .784E-020. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS -.52800E-14
SIGMA SQ OF RESIDUAL IS .85285E-04

57 MAXIMUM F VALUE IS .305E+02 FOR VARIABLE 7
VARIABLES IN REGRESSION 1 1 1 0 0 0 1 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .296E+04
PARTIAL F VALUE FOR VARIABLE 2 IS .553E+04
PARTIAL F VALUE FOR VARIABLE 3 IS .203E+05
PARTIAL F VALUE FOR VARIABLE 7 IS .297E+02
VARIABLES IN REGRESSION 1 1 1 0 0 0 1 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .296E+04
PARTIAL F VALUE FOR VARIABLE 2 IS .553E+04
PARTIAL F VALUE FOR VARIABLE 3 IS .203E+05
PARTIAL F VALUE FOR VARIABLE 7 IS .297E+02
PERCENT VARIATION EXPLAINED IS 99.97
STD. DEVIATION OF RESIDUALS IS .112E-02
TOTAL F VALUE IS .27162E+05
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
-.107E+01 .143E+02-.991E+000. 0. 0. .327E+030. 0. 0. 0. 0. 0. 0. 0. 0. -.717E-01
.179E-01 .657E-01 .595E-020. 0. 0. .203E+020. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS -.55085E-14
SIGMA SQ OF RESIDUAL IS .47891E-04

MAXIMUM F VALUE IS .424E+01 FOR VARIABLE 14

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RUN 1 EQUATION 3 NPTS 43

MAXIMUM F VALUE IS .174E+03 FOR VARIABLE 2
VARIABLES IN REGRESSION 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0
PERCENT VARIATION EXPLAINED IS 80.54
STD. DEVIATION OF RESIDUALS IS .255E-01
TOTAL F VALUE IS .16970E+03
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
C. .195E+020. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. -828E-01
0. .149E+010. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS -.48282E-14
SIGMA SQ OF RESIDUAL IS .26634E-01

MAXIMUM F VALUE IS .246E+03 FOR VARIABLE 3
VARIABLES IN REGRESSION 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 2 IS .686E+03
PARTIAL F VALUE FOR VARIABLE 3 IS .240E+03
VARIABLES IN REGRESSION 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 2 IS .686E+03
PARTIAL F VALUE FOR VARIABLE 3 IS .240E+03
PERCENT VARIATION EXPLAINED IS 97.22
STD. DEVIATION OF RESIDUALS IS .976E-02
TOTAL F VALUE IS .69957E+03
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
0. .160E+C2-.858E+CCC. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. -118E+00
C. .571E+00 .517E-C10. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS -.73430E-14
SIGMA SQ OF RESIDUAL IS .38071E-02

MAXIMUM F VALUE IS .175E+04 FOR VARIABLE 1
VARIABLES IN REGRESSION 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .170E+04
PARTIAL F VALUE FOR VARIABLE 2 IS .260E+05
PARTIAL F VALUE FOR VARIABLE 3 IS .121E+05
VARIABLES IN REGRESSION 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .170E+04
PARTIAL F VALUE FOR VARIABLE 2 IS .260E+05
PARTIAL F VALUE FOR VARIABLE 3 IS .121E+05

RUN 1 EQUATION 2 NPTS 43

MAXIMUM F VALUE IS .599E+02 FOR VARIABLE 2
VARIABLES IN REGRESSION 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0
PERCENT VARIATION EXPLAINED IS 58.76
STD. DEVIATION OF RESIDUALS IS .334E-01
TOTAL F VALUE IS .58427E+02
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
0. -150E+020. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. -131E+01
0. 196E+010. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS -.79977E-13
SIGMA SQ OF RESIDUAL IS .45829E-01

MAXIMUM F VALUE IS .208E+02 FOR VARIABLE 3
VARIABLES IN REGRESSION 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 2 IS .105E+03
PARTIAL F VALUE FOR VARIABLE 3 IS .203E+02
VARIABLES IN REGRESSION 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 2 IS .105E+03
PARTIAL F VALUE FOR VARIABLE 3 IS .203E+02
PERCENT VARIATION EXPLAINED IS 72.64
STD. DEVIATION OF RESIDUALS IS .276E-01
TOTAL F VALUE IS .53111E+02
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
0. -178E+02 -705E+000. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. -134E+01
0. 161E+01 .146E+000. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS -.85596E-13
SIGMA SQ OF RESIDUAL IS .30403E-01

MAXIMUM F VALUE IS .239E+11 FOR VARIABLE 1
VARIABLES IN REGRESSION 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .234E+11
PARTIAL F VALUE FOR VARIABLE 2 IS .749E+11
PARTIAL F VALUE FOR VARIABLE 3 IS .249E+11
VARIABLES IN REGRESSION 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .234E+11
PARTIAL F VALUE FOR VARIABLE 2 IS .749E+11
PARTIAL F VALUE FOR VARIABLE 3 IS .249E+11

MAXIMUM F VALUE IS .878E+03 FOR VARIABLE 1
VARIABLES IN REGRESSION 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
PERCENT VARIATION EXPLAINED IS 95.43
STD. DEVIATION OF RESIDUALS IS .139E-02
TOTAL F VALUE IS .85710E+03
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
.651E+000. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. .229E-03

.222E-010. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
RESIDUAL MEAN IS .61450E-15
SIGMA SQ OF RESIDUAL IS .79732E-04

MAXIMUM F VALUE IS .559E+09 FOR VARIABLE 3
VARIABLES IN REGRESSION 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .118E+11
PARTIAL F VALUE FOR VARIABLE 3 IS .546E+09
VARIABLES IN REGRESSION 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PARTIAL F VALUE FOR VARIABLE 1 IS .118E+11
PARTIAL F VALUE FOR VARIABLE 3 IS .546E+09
PERCENT VARIATION EXPLAINED IS 100.00
STD. DEVIATION OF RESIDUALS IS .382E-06
TOTAL F VALUE IS .59773E+10
NEW PARAMETER ESTIMATES AND STD. DEV. ARE
.700E+000. .500E-010. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. .630E-04
.510E-050. .203E-050. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.

RESIDUAL MEAN IS .69970E-15
SIGMA SQ OF RESIDUAL IS .58433E-11

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RUN 1 EQUATION 1 NPTS 43

TIME	V	ALPHA	Q	DELE
.1900E+01	.3500E+02	.5374E-01	.2420E+00	-.1732E+00
.1950E+01	.3500E+02	.6537E-01	.2647E+00	-.1732E+00
.2900E+01	.3500E+02	.6850E-01	-.2173E+00	-.5175E-01
.2950E+01	.3500E+02	.5170E-01	-.3565E+00	-.3884E-01
.4650E+01	.3500E+02	.3553E-01	.1953E+00	-.3984E-01
.4700E+01	.3500E+02	.4322E-01	.1919E+00	-.3961E-01
.4750E+01	.3500E+02	.5047E-01	.1868E+00	-.3917E-01
.4800E+01	.3500E+02	.5722E-01	.1798E+00	-.3906E-01
.4850E+01	.2500E+02	.6341E-01	.1711E+00	-.3884E-01
.4900E+01	.3500E+02	.6897E-01	.1605E+00	-.3861E-01
.5450E+01	.3500E+02	.6481E-01	-.1021E+00	-.3614E-01
.5500E+01	.3500E+02	.5780E-01	-.1290E+00	-.3570E-01
.5550E+01	.3500E+02	.4981E-01	-.1561E+00	-.3535E-01
.5600E+01	.3500E+02	.4086E-01	-.1633E+00	-.3468E-01
.7100E+01	.3500E+02	.3530E-01	.1309E+00	-.3782E-01
.7150E+01	.3500E+02	.4007E-01	.1237E+00	-.3839E-01
.7200E+01	.3500E+02	.4435E-01	.1153E+00	-.3906E-01
.7250E+01	.3500E+02	.4810E-01	.1056E+00	-.3950E-01
.7300E+01	.3500E+02	.5127E-01	.9469E-01	-.3984E-01
.7350E+01	.3500E+02	.5384E-01	.8256E-01	-.4006E-01
.7400E+01	.3500E+02	.5577E-01	.6929E-01	-.4039E-01
.7450E+01	.3500E+02	.5702E-01	.5484E-01	-.4028E-01
.7500E+01	.3500E+02	.5757E-01	.3936E-01	-.4028E-01
.7550E+01	.3500E+02	.5739E-01	.2289E-01	-.4039E-01
.7600E+01	.3500E+02	.5646E-01	.5478E-02	-.4017E-01
.7650E+01	.3500E+02	.5476E-01	-.1275E-01	-.4006E-01
.7700E+01	.3500E+02	.5230E-01	-.3164E-01	-.4028E-01
.7750E+01	.3500E+02	.4906E-01	-.5114E-01	-.4006E-01
.7800E+01	.3500E+02	.4504E-01	-.7107E-01	-.4017E-01
.7850E+01	.3500E+02	.4026E-01	-.9135E-01	-.4006E-01
.9200E+01	.3500E+02	.3555E-01	.8793E-01	-.3434E-01
.9250E+01	.3500E+02	.3834E-01	.7742E-01	-.3445E-01
.9300E+01	.3500E+02	.4052E-01	.6554E-01	-.3334E-01
.9350E+01	.3500E+02	.4208E-01	.5247E-01	-.3300E-01
.9400E+01	.3500E+02	.4298E-01	.3833E-01	-.3289E-01
.9450E+01	.3500E+02	.4321E-01	.2328E-01	-.3322E-01
.9500E+01	.3500E+02	.4272E-01	.7163E-02	-.3243E-01
.9550E+01	.3500E+02	.4151E-01	-.9791E-02	-.3232E-01
.9600E+01	.3500E+02	.3958E-01	-.2739E-01	-.3266E-01
.9650E+01	.3500E+02	.3691E-01	-.4561E-01	-.3266E-01
.1100E+02	.3500E+02	.3640E-01	.5560E-01	-.3547E-01
.1105E+02	.3500E+02	.3772E-01	.4323E-01	-.3513E-01
.1110E+02	.3500E+02	.3843E-01	.2984E-01	-.3411E-01

APPENDIX 3

This appendix contains the output generated by PROGRAM STEP for example 1.

RT = 0.0,
FCRT = .5E+01,
ITRIMOP = 1,
IPSKP = 10,
LATOP = 0,
IACELOP = 0,
IFILOP = 0,
SEND

50

TRIM VALUES

ALPHT	BETT	AILT	DELET	DELRT
.20950E+00 0.	0.	-	-.83180E-01	0.

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SINPUT

IPRESOP = 0,

TS = 0.0,

NEO = 3,

IEQN = 1, 2, 3,

NPTS = 43,

I PLOT = 1,

IFLAG = 1,

SAREA = .1374E+02,

BSPAN = .998E+01,

67 CBAR = .14E+01,

M = .1055E+04,

RHO = .10272E+01,

G = .981E+01,

IX = .2357E+04,

IY = .3051E+04,

IZ = .4833E+04,

IXZ = .177E+03,

DELET = -.8318E-01,

ALPHT = .2095E+00,

BETT = 0.0,

DELAT = 0.0,

DELRT = 0.0,

QT = 0.0,

PT = 0.0,

APPENDIX 2

This appendix contains the NAMELIST/INPUT/ for example 1.

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FUNCTION RANDOM 74/74 DPT-1 PAGE 1

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FUNCTION RANDOM(J)
DATA ISSEE0/32741/
ISSEE0-ISSEE0+16345
ISSEE0-ISSEE0+17777B
RANDOM=FL0AT(ISSEE0)/65536.
RETURN
END

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SUBROUTINE PSET

74/74 OPT=1

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PAGE 1

1 SUBROUTINE PSET
COMMON/FLAGS/ IPSKP,NPTS,JDIM,JDIM,NMAX,IMIN,ICNT(25),IORD(25)
*,IPPTS,ITRIMOP,ICALL
COMMON/START/ X(25,500),XXSUM(25,25),XSUM(25),XBAR(25),SIGMA(25)
COMMON /ORDER/ IEO,N
DIMENSION ITEMP(500),XTEM(500)
IRAN=0

10 C C SET INDEX FOR SELECTED DATA PTS

IPPTS=0
DO 5 J=1,NPTS,IPSKP
IPPTS=IPPTS+1
JP=J
IF(IRAN .EQ. 1) JP=RANDOM(J)*NPTS
IF(JP .EQ. 0) JP=1
ITEMP(IPPTS)=JP

15 5 CONTINUE
DO 10 I=1,N
DO 20 J=1,IPPTS
XTEM(J)=X(I,ITEMP(J))

20 20 CONTINUE
DO 30 J=1,IPPTS
X(I,J)=XTEM(J)

25 30 CONTINUE
10 CONTINUE
DO 40 K=1,625
XXSUM(K)=0.0

40 40 CONTINUE
DO 50 II=1,N
DO 50 I=1,N
DO 50 J=1,IPPTS
XXSUM(I,II)=XXSUM(I,II)+X(I,J)*X(II,J)

50 50 CONTINUE
35 C C REDEFINE JDIM FOR REDUCED # OF DATA PTS

JDIM=25+IPPTS
RETURN
END

40

SUBROUTINE REDEF 74/74 OPT=1

FTN 4.8+528

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PAGE 1

1 SUBROUTINE REDEF
COMMON/FLAGS/ IPSKP,NPTS, IDIM,JDIM,NMAX,IMIN,ICNT(25),IORD(25)
* ,IPPTS,ITRIMOP,ICALL
COMMON/START/ X(25,500),XXSUM(25,25),XSUM(25),XBAR(25),SIGMA(25)
COMMON/AQP/ A(25,525),O(500),PPRT(25),PRSHIN
COMMON /ORDER/ IEO,N
C
C INITIALIZE A,O,IORD
C
10 NPI=N+1
DO 100 I=1,N
DO 100 J=1,N
A(I,J)=XXSUM(I,J)
100 CONTINUE
15 DO 110 I=1,N
K=0
DO 110 J=NPI,JDIM
K=K+1
A(I,J)=X(I,K)
20 110 CONTINUE
DO 120 I=1,IPPTS
O(I)=0.0
120 CONTINUE
130 CONTINUE
DO 140 I=1,N
IORD(I)=I
140 CONTINUE
RETURN
END

SUBROUTINE INTRCHG 74/74 OPT=1

FTN 4.8+528

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PAGE 1

1 SUBROUTINE INTRCHG(ICHG,JCHG)
COMMON/AQP/ A(25,525),Q(500),PPRT(25),PRSMIN
COMMON/FLAGS/ IPSKP,NPTS,IDIM,JOIM,NMAX,IMIN,ICNT(25),ICRD(25)
* ,IPPTS,ITRIMOP,ICALL,IACELOP,IFILOP
5 DIMENSION AROW(525),ACOL(25),BROW(525),BCOL(25)

C C INTERCHANGE ROWS AND COLUMNS OF MATRIX A
C

10 DO 10 J=1,JOIM
AROW(J)=A(ICHG,J)
BROW(J)=A(JCHG,J)
A(ICHG,J)=BROW(J)
A(JCHG,J)=AROW(J)

15 10 CONTINUE
DO 20 I=1,IDIM
ACOL(I)=A(I,ICHG)
BCOL(I)=A(I,JCHG)
A(I,ICHG)=BCOL(I)
A(I,JCHG)=ACOL(I)

20 20 CONTINUE

C C INTERCHANGE ROWS OF ICRD
C

25 IROW=ICRD(ICHG)
JROW=ICRD(JCHG)
ICRD(JCHG)=IROW
ICRD(ICHG)=JROW
RETURN
END

SUBROUTINE UPDATE 74/74 OPT=1

FTN 4.8+528

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PAGE 2

DO 350 I=1,N
DO 350 J=NPI1,JDIM
A(I,J)=AP(I,J)
350 CONTINUE
C
C UPDATE Q
C
DO 400 I=1,IPPTS
C(I)=Q(I)+A(IDEF,N+I)*A(IDEF,N+I)
400 CONTINUE
10 CONTINUE
RETURN
END

43

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```
1      SUBROUTINE UPDATE
2      COMMON/FLAGS/ IPSKP,NPTS,IDIM,JDIM,NMAX,IMIN,ICNT(25),IORD(25)
3          ,IPPTS,ITRIMOP,ICALL,IACELOP,IFILOP
4      COMMON/AOP/ A(25,525),Q(500),PPRT(25),PRSMIN
5      COMMON /ORDER/ IEO,N
6      DIMENSION AP(25,525)
7
8      C
9      C      UPDATE A MATRIX (=AP) USED IN PRESS CALC
10
11      NM1=N-1  SNP1=N+1
12      CALL REDEF
13      KK=0
14      DO 10 II=1,NM1
15      IF(ICNT(II).EQ.0) GO TO 10
16      KK=KK+1
17      IDEF=KK
18      DO 210 LL=1,NM1
19      IF(IORD(LL).EQ.II) K=LL
20      210 CONTINUE
21      CALL INTRCHG(IDEF,K)
22      K=IDEF
23      DO 100 I=1,IDIM
24      DO 100 J=1,JDIM
25      AP(I,J)=A(I,J)
26      100 CONTINUE
27      DO 200 I=K,N
28      DO 200 J=K,JDIM
29      IF(I.EQ.K) GO TO 225
30      AP(I,J)=A(I,J)-(A(K,I)*A(K,J))/A(K,K)
31      GO TO 200
32      225 CONTINUE
33      IF(J.EQ.K) GO TO 250
34      AP(I,J)=A(I,J)/SORT(A(K,K))
35      GO TO 200
36      250 CONTINUE
37      AP(I,J)=SORT(A(K,K))
38      200 CONTINUE
39      DO 300 I=1,N
40      DO 300 J=1,N
41      A(I,J)=AP(I,J)
42      A(J,I)=A(I,J)
43      300 CONTINUE
```

SUBROUTINE PRESS

74/74 OPT=1

FTN 4.8+528

82/10/28. 07.41.22

PAGE 1

```
1 SUBROUTINE PRESS
COMMON/FLAGS/ IPSKP,NPTS,IDIM,JDIM,NMAX,IMIN,ICNT(25),IORD(25)
* ,IPPTS,ITRIMOP,ICALL,IACELOP,IFILOP
COMMON/START/ X(25,500),XXSUM(25,25),XSUM(25),XBAR(25),SIGMA(25)
COMMON/AOP/ A(25,525),O(500),PPRT(25),PRSMIN
COMMON /ORDER/ IEO,N
NM1=N-1
IDEF=0
IMIN=0
10 PRSMIN=1.E06
DO 10 I=1,NM1
IDEF=IDEF+ICNT(I)
10 CONTINUE
15 C INITIALIZE A,Q,IORD IF IDEF=0
C
C IF(IDEF .GT. 0) GO TO 130
CALL REDEF
130 CONTINUE
20 C COMPUTE PRESS (=PRSMIN) FOR VARIABLES NOT YET IN MODEL
C
DO 200 II=1,NM1
IF(ICNT(II).EQ.1) GO TO 200
DO 210 LL=1,NM1
IF(IORD(LL).EQ.II) K=LL
210 CCNTINUE
PRS=0.0
DO 250 I=1,IPPTS
PNUM=A(K,K)*A(N,I+N)-A(K,N)*A(K,N+I)
PDNM=A(K,K)*(1.-Q(I))-A(K,N+I)*A(K,N+I)
PRS=PRS+(PNUM*PNUM)/(PDNM*PDNM)
250 CONTINUE
WRITE(6,800) PRS,II
800 FORMAT(5X,*PRESS= *E12.5,5X,*FOR VARIABLE*,I5)
PPRT([I])=PRS
IF(PPSMIN .LT. PRS) GO TO 200
PRSMIN=PRS
IMIN=II
200 CONTINUE
RETURN
END
```

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277
 451 SUM=SUM*(I1*I2*I3*I4*I5*I6*I7*I8*I9*I10)
 452 I1=931 I2=174
 453 SUM=0.
 454 COUNT=0.
 455 B(I1)=25, IS1018(I1)=25.
 456 TO 449
 457 STUD(I1)=SUM*S0K1(A(I1,I1)/S(I1,I1))
 458 B(I1)=A(I1,I1)*S0T1(S(N,N)/S(I1,I1))
 459 COUNT(I1)=NC(I1) GO TO 448
 460 446 IS1018(I1)
 461 267 FORNAT(2,3)*100 E VALUE .5*E12*.5
 462 P111=957,4101
 463 F101=XMSDR/XMSRPL
 464 P101T=0.01, S0101
 465 S0101=S0K1T(A(N,N))*S(N,N)/P111
 466 P101=934,PVAR
 467 PVAPE=0.01*5.51R
 468 SSRELU=A(N,N) \$XMSRPL=S3SRPL/IV
 469 SSLE=L-.W(N,N) \$XMSDR=S3SDR/IV
 470 IV=IV+ICNT(I1)
 471 01 434 I1=154
 472 IV=0
 473 I1=I1VA=0
 474 *
 475 IF((I6)>1.0*1) A(N,N)=1.
 476 *
 477 COUNT=0.
 478 GO TO 479
 479 I1=I1VA
 480 *
 481 SUM=0.
 482 COUNT=0.
 483 A(12,12)=7.P(12,12)
 484 01 926 J2=7,924
 485 COUNT=7 I1=924
 486 COUNT=7
 487 01 11 475
 488 A(I1,I1)=A(I1,I1)/A(I1,I1)
 489 126 01 00 11181*2541
 490 T2541=0.0>2540
 491 T2541=1.25<0
 492 112541
 493 01 11 475
 494 I1=I1VA=0 I1=I1VA
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PROGRAM NAME		TYPE	7.774	DATE	REF. 4.3+552		57/05/02. 13.03.20		PAGE	5			
VARIABLES	SYN.	REPLICATION											
10062	I	INT.GER			R.FS	2*34	2*35	3*50	3*52	11*54	5*60	10*62	
					R.FS	1*55	2*71	77	2*73	2*81	3*83	3*89	
					R.FS	2*72	2*96	3*94	3*102	104	3*106	2*107	2*109
					R.FS	2*111	115	2*122	123	5*124	125	2*126	128
					R.FS	141	139	143	146	4*149	DEFINED	33	2*35
					R.FS	42	51	74	76	76	80	82	87
					R.FS	73	47	102	103	108	110	114	121
					R.FS	127	432						
54	LATELIP	INT.GER			R.FS	12	16						
10066	LANTIVA	INT.GER			R.FS	1*54	2*115	59	2*82	188			
53	LCALL	INT.GER			R.FS	12	42		DEFINED	27	46		
1	LCNT	INT.GER	ARRAY		R.FS	12	123	125	160	167	191	202	
0	LG0	INT.GER			R.FS	13	143	159					
53275	LGWM	INT.GER	ARRAY		R.FS	13	44	59	DEFINED	41			
99	LFILIP	INT.GER			R.FS	6	16	41					
10056	IFLAG	INT.GER			R.FS	12	18						
10101	II	INT.GER			R.FS	12	73						
					R.FS	15	3*37	3*42	146	4*147	3*149	155	
					R.FS	100	5*161	2*152	172	4*173	3*175	191	202
					R.FS	4*213	5*204	2*206	2*210	213	214	216	3*213
					R.FS	3*214	DEFINED	16	90	144	155	159	
					R.FS	170	201	203	213	214	215		
10114	IIIN	INT.GER			R.FS	172	4*175	DEFINED	169				
10071	IPASS	INT.GER			R.FS	121	157	DEFINED	59	121			
10055	IPLOT	INT.GER			R.FS	12	20						
10103	IP1	INT.GER			R.FS	115	DEFINED	104					
52	ITRIMIP	INT.GER			R.FS	12	18						
10115	IV	INT.GER			R.FS	121	142	DEFINED	109	191			
0	IX	REAL			R.FS	2	16	15	54	3*62	65		
11	IXZ	REAL			R.FS	2	10	16	54	62	65		
7	IY	REAL			R.FS	2	10	16	3*24	62	65		
10	IZ	REAL			R.FS	2	10	16	54	62	3*65		
10061	I	INT.GER			R.FS	2*24	167	150	3*164	DEFINED	26	166	
10112	I2	INT.GER			R.FS	2*153	2*172	DEFINED	151	177			
10102	J	INT.GER			R.FS	2*159	72	95	3*99	3*106	2*107		
					DEFIN	60	71	74	46	105			
10111	JJ	INT.GER			R.FS	2*147	3*147	2*173	3*175	2*212			
					DEFIN	145	171	217					
10113	JZ	INT.GER			R.FS	2*153	2*172	DEFINED	152	179			
53300	KNT	INT.GER	ARRAY		R.FS	6	35	35	34				
10054	L	INT.GER			R.FS	41	DEFINED	40					
51	LATELIP	INT.GER			R.FS	12	10	37	38	47			

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PROGRAM	STEPSPL	73/74	OPT=1		FTN 4.8+552		85/05/02. 13.03.28		PAGE	9
VARIABLES	SN	TYPE	RELOCATION							
10074	LINCNT	INTEGER		REFS	236	237	DEFINED	71	234	236
10063	LINMAX	INTEGER		REFS	127	234	237	DEFINED	36	38
10100	LINOP	INTEGER		REFS	127	135	140	168	DEFINED	73
				237						234
10075	LM1	INTEGER		REFS	128	DEFINED	71	127	234	238
3	M	REAL	ACDATA	REFS	2	10	18	50	52	60
10073	MAXLAG	INTEGER		REFS	74	221	229	DEFINED	70	
1	N	INTEGER	ORDER	REFS	13	50	52	54	60	62
				2*69	79	81	82	84	86	87
				93	97	98	101	105	108	110
				2*124	2*136	2*138	6*161	2*173	3*175	2*186
				2*192	2*193	4*196	3*203	2*211	213	216
				234	238	DEFINED	36	37		2*221
10054	NEQ	INTEGER		REFS	18	40				
10065	NGO	INTEGER		REFS	158	186	232	DEFINED	41	138
10107	NMAX	INTEGER		REFS	132	DEFINED	126			
10067	NM1	INTEGER		REFS	71	78	80	103	114	155
				166	201	209	214	217	DEFINED	69
0	NPTS	INTEGER	FLAGS	REFS	12	18	48	58	70	88
				94	96	99	111	113	215	221
10126	NPT2	INTEGER		REFS	223	225	227	DEFINED	222	
10072	N2	* INTEGER		DEFINED	70					
10070	N2M1	INTEGER		REFS	2*70	144	145	151	152	170
				177	178	DEFINED	69			171
14234	P	REAL	ARRAY	ACCEL	REFS	14	3*54	62	65	
5214	PDOT	REAL	ARRAY	ACCEL	REFS	14	62	65		
10104	PHI	REAL		REFS	116	136	143	161	193	196
				DEFINED	113	143				
70	20	PT	REAL	ACDATA	REFS	10	18	DEFINED	25	
10122	PVAR	REAL		REFS	195	DEFINED	194			
16040	Q	REAL	ARRAY	ACCEL	REFS	14	2*62	2*65		
7020	QDOT	REAL	ARRAY	ACCEL	REFS	14	54			
17	QT	REAL		ACDATA	REFS	10	18	DEFINED	25	
17644	R	REAL	ARRAY	ACCEL	REFS	14	3*54	62	65	
10624	RDOT	REAL	ARRAY	ACCEL	REFS	14	62	65		
4	RHO	REAL		ACDATA	REFS	10	18	50	52	54
					65					60
10127	RR	REAL	ARRAY	REFS	3	17	107	116	DEFINED	106
				109						107
21	RT	REAL		ACDATA	REFS	10	18	DEFINED	25	
47451	S	REAL	ARRAY	REFS	5	102	106	196	2*203	204
				DEFINED	99					

PROGRAM STEPSPL			73/74	OPT=1	FTN 4.8+552			85/05/02. 13.03.28			PAGE	10	
VARIABLES		SN	TYPE	RELOCATION									
O	SAREA	REAL		ACDATA		REFS	10	18	50	52	54	60	62
10123	SDRES	REAL				REFS	197	204	DEFINED	196			
111460	SIGMA	REAL	ARRAY	START		REFS	9	2*106	111	116	DEFINED	102	111
10116	SSDR	REAL				REFS	192	194	DEFINED	192			
10120	SSREG	REAL				REFS	193	DEFINED	193				
52671	STUER	REAL	ARRAY			REFS	6	214	DEFINED	204	206		
10125	SUM	REAL				REFS	210	211	DEFINED	208	210		
10105	SY	* REAL			DEFINED		116						
40431	T	REAL	ARRAY			REFS	4	43	223	225	227		
10060	TOL	REAL				REFS	122	134	DEFINED	27			
10053	TS	REAL				REFS	18	43					
52621	V	REAL	ARRAY			REFS	5	125	126	DEFINED	124		
12430	VEL	REAL	ARRAY	ACCEL		REFS	14	2*50	2*52	2*54	2*60	2*62	2*65
10106	VMAX	REAL				REFS	125	134	2*136	138	DEFINED	121	126
53011	W	REAL	ARRAY			REFS	7	221	229				
0	X	REAL	ARRAY	START		REFS	9	43	2*89	92	95	218	
111410	XBAR	REAL	ARRAY	START		DEFINED	50	52	54	60	62	65	
						REFS	9	95	96	210	211		
					DEFINED		83	95	96				
53143	XLAG	REAL	ARRAY			REFS	7	229	DEFINED	75			
10117	XMSDR	REAL				REFS	198	DEFINED	192				
10121	XMSREG	REAL				REFS	198	DEFINED	193				
0	XNOT	REAL	AKRAY	KNOT		REFS	16	34	DEFINED	29			
45645	XNU	REAL	ARRAY			REFS	4	221	227	DEFINED	219		
111340	XSUM	REAL	ARRAY	START		REFS	9	92	2*99	DEFINED	83	92	
106240	XXSUM	REAL	ARRAY	START		REFS	9	89	99	221	DEFINED	85	
42235	Y	REAL	ARRAY			REFS	4	43	219	221	223		
					DEFINED		50	52	54	60	62	65	
					REFS		4	218	219	221	225		
44041	YHAT	REAL	ARRAY			DEFINED		216	218				
					REFS								
FILE NAMES			MODE										
0	INPUT												
2054	OUTPUT	FMT											195
4130	TAPE1												197
0	TAPE5	NAME											
2054	TAPE6	NAME											

EXTERNALS	TYPL	ARGS	REFERENCES
AUTO		7	221
CALPLT		3	257
DATASET		4	43
EOF	REAL	1	31
INFOPLT		20	223 225 227 229
PSEUDO		0	26
SORT	REAL	1	LIBRARY 102 111 116 196 203 204

INLINE FUNCTIONS	TYPE	ARGS	DEF LINE	REFERENCES
FLOAT	REAL	1	INTRIN	111
IFIX	INTEGER	1	INTRIN	34

NAMELISTS	DEF LINE	REFERENCES
INPUT	18	30 32
STATEMENT LABELS		DEF LINE REFERENCES
0 30		34 33
0 49		29 28
0 50		85 82 84
0 51		77 76
0 52		79 78
0 53		81 80
0 100		89 86 87 88
0 101		90 91
0 200		95 94
0 201		96 93
0 202		100 97 98
0 203		102 101
72 0 204		107 103 105
0 205		109 108
0 206		75 74
0 210		112 110
0 250	INACTIVE	123 122
0 260	INACTIVE	126 125
6734 300		127 122 123 125
0 301		115 114
0 310	INACTIVE	129 128
6717 320		122 130
6744 330		131 128
0 400	INACTIVE	141 140
7017 401		150 144 145 148

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STATEMENT LABELS.

DEF LINE

REFERENCES

7014	402		149	146	
0	410	INACTIVE	161	160	
0	411		153	151	152
0	418	INACTIVE	164		
7070	419		163	159	160
0	420	INACTIVE	168	167	
0	421	INACTIVE	169	168	
0	426		179	177	178
7132	427		175	172	
7135	428		176	170	171 174
7157	429		180	166	167 168
7041	430		155	183	
7163	431		184	157	158 164
0	439		191	190	
6751	443		136	134	
6762	444		139	137	
7246	448		206	202	
7250	449		207	201	205
6714	450		121	235	239
0	451		210	209	
0	460		219	215	
0	461		218	217	
7342	470		231	220	
6352	800		58	47	
0	801	INACTIVE	50	49	
6325	802		52	49	
6333	803		54	49	
6347	804		56	48	51 53
73	6427	805		68	57
	6424	806		67	58 61 64
0	807	INACTIVE	60	59	
6373	808		62	59	
6410	809		65	59	
7732	950	FMT	240	139	
7741	951	FMT	241	155	
7746	952	FMT	242	162	
7755	953	FMT	243	169	
7762	954	FMT	244	195	
7770	955	FMT	245	197	
10013	956	FMT	249	213	214
7713	957	FMT	200	199	
7776	958	FMT	246	212	

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PROGRAM	STEP	SPL	73/74	OPT=1	FTN 4.8+552	35/05/02. 13.03.28	PAGE	13
STATEMENT LABELS			DEF LINE	REFERENCES				
10004	959	FMT	247	35				
10016	998	FMT	250	138				
7361	1000		252	40	232			
0	1500	INACTIVE	253					
7361	1999		251	135	140			
0	2000	INACTIVE	135	134				
10023	2001	FMT NO RFS	254					
7345	2111		234	135				
7352	2112		236	233				
0	2500	INACTIVE	255					
7364	2501		257	31				
6226	2502		27	256				
0	2503	INACTIVE	32	31				
LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES			
6233	49	I1	28 29	58	INSTACK			
6251	30	I	33 34	48	INSTACK			
6260		I	35 35	48		EXT RFS		
6276	1000	L	40 252	10668		EXT KEFS	NUT INNER	
6315	804	I	48 56	348	OPT			
6363	806	I	58 67	438	OPT			
6450	206	I	74 75	38	INSTACK			
6456	51	I	76 77	28	INSTACK			
6467	52	I	78 79	38	INSTACK			
6500	53	I	80 81	38	INSTACK			
6505	50	I	82 85	158		NOT INNER		
6515	50	II	84 85	28	INSTACK			
6523	100	II	86 89	238		NUT INNER		
6524	100	I	87 89	208		NOT INNER		
6535	100	J	68 89	38	INSTACK			
6547	101	II	90 92	148		NOT INNER		
6555	101	J	91 92	38	INSTACK			
6564	201	I	93 96	168		NOT INNER		
6572	200	J	94 95	38	INSTACK			
6603	202	I	97 100	218		NOT INNER		
6613	202	J	98 100	58	INSTACK			
6625	203	I	101 102	78		EXT KEFS		
6635	204	I	103 107	238		NOT INNER		
6650	204	J	105 107	58	INSTACK			
6664	205	I	108 109	38	INSTACK			
6671	210	I	110 112	68		EXT RFS		
6703	301	I	114 115	28	INSTACK			

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LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
6774	401	II	144 150	308	NOT INNER
7010	401	JJ	145 150	118	OPT
7025	411	I2	151 153	148	NOT INNER
7032	411	J2	152 153	38	INSTACK
7052	419	II	159 163	218	EXT REFS
7075	429	II	166 180	658	EXT REFS NOT INNER
7110	428	II	170 176	328	NOT INNER
7126	428	JJ	171 176	118	OPT
7143	426	I2	177 179	148	NOT INNER
7150	426	J2	178 179	38	INSTACK
7174	439	II	190 191	38	INSTACK
7226	449	II	201 207	258	EXT REFS
7256	451	II	209 210	48	INSTACK
7302	460	II	215 219	228	NOT INNER
7313	461	JJ	217 218	38	INSTACK

COMMON BLOCKS	LENGTH	MEMBERS - BIAS NAME(LENGTH)			
START	37720	0 X (36000)	36000	XXSUM (1600)	37600 XSUM (40)
ACDATA	18	37640 XBAR (40)	37680	SIGMA (40)	2 CBAR (1)
		0 SAREA (1)	1	BSPAN (1)	5 G (1)
		3 M (1)	4	RHU (1)	8 IZ (1)
		6 IX (1)	7	IY (1)	11 ALPHT (1)
		9 IXZ (1)	10	DELET (1)	14 DELRT (1)
FLAGS	46	12 BETT (1)	13	DELAT (1)	17 RT (1)
		15 QT (1)	16	PT (1)	41 LATOP (1)
		0 NPTS (1)	1	ICNT (40)	44 IACELOP(1)
		42 ITRIMOP(1)	43	ICALL (1)	
		45 IFILOP (1)			
ORDER	2	0 IEQ (1)	1	N (1)	
ACCEL	9000	0 AX (900)	900	AY (900)	1800 AZ (900)
		2700 PDOT (900)	3600	QDOT (900)	4500 RDOT (900)
		5400 VEL (900)	6300	P (900)	7200 Q (900)
KNOT	23	8100 R (900)			
		0 XNOT (23)			

EQUIV CLASSES	LENGTH	MEMBLRS - BIAS NAME(LENGTH)		
A	6241	0 RR (62+1)		

STATISTICS

PROGRAM LENGTH	45457B	19247
BUFFER LENGTH	56708	3000
CM LABELED COMMON LENGTH	133331B	46809

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STATISTICS

52000B CM USED

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SUPERSTRUCTURE DATASET 73/74 OPT=1 85/05/02, 13.03.28

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REAL M_{1Y},IX_{1Z},IX_Z

SUPERSTRUCTURE DATASETS,T,Y,X)

DIMENSION T(900),Y(900),X(40,900)

DIMENSION DELA(900),DELR(900),DELE(900)

DIMENSION NAME(S)(50),UNITS(50),HOR(8),DATA(50),

TRTEM(300),MRK1(900),MRK2(900),MRK3(900),MRK4(900),

SWRK(900),MRK(900),RDU(900),RUD(900),PTGM(900),ATEM(900),

COMMON/FLA65/ NPTS,ICNT(40),LATOP,ITRIMOP,ICALL,IFCLOC,P,IFLLP

DBETI,DELT,IQ,PT,RH

COMMON/ACCDATA/ S,B,C,M,RHD,G,IX,TY,IZ,IXZ,DELET,ALPHT

VE(L(900),P(900),A(900),AY(900),AZ(900),POOT(900),AOOT(900),KOOT(900)

CMMON/ACCBL/ AX(900),AY(900),AZ(900),POOT(900),AOOT(900)

CMMON/URDBR/ IED,N

J2-NPTS/2

IF(ICALL,G1,I) GO TO 46

C C C

20

C C C

25

* 501 READ(I) ID,NCH,(NAME\$1),I=1,NCH),(UNITS(I),I=1,NCH),HDR

IF(NPTS-JPTS) EQ, J) NPTS-JPTS-1

IF(EOP(I)) 9996,800T

502 READ(I) (DATA(J),J=1,NCH)

500 CONTINUE

3001 II (ITS),G1,DATA(I)) 502,600

IF(GEOF(I)) 9996,602

602 PRINT 1980,ALPHT,BETI,DELT,DELET,DELRT

1980 FORMAT(//,10X,*TRIM VALUES*,15X,

45 DO 15 I=1,NPTS
*10X,5E12.5)
**ALPHT BETI ALLT DELET
DO 15 I=1,NPTS
READ(I) (DATA(J),J=1,NCH)
IF(GEOF(I)) 9996,601

77

```
601 CONTINUE
    CALL GETRAN(IR,IN,2,RN,Y1,Y2)
45     IN=IN+1
      T(I)= DATA(1)-TS
      VEL(I)= DATA(2)
      BETA(I)= DATA(18)-BETT
      ALPH(I)= DATA(19)
50     P(I)= DATA(5)
      Q(I)=DATA(6)+.003*RN
      R(I)= DATA(7)
      AX(I)=DATA(10)
      AY(I)= DATA(11)
55     AZ(I)= DATA(12)
      DELA(I)= DATA(13)-DELAT
      DELR(I)= DATA(15)-DELRT
      DELE(I)=DATA(14)-DELET
      PDDOT(I)=DATA(16)  QDDOT(I)=DATA(20)  RDOT(I)=DATA(17)

60     15 CONTINUE
        IF(IACELOP.EQ.0) GO TO 46
        CALL SECDER(3,3,T,P,PDD,PTEM,NPTS,P0,P3,.5,.5,WRK1,WRK2,WRK3,
1WRK4,WRK5,WRK6)
        CALL SECDER(3,3,T,Q,QDD,QTEM,NPTS,P0,P3,.5,.5,WRK1,WRK2,WRK3,
1WRK4,WRK5,WRK6)
        CALL SECUDER(3,3,T,R,RDD,RTEM,NPTS,P0,P3,.5,.5,WRK1,WRK2,WRK3,
1WRK4,WRK5,WRK6)
        DO 45 I=1,NPTS
          PDDOT(I)=DERSP(T(I),T,P,NPTS,PDD,PTEM)
          QDDOT(I)=DERSP(T(I),T,Q,NPTS,QDD,QTEM)
          RDOT(I)=DERSP(T(I),T,R,NPTS,RDD,RTEM)
45     46 CONTINUE
46     CONTINUE
        IF(LATOP.NE.1) GO TO 803
        DO 800 I=1,NPTS
          X(1,I)=BETA(I)
          X(2,I)=P(I)*B/(2.*VEL(I))
          X(3,I)=R(I)*B/(2.*VEL(I))
          X(4,I)=DELA(I)
          X(5,I)=DELR(I)
          X(6,I)=ALPH(I)*X(1,I)
          X(7,I)=ALPH(I)*X(2,I)
          X(8,I)=X(3,I)*ALPH(I)
          X(9,I)=DELA(I)*ALPH(I)
800   
```

DATAFILE ROUTINE SUBROUTINE FIN 4.8+552 OPT=1 73/74 05/05/02. 13.03.28

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      IF(ALPH(I).GE.XNOT(10)) X(22,I)=ALPH(I)-XNOT(10)
      IF(ALPH(I).GE.XNOT(10)) X(23,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(11)) X(24,I)=ALPH(I)-XNOT(11)
      IF(ALPH(I).GE.XNOT(11)) X(25,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(12)) X(26,I)=ALPH(I)-XNOT(12)
      IF(ALPH(I).GE.XNOT(12)) X(27,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(13)) X(28,I)=ALPH(I)-XNOT(13)
      IF(ALPH(I).GE.XNOT(13)) X(29,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(14)) X(30,I)=ALPH(I)-XNOT(14)
      IF(ALPH(I).GE.XNOT(14)) X(31,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(15)) X(32,I)=ALPH(I)-XNOT(15)
      IF(ALPH(I).GE.XNOT(15)) X(33,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(16)) X(34,I)=ALPH(I)-XNOT(16)
      IF(ALPH(I).GE.XNOT(16)) X(35,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(17)) X(36,I)=ALPH(I)-XNOT(17)
      IF(ALPH(I).GE.XNOT(17)) X(37,I)=X(2,I)
      IF(ALPH(I).GE.XNOT(7)) X(38,I)=X(3,I)
      801 IF(ALPH(I).GE.XNOT(11)) X(39,I)=X(3,I)
      145 804 CONTINUE
            PRINT 964, ID, I EQ, NPTS
            IF(1CALL.GT.1) GO TO 999
            IF(LATOP.EQ.0) GO TO 50
            PRINT 968
      150 969 FORMAT(1X,7X,*TIME*,11X,*V*,12X,*BETA*,11X,*P*,14X,*R*,11X,
             1*DELA*,11X,*DELR*)
      964 FORMAT(1H1,3X,*RUN*,15,5X,*EQUATION *,I2,5X,*NPTS*,I5,///)
            PRINT 962, (T(I),VEL(I),BETA(I),P(I),R(I),DELA(I),DELR(I),I=1,NPTS)
      962 FORMAT(7(2X,E12.4))
      155  CALL INFOPLT(1,NPTS,T,1,DELA,1,0.,0.,0.,0.,0.,1,1HT,
             14,4HDELA,22,7.,5.,.75,.75)
            CALL INFOPLT(1,NPTS,T,1,DELR,1,0.,0.,0.,0.,0.,1,1HT,
             14,4HDELR,22,7.,5.,.75,.75)
            GO TO 999
      160 50 CONTINUE
            PRINT 998
      998 FORMAT(1X,7X,*TIME*,11X,*V*,11X,*ALPHA*,11X,*Q*,14X,*DELE*)
            PRINT 997, (T(I),VEL(I),ALPH(I),Q(I),DELE(I),I=1,NPTS)
      997 FORMAT(5(2X,E12.4))
            CALL INFOPLT(1,NPTS,T,1,DELE,1,0.,0.,0.,0.,0.,1,1HT,
             14,4HDELE,22,7.,5.,.75,.75)
            GO TO 999
      998 PRINT 9999

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SUBROUTINE DATASLT

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VARIABLES	SN	TYPE	RELOCATION									
15	DELAT	RFAL	ACDATA	REFS	11	36	56	DEFINED	34			
10315	DELE	REAL	ARRAY	REFS	6	106	163	165	DEFINED	58		
12	DELET	REAL	ACDATA	REFS	11	36	58	DEFINED	34			
6511	DLR	REAL	ARRAY	REFS	6	80	85	153	157			
			DEFINED		57							
16.	DELRT	REAL	ACDATA	REFS	11	36	57	DEFINED	34			
5	G	REAL	ACDATA	REFS	11							
12265	HDR	REAL	ARRAY	REFS	7	DEFINED	28					
1264	I	INTEGER		REFS	46	47	48	49	50	51	52	
				REFS	53	54	55	56	57	58	3*59	2*69
					2*70	2*71	2*76	3*77	3*78	2*79	2*80	3*81
					3*82	3*83	3*84	3*85	4*86	4*87	4*88	4*89
					4*90	3*91	3*92	3*93	3*94	3*95	3*96	2*97
					3*98	3*99	2*104	3*105	2*106	108	3*109	3*110
					3*111	3*112	3*113	3*114	3*115	3*116	3*117	3*118
					3*119	3*120	3*121	3*122	3*123	3*124	3*125	3*126
					3*127	3*128	3*129	3*130	3*131	3*132	3*133	3*134
					3*135	3*136	3*137	3*138	3*139	3*140	3*141	3*142
					3*143	3*144	7*153	5*163	171	DEFINED	40	68
					75	103	153	163				
54	IACELOP	INTEGER		FLAGS	REFS	13	61					
53	ICALL	INTEGER		FLAGS	REFS	13	21	147				
1	ICNT	INTEGER	ARRAY	FLAGS	REFS	13						
1260	ID	INTEGER		REFS	146	DEFINED	28					
0	IEQ	INTEGER		REFS	14	146						
55	IFILOP	INTEGER		FLAGS	REFS	13						
1272	III	INTEGER		REFS	108	DEFINED	107					
1262	IN	INTEGER		REFS	44	45	DEFINED	28	45			
82	1273	IK	INTEGER	ARRAY	REFS	3	44	DEFINED	2*28			
52	ILKIMOP	INTEGER		FLAGS	REFS	13	33					
12203	IUNITS	INTEGER	*UNDEF	REFS	7							
6	IX	RFAL		ACDATA	REFS	2	11					
11	IXZ	REAL		ACDATA	REFS	2	11					
7	IY	REAL		ACDATA	REFS	2	11					
10	IZ	REAL		ACDATA	REFS	2	11					
1263	J	INTEGER		REFS	29	41	171	DEFINED	29	41		
1257	JPTS	INTEGER		REFS	2*24	DEFINED	23					
1256	J2	INTEGER		REFS	23	DEFINED	22					
51	LATUP	INTEGER		FLAGS	REFS	13	74	148				
3	M	REAL		ACDATA	REFS	2	11					
1	N	INTEGER		ORDER	REFS	14						
12121	NAMES	INTEGER	*UNDEF	REFS	7							

SUBROUTINE DATASET			73/74	OPT=1	FTN 4.8+552			85/05/02. 13.03.28			PAGE	
VARIABLES	SN	TYPE	RELOCATION			REFS	29	41	DEFINED	28		
1261	NCH	INTEGER	ARRAY	ACCEL	FLAGS	REFS	13	22	24	40	62	
0	NPTS	INTEGER				REFS	68	69	71	75	103	
						155	157	163	165	24		
14234	P	REAL	ARRAY	ACCEL	DEFINED	REFS	15	62	69	77	153	
12357	PDD	REAL	ARRAY	ACCEL		REFS	50					
5214	PDOT	REAL	ARRAY	ACDATA		REFS	15		DEFINED	59	69	
20	PT	REAL				REFS	11					
17573	PTEM	REAL	ARRAY			REFS	8		62	69		
1270	PO	REAL				REFS	62		64	66		
1271	P3	REAL				REFS	62		64	66		
16040	Q	REAL	ARRAY	ACCEL	DEFINED	REFS	15	64	70	105	163	
14163	QDD	REAL	ARRAY	ACCEL		REFS	51					
7020	QDOT	REAL	ARRAY	ACDATA		REFS	8		64	70		
17	QT	REAL				REFS	15		DEFINED	59	70	
21377	QTEM	REAL	ARRAY			REFS	11					
17644	R	REAL	ARRAY	ACCEL	DEFINED	REFS	8		64	70		
15767	RDD	REAL	ARRAY			REFS	15		DEFINED	59		
10624	RDOT	REAL	ARRAY	ACCEL		REFS	52					
4	RHO	REAL		ACDATA		REFS	8		66	71		
1265	RN	REAL				REFS	15		DEFINED	59	71	
21	RT	REAL		ACDATA		REFS	11					
23203	RTEM	REAL	ARRAY			REFS	44		51			
0	S	REAL				REFS	11					
0	T	REAL	ARRAY	F.P.		REFS	8		66	71		
83	0	TS	REAL	ARRAY	F.P.	REFS	11					
12430	VEL	REAL	ARRAY	ACCEL	DEFINED	REFS	4					
25007	WRK1	REAL	ARRAY			REFS	153		155	157	163	2*69
26613	WRK2	REAL	ARRAY			REFS	15		157	163	165	2*70
30417	WRK3	REAL	ARRAY			REFS	8		62	64	66	2*71
32223	WRK4	REAL	ARRAY			REFS	8		62	64	66	46
34027	WRK5	REAL	ARRAY			REFS	8		62	64	66	
35633	WRK6	REAL	ARRAY			REFS	8		62	64	66	
0	X	REAL	ARRAY	F.P.		REFS	4		81	82	83	86
						REFS	89	90	2*91	2*92	2*93	2*94
						REFS	99	110	112	114	116	118
						REFS	124	126	128	130	132	134
						REFS						136
						REFS						138

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VARIABLES	SN	TYPE	RELOCATION	140	142	143	144	DEFINED	1	76	77
				78	79	80	31	82	83	84	85
				86	87	88	89	90	91	92	93
				94	95	96	97	98	99	104	105
				106	108	109	110	111	112	113	114
				115	116	117	118	119	120	121	122
				123	124	125	126	127	128	129	130
				131	132	133	134	135	136	137	138
0	XNOT	REAL	ARRAY KNOT	RFFS	17	2*109	110	2*111	112	2*113	114
				2*115	116	2*117	118	2*119	120	2*121	122
				2*123	124	2*125	126	2*127	128	2*129	130
				2*131	132	2*133	134	2*135	136	2*137	138
				2*134	140	2*141	142	143	144		
0	Y	REAL	ARRAY F.P.	REFS	4	DEFINED	1				
1266	Y1	* REAL		REFS	44						
1267	Y2	* REAL		REFS	44						

FILE NAMES	MODE	OUTPUT	FMT	WRITES	36	146	149	153	161	163	168	171
				174								
				READS	29	41						

EXTERNALS	TYPE	ARGS	REFERENCES	
DERSP	REAL	6	69	70
EOF	REAL	1	30	42
GETRAN		6	44	
INFOPLT		20	155	157
SECDFR		17	62	64

STATEMENT LABELS		DEF LINE	REFERENCES	
0 15		60	40	
0 45		72	68	
160 46		73	21	61
573 50		160	148	
0 501	INACTIVE	27		
23 502		29	31	
0 600	INACTIVE	32	31	
0 601	INACTIVE	43	42	
45 602		36	33	
0 800		100	75	
0 801		144	103	

SUBROUTINE DATASET

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STATEMENT LABELS DEF LINE REFERENCES

223	803		102	74				
532	804		145	101				
0	805		108	107				
1156	962	FMT	154	153				
1133	964	FMT	152	146				
1122	968	FMT	150	149				
1205	997	FMT	164	163				
1164	998	FMT	162	161				
631	999		176	147	159	167	170	173
1072	1980	FMT	37	36				
0	8001	INACTIVE	31	30				
0	9994	INACTIVE	174					
1235	9995	FMT	175	174				
624	9995		171	30	42			
1224	9997	FMT	172	171				
0	9998	INACTIVE	168					
1213	9999	FMT	169	168				

LOOPS LABEL INDFX FRUM-TD LENGTH PROPERTIES

50	15	I	40 60	538	EXT REFS	EXITS
136	45	I	58 72	228	EXT REFS	
171	800	I	75 100	318	OPT	
224	801	I	103 144	3068	NOT INNER	
241	805	III	107 108	28	INSTACK	
544	I		153 153	178	EXT REFS	
600	I		163 163	148	EXT REFS	

COMMON BLOCKS LENGTH MEMBERS - BIAS NAME(LENGTH)

85	ACDATA	18	0 S	(1)	1 8	(1)	2 C	(1)
			3 M	(1)	4 RHO	(1)	5 G	(1)
			6 IX	(1)	7 IY	(1)	8 IZ	(1)
			9 IX2	(1)	10 DELET	(1)	11 ALPHT	(1)
			12 BETT	(1)	13 DELAT	(1)	14 DELRT	(1)
			15 QT	(1)	16 PT	(1)	17 RT	(1)
			0 NPTS	(1)	1 ICNT	(40)	41 LATDP	(1)
			42 ITRIMOP(1)		43 ICALL	(1)	44 IACELDP(1)	
			45 IFILUP(1)					
			0 IEQ	(1)	1 N	(1)		
			0 AX	(900)	900 AY	(900)	1800 AZ	(900)
			2700 PDOT	(900)	3600 QDOT	(900)	4500 RDOT	(900)
			5400 VEL	(900)	6300 P	(900)	7200 Q	(900)
			8100 R	(900)				

ORIGINAL PAGE IS
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SUBROUTINE DATASET 73/74 OPT=1 PAGE 10

COMMON BLOCKS LENGTH 23
MEMBERS - BASIS NAME(LENGTH)

STATISTICS LENGTH 52000B CM USED
PROGRAM LENGTH 37534B 16220 9069
CM LABELED COMMON LENGTH 21601A

SUBROUTINE AUTO

73/74 OPT=1

FTN 4.8+552

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PAGE 1

```
1      SUBROUTINE AUTO(X,MAXLAG,V,W,YSQ,YHAT,Y)
2      DIMENSION X(1),W(1),YHAT(1),Y(1)
3      MLAGM1=MAXLAG-1
4      XSUM=0. $XXSUM=0.
5      DO 7 I=1,N
6      7 XSUM=XSUM+X(I)
7      XMEAN=XSUM/N
8      DO 8 I=1,N
9      8 X(I)=X(I)-XMEAN
10     DO 12 I=1,N
11     12 XXSUM=XXSUM+X(I)*X(I)
12     PPINT 900,XMEAN,XXSUM
13     900 FORMAT(1X,*RESIDUAL MEAN IS*,E12.5,/,1X,
14     *SIGMA SQ OF RESIDUALS IS*,E12.5)
15     DO 2 K=1,MAXLAG
16     2 SUM=0. $W0=0.
17     NMK=N-K
18     DO 1 I=1,NMK
19     1 SUM=SUM+X(I)*X(I+K)
20     2 W(K)=1./(N-K)*SUM
21     DO 3 I=1,N
22     3 W0=W0+X(I)*X(I)
23     W0=W0/N
24     DO 9 I=1,MAXLAG
25     9 W(MAXLAG+2-I)=W(MAXLAG+1-I)
26     W(1)=W0
27     DO 10 I=1,N
28     10 X(I)=X(I)+XMEAN
29     DO 11 I=1,MAXLAG
30     11 W(I)=W(I)/W0
31     RETURN
END
```

SYMBOLIC REFERENCE MAP (R=3)

ENTRY POINTS	DEF LINE	REFERENCES
3 AUTO	1	31

ORIGINAL PAGE IS
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SUBROUTINE AUTO 73/74 OPT=1 FIN 4.8+552 85/05/02. 13.03.28 PAGE 2

VARIABLES	SN	TYPE	RELOCATION	REFS	6	2*9	2*11	2*19	2*22	2*25	2*28
	153	I		2*30	DEFINED	5	8	10	18	21	24
155 K		INTEGER		REFS	27	29					
0 MAXLAG	0	INTEGER	F.P.	REFS	17	19	2*20	DEFINED	15		
150 MLAGM1 *	150	INTEGER		REFS	3	15	24	2*25	29		
0 N	0	INTEGER	F.P.	DEFINED	1						
160 NMK		INTEGER		REFS	3						
156 SUM		REAL		REFS	5	7	8	10	17	20	21
0 W	0	REAL	ARRAY	F.P.	23	27	DEFINED	1			
157 W0		REAL		REFS	19	18	DEFINED	17			
0 X	0	REAL	ARRAY	F.P.	2	20	DEFINED	16	19	20	25
154 XMEAN		REAL		REFS	25	25	30	DEFINED	1		
151 XSUM		REAL		REFS	30	22	23	30	DEFINED	16	22
152 XXSUM		REAL		REFS	22	23	26				
0 Y	0	REAL	ARRAY	F.P.	REFS	2	6	9	2*11	2*19	2*22
0 YHAT	0	REAL	ARRAY	F.P.	1	9	28				
0 YSQ	0	REAL	*UNUSED	F.P.	REFS	4	12	28	DEFINED	7	
				DEFINED	6	7	DEFINED	4	6		
				REFS	11	12	DEFINED	4	11		
				DEFINEd	1						
				DEFINEd	1						

FILE NAMES	MODE		
OUTPUT	FMT	WRITES	12

STATEMENT LABELS	DEF LINE	REFERENCES
0 1	19	18
0 2	20	15
0 3	22	21
0 7	6	5
0 8	9	8
0 9	25	24
0 10	28	27
0 11	30	29
0 12	11	10
137 900	FMT	13
		12

SUBROUTINE AUTO		73/74	OPT=1		FTN 4.8+552	85/05/02. 13.03.28	PAGE	3
LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES			
15	7	I	5 6	38	INSTACK			
27	8	I	8 9	38	INSTACK			
36	12	I	10 11	38	INSTACK			
44	2	K	15 20	248	NOT INNER			
55	1	I	18 19	48	INSTACK			
73	3	I	21 22	38	INSTACK			
106	9	I	24 25	28	INSTACK			
116	10	I	27 28	38	INSTACK			
126	11	I	29 30	38	INSTACK			

STATISTICS

PROGRAM LENGTH	170B	120
52000B CM USED		

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1 SUBROUTINE FIL(T,P,NPTS)
2 DIMENSION PF(500),H(500),P(500),T(500),HOMEKA(500)
3 PI=3.14159 \$FC=2.5 \$T=2.51 \$WC=2*PI*FC \$WT=2*PI*FT
4 NMID=NPTS/2 \$DT=.02
5 W2=(WT-WC)*(WT-WC)
6 DO 3 I=1,NMID
7 K=I
8 H(I)=PI/(2*K*DT)*(SIN(WT*K*DT)+SIN(WC*K*DT))/(PI*PI-W2*K*DT
9 1*K*DT)
10 H0=FC+FT
11 NPM1=NPTS-1
12 HNORM=H0
13 DO 1 I=1,NMID
14 HNORM=HNORM+H(I)*2.
15 DO 2 I=1,NMID
16 H(I)=H(I)/HNORM
17 H0=H0/HNORM
18 DO 5 I=2,NMID
19 IM1=I-1
20 P(I)=H0*P(I)
21 DO 51 J=1,IM1
22 PF(I)=PF(I)+H(J)*(P(I+J)+P(I-J))
23 DO 52 J=1,NMID
24 PF(I)=PF(I)+2*H(J)*P(I+J)
25 CONTINUE
26 NP2=NMID+2
27 DO 4 I=NP2,NPM1
28 NPM1=NPTS-I
29 PF(I)=H0*P(I)
30 DO 41 J=1,NPM1
31 PF(I)=PF(I)+H(J)*(P(I-J)+P(I+J))
32 NPM1P1=NPM1+1
33 DO 42 J=NPM1P1,NMID
34 PF(I)=PF(I)+2*H(J)*P(I-J)
35 CONTINUE
36 PF(I)=H0*P(I) \$PF(NPTS)=H0*P(NPTS) \$PF(NMID+1)=H0*P(NMID+1)
37 DO 10 J=1,NMID
38 PF(I)=PF(I)+2*H(J)*P(I+J)
39 PF(NMID+1)=PF(NMID+1)+H(J)*(P(NMID+1+J)+P(NMID+1-J))
40 PF(NPTS)=PF(NPTS)+2*H(J)*P(NPTS-J)
41 DO 6 I=1,NPTS
42 P(I)=PF(I)

SUBROUTINE FIL

73/74 OPT=1

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PAGE

2

RETURN
END

SYMBOLIC REFERENCE MAP (R=3)

ENTRY POINTS	DEF LINE	REFERENCES										
3 FIL	1	43										
VARIABLES	SN TYPE	RELUCATION										
237 DT	REAL		REFS	5*8	DEFINED	4						
232 FG	REAL		REFS	3	10	DEFINED	3					
233 FT	REAL		REFS	3	10	DEFINED	3					
1237 H	REAL	ARRAY	REFS	2	14	16	22	24	31	34		
			REFS	38	39	40	DEFINED	8	16			
245 HNORM	REAL		REFS	14	16	17	DEFINED	12	14			
2223 HOMEGA	REAL	*UNDEF	REFS	2								
243 HU	REAL		REFS	12	17	20	29	3*36				
			DEFINED	10	17							
241 I	INTEGER		REFS	7	8	14	2*16	19	2*20	4*22		
			REFS	23	3*24	28	2*29	4*31	3*34	2*42		
			DEFINED	6	13	15	18	27	41			
246 IM1	INTEGER		REFS	21	DEFINED	19						
247 J	INTEGER		REFS	3*22	2*24	3*31	2*34	2*38	3*39	2*40		
			DEFINED	21	23	30	33	37				
242 K	INTEGER		REFS	5*8	DEFINED	7						
236 NMID	INTEGER		REFS	6	13	15	18	23	26	33		
			REFS	2*36	37	4*39	DEFINED	4				
251 NPM1	INTEGER		REFS	30	32	DEFINED	28					
252 NPM1P1	INTEGER		REFS	33	DEFINED	32						
244 NPM1	INTEGER		REFS	27	DEFINED	11						
0 NPTS	INTEGER	F.P.	REFS	4	11	28	2*36	3*40	41			
			DEFINED	1								
250 NP2	INTEGER		REFS	27	DEFINED	26						
0 P	REAL	ARRAY	F.P.	REFS	2	20	2*22	24	29	2*31	34	
				3*36	38	2*39	40	DEFINED	1	42		
253 PF	REAL	ARRAY		REFS	2	22	24	31	34	38	39	
				40	42	DEFINED	20	22	24	29	31	
				34	3*36	38	39	40				

SUBROUTINE FIL

73/74 OPT=1

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VARIABLES	SN	TYPE	RELOCATION	REFS	2*3	3*8	DEFINED	3
231	P1	REAL		REFS	2	DEFINED	1	
0	T	REAL	ARRAY F.P.	REFS	2*5	8	DEFINED	3
234	WC	REAL		REFS	2*5	8	DEFINED	3
235	WT	REAL		REFS	8	DEFINED	5	
240	W2	REAL						

EXTERNALS	SIN	TYPL	ARGS	REFERENCES
			1 LIBRARY	2*8

STATEMENT LABELS	DEF	LINE	REFERENCES
0 1	14	13	
0 2	16	15	
0 3	8	6	
0 4	35	27	
0 5	25	18	
0 6	42	41	
0 10	40	37	
0 41	31	30	
0 42	34	33	
0 51	22	21	
0 52	24	23	

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES	EXT REFS
22	3	I	6 8	22B		
53	1	I	13 14	3B	INSTACK	
62	2	I	15 16	3B	INSTACK	
70	5	I	18 25	33B		NOT INNER
101	51	J	21 22	4B	INSTACK	
114	52	J	23 24	4B	INSTACK	
126	4	I	27 35	35B		NOT INNER
140	41	J	30 31	4B	INSTACK	
154	42	J	33 34	4B	INSTACK	
201	10	J	37 40	11B	OPT	
217	6	I	41 42	2B	INSTACK	

STATISTICS
PROGRAM LENGTH 3222B
52000B CM USED 1682

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FUNCTION JERS

73 / 74 UPT = 1

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FUNCTION DERSP(XX,X,Y,N,P,H)
FUNCTION DERSP

DERSP IS USED TO OBTAIN THE FIRST DERIVATIVE OF SPLINE
CURVE FITTED DATA

USAGE -
X = DERSP(XX,X,Y,N,P,H)
NOTE - IF XX LESS THAN X(1) THEN DERSP = DX(1)/DY
      IF XX GREATER THAN X(N) THEN DERSP = DX(N)/DY

WHERE -
XX           INDEPENDENT VARIABLE FOR WHICH INTERPOLATED SLOPE
IS DESIRED
X            N-DIMENSIONED VECTOR OF INDEPENDENT POINTS
Y            N-DIMENSIONED VECTOR OF DEPENDENT POINTS
N            NUMBER OF DATA POINTS
P            N-DIMENSIONED VECTOR FROM UPDATE
H            (N-1)-DIMENSIONED VECTOR FROM UPDATE

SUBROUTINES CALLED -
NONE

DIMENSION X(1),Y(1),P(1),H(1)
XP=XX
IF (XX.LT.X(1)) GO TO 1
K=N-1
DO 2 I=1,K
IF (XX.LT.X(I+1)) GO TO 3
CONTINUE
I=K
XP=X(N)
GO TO 3
XP=X(1)
I=1
F1=(X(I+1)-XP)**2
F2=(XP-X(I))**2
F3=H(I)/3.
DERSP=((F3-F1/H(I))*P(I) + (F2/H(I)-F3)*P(I+1))/2.+ (Y(I+1)-Y(I))
H(I)
RETURN
END

```

DSCF 230
DSCF 10
DSCF 20
DSCF 30
DSCF 40
DSCF 50
DSCF 60
DSCF 70
DSCF 80
DSCF 90
DSCF 100
DSCF 110
DSCF 120
DSCF 130
DSCF 140
DSCF 150
DSCF 160
DSCF 170
DSCF 180
DSCF 190
DSCF 200
DSCF 210
DSCF 220
DSCF 240
DSCF 250
DSCF 260
DSCF 270
DSCF 280
DSCF 290
DSCF 300
DSCF 310
DSCF 320
USCF 330
DSCF 340
DSCF 350
DSCF 360
DSCF 370
DSCF 380
/ DSCF 390
DSCF 400
DSCF 410
DSCF 420

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FUNCTION PERSP

73 / 74 OPT = 1

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PAGE

2

SYMBOLIC REFERENCE MAP ($\kappa=3$)

ENTRY POINTS		DEF LINE	REFERENCES	
4	DERSP	1	41	
<u>VARIABLES</u>		<u>SN</u>	<u>TYPE</u>	<u>RELOCATION</u>
56	DERSP	REAL		DEFINED 39
62	F1	REAL		REFS 39
63	F2	REAL		REFS 39
64	F3	REAL		REFS 2*39
0	H	REAL	ARRAY	F.P.
61	I	INTEGER		
60	K	INTEGER		DEFINED 28
0	N	INTEGER		REFS 28
0	P	REAL	ARRAY	F.P.
0	X	REAL	ARRAY	F.P.
57	XP	REAL		DEFINED 1
0	XX	REAL		REFS 36
0	Y	REAL	ARRAY	F.P.
27	1			REFS 25
0	2			REFS 24
32	3			REFS 24
<u>STATEMENT LABELS</u>		DEF LINE	REFERENCES	
27	1	34	26	
0	2	30	28	
32	3	36	29 33	
46	LOOPS	LABEL	INDEX	FRJM-TO LENGTH PROPERTIES
	15	2	I	28 30 58 INSTACK EXITS
<u>STATISTICS</u>		PROGRAM LENGTH	708	96
		52000B CM USED		

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FTN 4.8+552

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1      SUBROUTINE SECDER(L1,L2,X,Y,P,H,N,P0,P3,XK1,XK2,A,B,C,D,GAMMA,
1      BETA)          UPD  480
C      SUBROUTINE SECDER          UPD  490
C
5      C      SECDER IS USED WITH FUNCTION SPLINE TO PERFORM A SPLINE          UPD  10
C      INTERPOLATION. IT IS USED TO GENERATE P AND H.          UPD  20
C
C      C      USAGE -          UPD  30
C      CALL SECDER(L1,L2,X,Y,P,H,N,P0,P3,XK1,XK2,A,B,C,D,GAMMA,BETA)          UPD  40
10     C
C      WHERE -          UPD  50
C      L1,L2  DETERMINE THE END CONDITIONS AT X(1) AND X(N) TO BE          UPD  60
C      USED. (SEE BELOW)          UPD  70
C      X    N-DIMENSIONED VECTOR OF INDEPENDENT POINTS          UPD  80
C      Y    N-DIMENSIONED VECTOR OF DEPENDENT POINTS          UPD  90
15     C      P    N-DIMENSIONED VECTOR TO BE RETURNED          UPD 100
C      H    (N-1)-DIMENSIONED VECTOR TO BE RETURNED          UPD 110
C      N    NUMBER OF DATA POINTS          UPD 120
C      SECND DERIVATIVES ARE GIVEN AT THE END POINTS          UPD 130
20     C      XK1  NOT USED          UPD 140
C      XK2  NOT USED          UPD 150
C      IF L1=1 THEN          UPD 160
C      P0   SECOND DERIVATIVE AT X(1),Y(1)          UPD 170
C      IF L2=1 THEN          UPD 180
25     C      P3   SECOND DERIVATIVE AT X(N),Y(N)          UPD 190
C      FIRST DERIVATIVES ARE GIVEN AT THE END POINT          UPD 200
C      XK1  NOT USED          UPD 210
C      XK2  NOT USED          UPD 220
C      IF L1=2 THEN          UPD 230
30     C      P0   FIRST DERIVATIVE AT X(1),Y(1)          UPD 240
C      IF L2=2 THEN          UPD 250
C      P3   FIRST DERIVATIVE AT X(N),Y(N)          UPD 260
C      NO INFORMATION ABOUT THE CURVE IS KNOWN          UPD 270
C      P0   NOT USED          UPD 280
C      P3   NOT USED          UPD 290
35     C      IF L1=3 THEN          UPD 300
C      XK1  P''(3,0) = XK1*P''(3,1), XK1 GREATER THAN 0          UPD 310
C      IF L2=3 THEN          UPD 320
C      XK2  P''(3,N) = XK2*P''(3,N-1), XK2 GREATER THAN 0          UPD 330
40     C      A    N-DIMENSIONED WORK VECTOR          UPD 340
C      B    N-DIMENSIONED WORK VECTOR          UPD 350
C      C    N-DIMENSIONED WORK VECTOR          UPD 360

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ORIGINAL PAGE
OF POOR
QUALITY

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C      D      N-DIMENSIONED WORK VECTOR          UPD  410
C      BETA   N-DIMENSIONED WORK VECTOR          UPD  420
45     C      GAMMA   N-DIMENSIONED WORK VECTOR    UPD  430
C      SUBROUTINES CALL -
C      NONE
C      DIMENSION X(N),Y(N),A(N),B(N),C(N),D(N),GAMMA(N),BETA(N),H(N),P(N)
50     K=N-1
      DO 1 J=1,K
1 H(J)=X(J+1)-X(J)
      DO 2 J=2,K
2 A(J) = H(J-1)/H(J)
      B(J) = 2.* (H(J)+H(J-1))/H(J)
      C(J) = 1.
      2 D(J) = 6./H(J)*((Y(J+1)-Y(J))/H(J)-(Y(J)-Y(J-1))/H(J-1))
      IF(L1.EQ.2) GO TO 20
      IF(L1.EQ.3) GO TO 10
      60     B(1)=1.
      C(1)=0.
      D(1)=P0
      GO TO 30
      65     10 B(1)=1.
      C(1)=-XK1
      D(1)=0.
      GO TO 30
      70     20 B(1)=H(1)/3.
      C(1)=H(1)/6.
      D(1)=(Y(2)-Y(1))/H(1)-P0
      30 IF(L2.EQ.2) GO TO 21
      IF(L2.EQ.3) GOTO 11
      A(N)=0.
      B(N)=1.
      D(N)=P3
      GO TO 40
      75     11 A(N)=-XK2
      B(N)=1.
      D(N)=0.
      GO TO 40
      80     21 A(N)=H(K)/76.
      B(N)=H(K)/3.
      D(N)=P3-(Y(N)-Y(K))/H(K)
      UPD  510
      UPD  520
      UPD  530
      UPD  540
      UPD  550
      UPD  560
      UPD  570
      UPD  580
      UPD  590
      UPD  600
      UPD  610
      UPD  620
      UPD  630
      UPD  640
      UPD  650
      UPD  660
      UPD  670
      UPD  680
      UPD  690
      UPD  700
      UPD  710
      UPD  720
      UPD  730
      UPD  740
      UPD  750
      UPD  760
      UPD  770
      UPD  780
      UPD  790
      UPD  800
      UPD  810
      UPD  820
      UPD  830
      UPD  840

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SUBROUTINE SECDFR

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PAGE

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85      40 BETA(1)=B(1)          UPD 850
        GAMMA(1)=D(1)/BETA(1)    UPD 860
        DO 6 J=2,N                UPD 870
        BETA(J)=B(J)-A(J)*C(J-1)/BETA(J-1) UPD 880
6       GAMMA(J)=(D(J)-A(J)*GAMMA(J-1))/BETA(J) UPD 890
90      P(N) = GAMMA(N)         UPD 900
        DO 7 J=1,K                UPD 910
        M=N-J                      UPD 920
7       P(M)=GAMMA(M)-C(M)*P(M+1)/BETA(M)   UPD 930
        RETURN                     UPD 940
95      END                       UPD 950

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SYMBOLIC REFERENCE MAP (R=3)

ENTRY POINTS	DEF LINE	REFERENCES
3 SECDFR	1	94

VARIABLES	SN	TYPE	RELOCATION		REFS	50	88	89	DEFINED	1	55	74
			ARRAY	F.P.								
0 A	REAL	ARRAY	F.P.	78	82							
0 B	REAL	ARRAY	F.P.	REFS	50	85	88	DEFINED	1	56	61	
				65	69	75	79	83				
0 BETA	REAL	ARRAY	F.P.	REFS	50	86	88	89	93			
				1	85							
0 C	REAL	ARRAY	F.P.	REFS	50	88	93	DEFINED	1	57	62	
				66	70							
0 D	REAL	ARRAY	F.P.	REFS	50	86	89	DEFINED	1	58	63	
				67	71	76	80	84				
0 GAMMA	REAL	ARRAY	F.P.	REFS	50	89	90	93	DEFINED	1	86	
				84								
0 H	REAL	ARRAY	F.P.	REFS	50	2*55	3*56	3*53	69	70	71	
				82	83	84	DEFINED	1	53			
201 J	INTEGER			REFS	3*53	3*55	4*56	57	8*58	5*68	5*89	
				92	DEFINED	52	54	67	91			
200 K	INTEGER			REFS	52	54	82	83	2*84	91		
				DEFINED	51							
0 L1	INTEGER		F.P.	REFS	59	60	DEFINED	1				
0 L2	INTEGER		F.P.	REFS	72	73	DEFINED	1				

SUBROUTINE SECOLK			73/74	OPT=1		FTN 4.8+552	85/05/02. 13.03.28	PAGE	4
VARIABLES	SN	TYPE	RELOCATION		REFS	5*93	DEFINED	92	
202	M	INTEGER	F.P.		REFS	10*50	51	74	76
0	N	INTEGER			REFS	80	82	83	87
					REFS	1			92
0	P	REAL	ARRAY	F.P.	REFS	50	93	DEFINED	1
0	P0	REAL		F.P.	REFS	63	71	DEFINED	1
0	P3	REAL		F.P.	REFS	76	84	DEFINED	1
0	X	REAL	ARRAY	F.P.	REFS	50	2*53	DEFINED	1
0	XX1	REAL		F.P.	REFS	66	DEFINED	1	
0	XX2	REAL		F.P.	REFS	78	DEFINED	1	
0	Y	REAL	ARRAY	F.P.	REFS	50	4*58	2*71	2*84
					REFS		DEFINED		1
STATEMENT LABELS			DEF LINE	REFERENCES					
0	1		53	52					
0	2		58	54					
0	6		89	87					
0	7		93	91					
53	10		65	60					
103	11		78	73					
60	20		69	59					
113	21		82	72					
70	30		72	64	68				
127	40		85	77	81				
LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES				
15	1	J	52 53	38	INSTACK				
30	2	J	54 58	128	OPT				
142	6	J	87 89	68	INSTACK				
6	165	J	91 93	58	INSTACK				
88									
STATISTICS									
PROGRAM LENGTH			2128	138					
52000B CM USED									

APPENDIX 6

This appendix contains the output generated by PROGRAM STEPSPL for example 2.

SINPUT

TS = 0.0,
NSEQ = 1,
IEQN = 3, -576460752303354399, -576460752303354398,
NPTS = 240,
IPLOT = 1,
IFLAG = 1,
SAREA = .1374E+02,
BSPAN = .998E+01,
CBAR = .14E+01,
M = .1055E+04,
RHO = .10272E+01,
G = .981E+01,
IX = .2357E+04,
IY = .3051E+04,
IZ = .4833E+04,
100 IXZ = .177E+03,
DELET = 0.0,
ALPHT = 0.0,
BETT = 0.0,
DELAT = 0.0,
DELRD = 0.0,
QT = 0.0,
PT = 0.0,
RT = 0.0,

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KNOT NUMBER	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
KNOT VALUE (DEG)	2	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17

TRIM VALUES
ALPHAT

BEET

AILT

DELETE

DELET

.26247E+00 0.
0.
0.
0.

SEND

FILEOP = 0,

ACELOP = 1,

LATOP = 0,

ITRIMOP = 0,

FCRT = .5E+01,

TIME	V	ALPHA	Q	DELETE
1000E+00	3500E+02	2629E+00	-4934E-02	0.
1500E+00	3500E+02	2632E+00	-1711E-01	0.
2000E+00	3500E+02	2639E+00	-1881E-03	0.
2500E+00	3500E+02	2632E+00	-1775E-01	0.
3000E+00	3500E+02	2666E+00	-1000E+00	-5000E-01
3500E+00	3500E+02	2706E+00	-8090E-01	-3127E-01
4000E+00	3500E+02	2772E+00	-1338E+00	-1400E+00
4500E+00	3500E+02	2829E+00	-1873E+00	-1400E+00
5000E+00	3500E+02	2842E+00	-2896E+00	-1400E+00
5500E+00	3500E+02	3091E+00	-3029E+00	-1400E+00
6000E+00	3500E+02	3229E+00	-3255E+00	-1400E+00
6500E+00	3500E+02	3376E+00	-3476E+00	-1400E+00
7000E+00	3500E+02	3524E+00	-3550E+00	-1000E+00
7500E+00	3500E+02	3664E+00	-3693E+00	-5000E-01
8000E+00	3500E+02	3783E+00	-2925E+00	0.
8500E+00	3500E+02	3878E+00	-1382E+00	1000E+00
9000E+00	3500E+02	3927E+00	-3994E-01	1400E+00
9500E+00	3500E+02	3927E+00	-3994E-01	1400E+00
10000E+01	3500E+02	3887E+00	-7266E-01	1400E+00
10500E+01	3500E+02	3806E+00	-1619E+00	1400E+00
11000E+01	3500E+02	3687E+00	-2525E+00	1400E+00
11500E+01	3500E+02	3531E+00	-3325E+00	1400E+00
12000E+01	3500E+02	3334E+00	-4100E+00	1400E+00
12500E+01	3500E+02	3130E+00	-4736E+00	1400E+00
13000E+01	3500E+02	2887E+00	-5321E+00	1000E+00
13500E+01	3500E+02	2635E+00	-5787E+00	5000E-01
14000E+01	3500E+02	2383E+00	-5894E+00	0.
14500E+01	3500E+02	2131E+00	-5855E+00	0.
15000E+01	3500E+02	1891E+00	-5634E+00	0.
15500E+01	3500E+02	1672E+00	-5479E+00	0.
16000E+01	3500E+02	1482E+00	-5050E+00	0.
16500E+01	3500E+02	1230E+00	-4671E+00	0.
17000E+01	3500E+02	1125E+00	-4244E+00	0.
17500E+01	3500E+02	1073E+00	-3900E+00	0.
18000E+01	3500E+02	9841E-01	-3574E+00	0.
18500E+01	3500E+02	9150E-01	-3217E+00	0.
19000E+01	3500E+02	8642E-01	-2892E+00	0.
19500E+01	3500E+02	8300E-01	-2653E+00	0.
20000E+01	3500E+02	8046E-01	-2284E+00	0.
20500E+01	3500E+02	8046E-01	-2058E+00	0.
21000E+01	3500E+02	8107E-01	-1812E+00	0.
21500E+01	3500E+02	8107E-01	-1585E+00	0.
22000E+01	3500E+02	8527E-01	-1347E+00	0.
22500E+01	3500E+02	9860E-01	-1095E+00	0.

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$2300E+01$	$3500E+02$	$9263E-01$	$-9381E-01$	$2500E+01$	$3500E+02$	$9723E-01$	$-7583E-01$	$2400E+01$	$3500E+02$	$1023E+00$	$-3757E-01$	$2500E+01$	$3500E+02$	$1136E+00$	$-2778E-01$	$2500E+01$	$3500E+02$	$1194E+00$	$-1136E-01$	$2700E+01$	$3500E+02$	$1386E+00$	$-1393E-01$	$2700E+01$	$3500E+02$	$1386E+00$	$-6836E-02$	$2600E+01$	$3500E+02$	$1259E+00$	$-9996E-04$	$2500E+01$	$3500E+02$	$1194E+00$	$-1136E-01$	$2800E+01$	$3500E+02$	$1514E+00$	$-3023E-01$	$2850E+01$	$3500E+02$	$1578E+00$	$-3542E-01$	$2900E+01$	$3500E+02$	$1640E+00$	$-4170E-01$	$2950E+01$	$3500E+02$	$1578E+00$	$-521AE-01$	$3100E+01$	$3500E+02$	$1878E+00$	$-6847E-01$	$3150E+01$	$3500E+02$	$1935E+00$	$-7318E-01$	$3200E+01$	$3500E+02$	$1991E+00$	$-7366E-01$	$3250E+01$	$3500E+02$	$2045E+00$	$-7445E-01$	$3300E+01$	$3500E+02$	$2098E+00$	$-8244E-01$	$3350E+01$	$3500E+02$	$2142E+00$	$-9937E-01$	$3400E+01$	$3500E+02$	$2174E+00$	$-9532E-01$	$3450E+01$	$3500E+02$	$2251E+00$	$-9461E-01$	$3500E+01$	$3500E+02$	$2294E+00$	$-9937E-01$	$3550E+01$	$3500E+02$	$2339E+00$	$-9095E-01$	$3600E+01$	$3500E+02$	$2384E+00$	$-8983E-01$	$3650E+01$	$3500E+02$	$2393E+00$	$-8248E-01$	$3700E+01$	$3500E+02$	$2429E+00$	$-9937E-01$	$3750E+01$	$3500E+02$	$2517E+00$	$-9461E-01$	$3800E+01$	$3500E+02$	$2559E+00$	$-9302E-01$	$3850E+01$	$3500E+02$	$2600E+00$	$-9058E-01$	$3900E+01$	$3500E+02$	$2639E+00$	$-8794E-01$	$3950E+01$	$3500E+02$	$2679E+00$	$-8279E-01$	$4100E+01$	$3500E+02$	$2740E+00$	$-7613E-01$	$4150E+01$	$3500E+02$	$2776E+00$	$-7279E-01$	$4200E+01$	$3500E+02$	$2809E+00$	$-7059E-01$	$4250E+01$	$3500E+02$	$2840E+00$	$-6857E-01$	$4300E+01$	$3500E+02$	$2874E+00$	$-6532E-01$	$4350E+01$	$3500E+02$	$2904E+00$	$-6297E-01$	$4400E+01$	$3500E+02$	$2936E+00$	$-5996E-01$	$4450E+01$	$3500E+02$	$2967E+00$	$-5637E-01$	$4500E+01$	$3500E+02$	$2994E+00$	$-5297E-01$	$4550E+01$	$3500E+02$	$3023E+00$	$-4944E-01$	$4600E+01$	$3500E+02$	$3050E+00$	$-4545E-01$	$4650E+01$	$3500E+02$	$3076E+00$	$-4144E-01$	$4700E+01$	$3500E+02$	$3103E+00$	$-3759E-01$
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.7200E+01	.3500E+02	.2371E+00	.5063E-01	0.
.7250E+01	.3500E+02	.2394E+00	.4900E-01	0.
.7300E+01	.3500E+02	.2417E+00	.5066E-01	0.
.7350E+01	.3500E+02	.2439E+00	.4456E-01	0.
.7400E+01	.3500E+02	.2462E+00	.4336E-01	0.
.7450E+01	.3500E+02	.2484E+00	.4852E-01	0.
.7500E+01	.3500E+02	.2505E+00	.4354E-01	0.
.7550E+01	.3500E+02	.2525E+00	.4263E-01	0.
.7600E+01	.3500E+02	.2544E+00	.4184E-01	0.
.7650E+01	.3500E+02	.2562E+00	.4512E-01	0.
.7700E+01	.3500E+02	.2578E+00	.4072E-01	0.
.7750E+01	.3500E+02	.2593E+00	.3774E-01	0.
.7800E+01	.3500E+02	.2606E+00	.3791E-01	0.
.7850E+01	.3500E+02	.2618E+00	.2964E-01	0.
.7900E+01	.3500E+02	.2627E+00	.2272E-01	0.
.7950E+01	.3500E+02	.2635E+00	.1746E-01	0.
.8000E+01	.3500E+02	.2641E+00	.1568E-01	0.
.8050E+01	.3500E+02	.2645E+00	.2438E-01	0.
.8100E+01	.3500E+02	.2646E+00	.8031E-02	0.
.8150E+01	.3500E+02	.2646E+00	.6162E-02	0.
.8200E+01	.3500E+02	.2643E+00	.3082E-02	0.
.8250E+01	.3500E+02	.2638E+00	-.9692E-03	0.
.8300E+01	.3500E+02	.2632E+00	-.1275E-01	0.
.8350E+01	.3500E+02	.2623E+00	-.1454E-01	0.
.8400E+01	.3500E+02	.2613E+00	-.1714E-01	0.
.8450E+01	.3500E+02	.2600E+00	-.2094E-01	0.
.8500E+01	.3500E+02	.2587E+00	-.2915E-01	0.
.8550E+01	.3500E+02	.2571E+00	-.3490E-01	0.
.8600E+01	.3500E+02	.2554E+00	-.3315E-01	0.
.8650E+01	.3500E+02	.2536E+00	-.3291E-01	0.
.8700E+01	.3500E+02	.2517E+00	-.3785E-01	0.
.8750E+01	.3500E+02	.2497E+00	-.3979E-01	0.
.8800E+01	.3500E+02	.2476E+00	-.4808E-01	0.
.8850E+01	.3500E+02	.2454E+00	-.5018E-01	0.
.8900E+01	.3500E+02	.2432E+00	-.4747E-01	0.
.8950E+01	.3500E+02	.2410E+00	-.4659E-01	0.
.9000E+01	.3500E+02	.2388E+00	-.5029E-01	0.
.9050E+01	.3500E+02	.2366E+00	-.5204E-01	0.
.9100E+01	.3500E+02	.2344E+00	-.4532E-01	0.
.9150E+01	.3500E+02	.2323E+00	-.4815E-01	0.
.9200E+01	.3500E+02	.2303E+00	-.4862E-01	0.
.9250E+01	.3500E+02	.2284E+00	-.4763E-01	0.
.9300E+01	.3500E+02	.2265E+00	-.4677E-01	0.
.9350E+01	.3500E+02	.2248E+00	-.3728E-01	0.
.9400E+01	.3500E+02	.2234E+00	-.4370E-01	0.
.9450E+01	.3500E+02	.2222E+00	-.3741E-01	0.
.9500E+01	.3500E+02	.2211E+00	-.3352E-01	0.
.9550E+01	.3500E+02	.2204E+00	-.2693E-01	0.
.9600E+01	.3500E+02	.2198E+00	-.1753E-01	0.

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* 96500E+01 * 3500E+02 * 21494E+00 * -1332E-01 * 0.

* 97500E+01 * 3500E+02 * 21492E+00 * -12539E-01 * 0.

* 98500E+01 * 3500E+02 * 21492E+00 * -94536E-02 * 0.

* 99500E+01 * 3500E+02 * 21492E+00 * -7934E-03 * 0.

* 100500E+02 * 3500E+02 * 22124E+00 * 3657E-02 * 0.

* 10100E+02 * 3500E+02 * 22323E+00 * 2254E+00 * 0.

* 10150E+02 * 3500E+02 * 22323E+00 * 1483E-01 * 0.

* 10400E+02 * 3500E+02 * 23030E+00 * 3030E-01 * 0.

* 10550E+02 * 3500E+02 * 2323E+00 * 3328E-01 * 0.

* 10650E+02 * 3500E+02 * 2393E+00 * 3523E-01 * 0.

* 10700E+02 * 3500E+02 * 24111E+00 * 38339E-01 * 0.

* 10750E+02 * 3500E+02 * 24229E+00 * 4165E-01 * 0.

* 10850E+02 * 3500E+02 * 2464E+00 * 3969E-01 * 0.

* 10900E+02 * 3500E+02 * 24812E+00 * 3435E-01 * 0.

* 11100E+02 * 3500E+02 * 2534E+00 * 3078E-01 * 0.

* 11150E+02 * 3500E+02 * 2556E+00 * 3345E-01 * 0.

* 11200E+02 * 3500E+02 * 2575E+00 * 2878E-01 * 0.

* 11250E+02 * 3500E+02 * 2593E+00 * 2466E-01 * 0.

* 11300E+02 * 3500E+02 * 2593E+00 * 2475E-01 * 0.

* 11350E+02 * 3500E+02 * 2593E+00 * 2148E-01 * 0.

* 11400E+02 * 3500E+02 * 2595E+00 * 1938E-01 * 0.

* 11450E+02 * 3500E+02 * 2595E+00 * 11147E-01 * 0.

* 11500E+02 * 3500E+02 * 2598E+00 * 6646E-02 * 0.

* 11550E+02 * 3500E+02 * 2583E+00 * 6463E-02 * 0.

* 11600E+02 * 3500E+02 * 2590E+00 * 1069E-02 * 0.

* 11650E+02 * 3500E+02 * 2595E+00 * 1095E-02 * 0.

* 11700E+02 * 3500E+02 * 2583E+00 * 1069E-02 * 0.

* 11750E+02 * 3500E+02 * 2590E+00 * 1069E-02 * 0.

* 11800E+02 * 3500E+02 * 2575E+00 * 12539E-01 * 0.

* 11850E+02 * 3500E+02 * 2565E+00 * 85453E-02 * 0.

* 11900E+02 * 3500E+02 * 2543E+00 * 94536E-02 * 0.

* 11950E+02 * 3500E+02 * 2543E+00 * 9734E-03 * 0.

* 12000E+02 * 3500E+02 * 2506E+00 * 2980E-02 * 0.

* 12050E+02 * 3500E+02 * 2214E+00 * 3657E-02 * 0.

* 12100E+02 * 3500E+02 * 2232E+00 * 2254E+00 * 0.

* 12150E+02 * 3500E+02 * 2232E+00 * 1483E-01 * 0.

* 12200E+02 * 3500E+02 * 2575E+00 * 3523E-01 * 0.

* 12250E+02 * 3500E+02 * 2556E+00 * 3345E-01 * 0.

* 12300E+02 * 3500E+02 * 2583E+00 * 2878E-01 * 0.

* 12350E+02 * 3500E+02 * 2593E+00 * 2466E-01 * 0.

* 12400E+02 * 3500E+02 * 2595E+00 * 1938E-01 * 0.

* 12450E+02 * 3500E+02 * 2598E+00 * 11147E-01 * 0.

* 12500E+02 * 3500E+02 * 2600E+00 * 6646E-02 * 0.

* 12550E+02 * 3500E+02 * 2600E+00 * 6463E-02 * 0.

* 12600E+02 * 3500E+02 * 2600E+00 * 4867E-02 * 0.

* 12650E+02 * 3500E+02 * 2594E+00 * 1095E-02 * 0.

* 12700E+02 * 3500E+02 * 2590E+00 * 1069E-02 * 0.

* 12750E+02 * 3500E+02 * 2583E+00 * 1069E-02 * 0.

* 12800E+02 * 3500E+02 * 2575E+00 * 12539E-01 * 0.

* 12850E+02 * 3500E+02 * 2565E+00 * 85453E-02 * 0.

* 12900E+02 * 3500E+02 * 2543E+00 * 94536E-02 * 0.

* 12950E+02 * 3500E+02 * 2543E+00 * 9734E-03 * 0.

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QUALITY

SIGMA SQ OF RESIDUALS IS .16858E+00

601

ORIGINAL PAGE IS
OF POOR
QUALITY

110

ORIGINAL PAGE IS
OF POOR
QUALITY

RESIDUAL MEAN IS .33002E-13
SIGMA SQ OF RESIDUALS IS .10908E+00

ORIGINAL PAGE IS
OF POOR QUALITY

PARTIAL F VALUE FOR VARIABLE 3 IS .103E+04
PARTIAL F VALUE FOR VARIABLE 13 IS .607E+01
PARTIAL F VALUE FOR VARIABLE 15 IS .697E+01
PARTIAL F VALUE FOR VARIABLE 20 IS .250E+02
PARTIAL F VALUE FOR VARIABLE 21 IS .195E+02
PARTIAL F VALUE FOR VARIABLE 28 IS .244E+02
PARTIAL F VALUE FOR VARIABLE 29 IS .103E+02
PARTIAL F VALUE FOR VARIABLE 31 IS .785E+01

PERCENT VARIATION EXPLAINED IS 96.76
STD. DEVIATION OF RESIDUALS IS .204E-01

TOTAL F VALUE IS .68020E+03

NEW PARAMETER ESTIMATES AND STD. DEV. ARE

-.384E+00	-.158E+02	-.216E+010.	0.	0.	0.	0.	0.	0.	0.	.530E+010.	.574E+0
0.	0.	0.	-.561E+00	.665E+010.	0.	0.	0.	0.	0.	0.	0.
0.	0.	-.939E+00	-.698E+010.	-.596E+010.	0.	0.	0.	0.	0.	0.	.101E+0
.227E-01	.453E+00	.358E-010.	0.	0.	0.	0.	0.	0.	0.	.525E+000.	.547E+0
0.	0.	0.	0.	.388E-01	.623E+000.	0.	0.	0.	0.	0.	0.
0.	0.	.795E-01	.894E+000.	.102E+010.	0.	0.	0.	0.	0.	0.	0.

RESIDUAL MEAN IS .30831E-13

SIGMA SQ OF RESIDUALS IS .94620E-01

MAXIMUM F VALUE IS .396E+01 FOR VARIABLE 30

APPENDIX 7

This appendix presents three optional forms for the model structure determination basis in SUBROUTINE DATASET. One longitudinal option and two lateral options are given.

The longitudinal option given here is an example of the second-order spline which gives a smoother representation than the first or zeroth-order spline. The example here provides for a second-order spline in C_{zq} . When this basis is used for the C_m equation, it provides a second-order spline for C_{mq} .

LONGITUDINAL EQUATIONS: SECOND OPTION

an example for C_z

$$C_z = C_z(\alpha) \beta = q = \delta_e = 0 + C_{zq}(\alpha) \bar{qc}/2V + C_{z\delta e}(\alpha) \delta_e$$

where

$$C_z(\alpha) = C_z(0) + C_{z\alpha} + \sum_{i=1}^{17} D_{\alpha i} (\alpha - \alpha_i) +$$

$$C_{zq}(\alpha) = C_{zq} + C_{zq\alpha} \alpha + C_{zq\alpha^2} \alpha^2$$

$$+ \sum_{i=1}^{17} D_{q\alpha^2 i} (\alpha - \alpha_i)^2 +$$

$$C_{z\delta e}(\alpha) = C_{z\delta e} + \sum_{i=1}^3 D_{\delta e i} (\alpha - \alpha_i)^0 +$$

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C LONGITUDINAL EQUATIONS: SECOND OPTION

```
DO 906 I=1,NPTS
X(1,I)=ALPH(I)
X(2,I)=C/(2*VEL(I))*Q(I)
X(3,I)=DELE(I)
DO 907 III=4,39
907 X(III,I)=0.
IF(ALPH(I).GE.XKNOT(1)) X(4,I)=ALPH(I)-XKNOT(1)
X(5,I)=X(2,I)*ALPH(I)
IF(ALPH(I).GE.XKNOT(2)) X(6,I)=ALPH(I)-XKNOT(2)
X(7,I)=X(2,I)*ALPH(I)**2
IF(ALPH(I).GE.XKNOT(3)) X(8,I)=ALPH(I)-XKNOT(3)
IF(ALPH(I).GE.XKNOT(1)) X(9,I)=(ALPH(I)-XKNOT(1))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(4)) X(10,I)=ALPH(I)-XKNOT(4)
IF(ALPH(I).GE.XKNOT(3)) X(11,I)=(ALPH(I)-XKNOT(3))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(5)) X(12,I)=ALPH(I)-XKNOT(5)
IF(ALPH(I).GE.XKNOT(4)) X(13,I)=(ALPH(I)-XKNOT(4))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(6)) X(14,I)=ALPH(I)-XKNOT(6)
IF(ALPH(I).GE.XKNOT(5)) X(15,I)=(ALPH(I)-XKNOT(5))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(7)) X(16,I)=ALPH(I)-XKNOT(7)
IF(ALPH(I).GE.XKNOT(6)) X(17,I)=(ALPH(I)-XKNOT(6))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(8)) X(18,I)=ALPH(I)-XKNOT(8)
IF(ALPH(I).GE.XKNOT(7)) X(19,I)=(ALPH(I)-XKNOT(7))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(9)) X(20,I)=ALPH(I)-XKNOT(9)
IF(ALPH(I).GE.XKNOT(8)) X(21,I)=(ALPH(I)-XKNOT(8))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(10)) X(22,I)=ALPH(I)-XKNOT(10)
IF(ALPH(I).GE.XKNOT(9)) X(23,I)=(ALPH(I)-XKNOT(9))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(11)) X(24,I)=ALPH(I)-XKNOT(11)
IF(ALPH(I).GE.XKNOT(10)) X(25,I)=(ALPH(I)-XKNOT(10))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(12)) X(26,I)=ALPH(I)-XKNOT(12)
IF(ALPH(I).GE.XKNOT(11)) X(27,I)=(ALPH(I)-XKNOT(11))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(13)) X(28,I)=ALPH(I)-XKNOT(13)
IF(ALPH(I).GE.XKNOT(12)) X(29,I)=(ALPH(I)-XKNOT(12))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(14)) X(30,I)=ALPH(I)-XKNOT(14)
IF(ALPH(I).GE.XKNOT(13)) X(31,I)=(ALPH(I)-XKNOT(13))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(15)) X(32,I)=ALPH(I)-XKNOT(15)
IF(ALPH(I).GE.XKNOT(14)) X(33,I)=(ALPH(I)-XKNOT(14))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(16)) X(34,I)=ALPH(I)-XKNOT(16)
IF(ALPH(I).GE.XKNOT(15)) X(35,I)=(ALPH(I)-XKNOT(15))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(17)) X(36,I)=ALPH(I)-XKNOT(17)
IF(ALPH(I).GE.XKNOT(17)) X(37,I)=(ALPH(I)-XKNOT(17))**2*X(2,I)
IF(ALPH(I).GE.XKNOT(7)) X(38,I)=X(3,I)
IF(ALPH(I).GE.XKNOT(13)) X(39,I)=X(3,I)
906 CONTINUE
GO TO 800
```

Next, we give an example of a first option for the lateral equations. This simple version, incorporating zeroth-order splines in α and first-order splines in β should be used for the first approximations to the lateral coefficients.

LATERAL EQUATIONS: FIRST OPTION

An example for C_n

$$C_n = C_n(\alpha, \beta)_{p=0} + C_n(\alpha)_{p} \frac{pb}{2V} + C_n(\alpha)_{r} \frac{rb}{2V}$$

$$\delta_a = \delta_r = 0$$

$$+ C_{n\delta_a}(\alpha)_{a} + C_{n\delta_r}(\alpha)_{r}$$

where

$$C_n(\alpha, \beta) = C_0 + C_1 \beta + \sum_{i=1}^9 B_i (\beta - \beta_i)_+ +$$

$$+ C_{n\alpha}(\alpha) + \sum_{i=1}^6 C_{n\beta_i}(\alpha - \alpha_i)_0$$

$$C_{np}(\alpha) = C_{np} + \sum_{i=1}^6 C_{n\beta_i}(\alpha - \alpha_i)_0$$

$$C_{nr}(\alpha) = C_{nr} + \sum_{i=1}^6 C_{n\alpha_i}(\alpha - \alpha_i)_0$$

$$C_{n\delta_a}(\alpha) = C_{n\delta_a} + \sum_{i=1}^6 C_{n\delta a_i}(\alpha - \alpha_i)_0$$

$$C_{n\delta_r}(\alpha) = C_{n\delta_r} + \sum_{i=1}^6 C_{n\delta r_i}(\alpha - \alpha_i)_0$$

and

$$(\beta - \beta_i)_+ = \begin{cases} 0 & \text{for } |\beta| < \beta_i \\ \beta - \beta_i & \text{for } \beta \geq \beta_i \\ \beta + \beta_i & \text{for } \beta \leq -\beta_i \end{cases}$$

LATERKAL EQUATIONS; FIRST OPTION

DN 807 I=1,NPTS

X(2,I)*P(I)*R/(2*VFL(I))

X(1,I)-BETA(I)

NO 899 III-6,39

IE(ALPH(I),GE,XKNOT(1))

IE(ALPH(I),GE,XKNOT(2))

IE(ALPH(I),GE,XKNOT(3))

IE(ALPH(I),GE,XKNOT(4))

IE(ALPH(I),GE,XKNOT(5))

IE(ALPH(I),GE,XKNOT(6))

IE(ALPH(I),GE,XKNOT(7))

IE(ALPH(I),GE,XKNOT(8))

IE(ALPH(I),GE,XKNOT(9))

IE(ALPH(I),GE,XKNOT(10))

IE(ALPH(I),GE,XKNOT(11))

IE(ALPH(I),GE,XKNOT(12))

IE(ALPH(I),GE,XKNOT(13))

IE(ALPH(I),GE,XKNOT(14))

IE(ALPH(I),GE,XKNOT(15))

IE(ALPH(I),GE,XKNOT(16))

IE(ALPH(I),GE,XKNOT(17))

IE(ALPH(I),GE,XKNOT(18))

IE(ALPH(I),GE,XKNOT(19))

IE(ALPH(I),GE,XKNOT(20))

IE(ALPH(I),GE,XKNOT(21))

IE(ALPH(I),GE,XKNOT(22))

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IE(ALPH(I),GE,XKNOT(26))

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IE(ALPH(I),GE,XKNOT(35))

IE(ALPH(I),GE,XKNOT(36))

IE(ALPH(I),GE,XKNOT(37))

IE(ALPH(I),GE,XKNOT(38))

IE(ALPH(I),GE,XKNOT(39))

IE(ALPH(I),GE,XKNOT(40))

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IE(ALPH(I),GE,XKNOT(61))

IE(ALPH(I),GE,XKNOT(62))

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IE(ALPH(I),GE,XKNOT(68))

IE(ALPH(I),GE,XKNOT(69))

IE(ALPH(I),GE,XKNOT(70))

IE(ALPH(I),GE,XKNOT(71))

IE(ALPH(I),GE,XKNOT(72))

IE(ALPH(I),GE,XKNOT(73))

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If the first option given for the lateral equations indicates a need for a two-degree spline in (α, β) , the following lateral option can be used.

LATERAL EQUATIONS: SECOND OPTION

and example for C_n

$$C_n(\alpha, \beta) = C_0 + C_1 \beta + \sum_{i=1}^4 (A_{0i} + A_{1i} \beta) (\alpha - \alpha_i)^0 + \\ + \sum_{j=6}^7 \beta_0 j (\beta - \beta_j)^0 + \sum_{i=1}^4 \sum_{j=6}^7 D_{ij} (\beta - \beta_j)^0 + (\alpha - \alpha_i)^0$$

Note: for the analysis it was assumed that $A_{0i} = 0$, $i = 1, 2, 3, 4$. This assumption was confirmed by the later analysis using partitioned data.

$$C_{n_p}(\alpha) = C_{n_p} + \sum_{i=1}^5 C_{n_{p_i}} (\alpha - \alpha_i)^0$$

$$C_{n_r}(\alpha) = C_{n_r} + \sum_{i=1}^5 C_{n_{r_i}} (\alpha - \alpha_i)^0$$

$$C_{n_{\delta a}}(\alpha) = C_{n_{\delta a}} + \sum_{i=1}^5 C_{n_{\delta a_i}} (\alpha - \alpha_i)^0$$

$$C_{n_{\delta r}}(\alpha) = C_{n_{\delta r}} + \sum_{i=1}^5 C_{n_{\delta r_i}} (\alpha - \alpha_i)^0$$

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```
* IF(BETA(1),LE,-XKN0T(7),AND,ALPH(1),GE,XKN0T(4))  
* X(39,I)-BETA(1)+XKN0T(7)  
* IF(BETA(1),LE,-XKN0T(7),AND,ALPH(1),GE,XKN0T(7))  
* X(39,I)-BETA(1)-XKN0T(7)  
* IF(BETA(1),LE,XKN0T(7),AND,ALPH(1),GE,XKN0T(4))  
* X(38,I)-BETA(1)+XKN0T(7)  
* IF(BETA(1),LE,XKN0T(6),AND,ALPH(1),GE,XKN0T(6))  
* X(38,I)-BETA(1)-XKN0T(6)  
* IF(BETA(1),LE,XKN0T(6),AND,ALPH(1),GE,XKN0T(4))  
* X(37,I)-BETA(1)+XKN0T(4)  
* IF(BETA(1),LE,-XKN0T(7),AND,ALPH(1),GE,XKN0T(7))  
* X(37,I)-BETA(1)-XKN0T(7)  
* IF(BETA(1),LE,XKN0T(6),AND,ALPH(1),GE,XKN0T(6))  
* X(36,I)-BETA(1)+XKN0T(6)  
* IF(BETA(1),LE,-XKN0T(6),AND,ALPH(1),GE,XKN0T(3))  
* X(36,I)-BETA(1)-XKN0T(3)  
* IF(BETA(1),LE,XKN0T(7),AND,ALPH(1),GE,XKN0T(7))  
* X(35,I)-BETA(1)+XKN0T(7)  
* IF(BETA(1),LE,-XKN0T(7),AND,ALPH(1),GE,XKN0T(2))  
* X(35,I)-BETA(1)-XKN0T(2)  
* IF(BETA(1),LE,XKN0T(7),AND,ALPH(1),GE,XKN0T(1))  
* X(35,I)-BETA(1)+XKN0T(1)
```

TABLE 1

α^2	$\alpha\beta^2$	α^3	β	$\beta\alpha$	$\beta\alpha^2$	β^2	α
αq	$\alpha^2\beta^2$	α^4	p	$p\alpha$	$p\alpha^2$	β^3	α^2
δ_e	$\alpha\delta_e$	α^5	r	$r\alpha$	$r\alpha^2$	β^4	α^3
δ_{re}	$\alpha\delta_{re}$	α^6	δ_a	$\delta_a\alpha$	$\delta_a\alpha^2$	β^5	
δ_r	α^7	$\delta_r\alpha$	$\delta_r\alpha^2$	$\beta^2\alpha^2$	α^8		

TABLE 2

	TRUE VALUE	ESTIMATED VALUE	ESTIMATED STANDARD ERROR
C_{m_o}	.105	.101	-----
C_{m_α}	-.400	-.384	(.023)
C_{m_q}	-15.0	-15.8	(0.4)
$C_{m_{\delta e}}$	-2.00	-2.16	(.04)
$C_{m(\Delta\alpha)}^o, 13^\circ$	-.600	-.561	(.039)
$C_{m(\Delta\alpha)}^o, 17^\circ$	0.00	-.939	(.080)
$C_{m(\Delta\alpha)}^o, 18^\circ$	-1.00	0.00	-----
$C_{m_q(\Delta\alpha)}^o, 9^\circ$	0.00	5.30	(.52)
$C_{m_q(\Delta\alpha)}^o, 10^\circ$	+10.0	5.74	(.55)
$C_{m_q(\Delta\alpha)}^o, 13^\circ$	+10.0	+6.65	(.62)
$C_{m_q(\Delta\alpha)}^o, 17^\circ$	0.00	-6.98	(.89)
$C_{m_q(\Delta\alpha)}^o, 18^\circ$	-10.0	-5.96	(1.0)

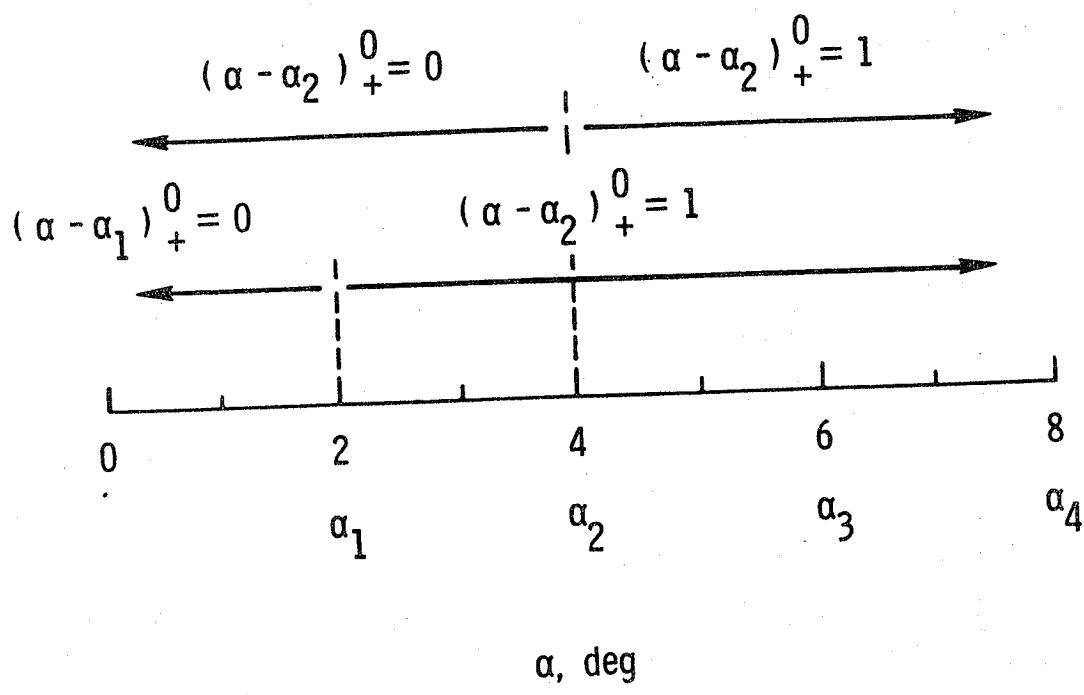
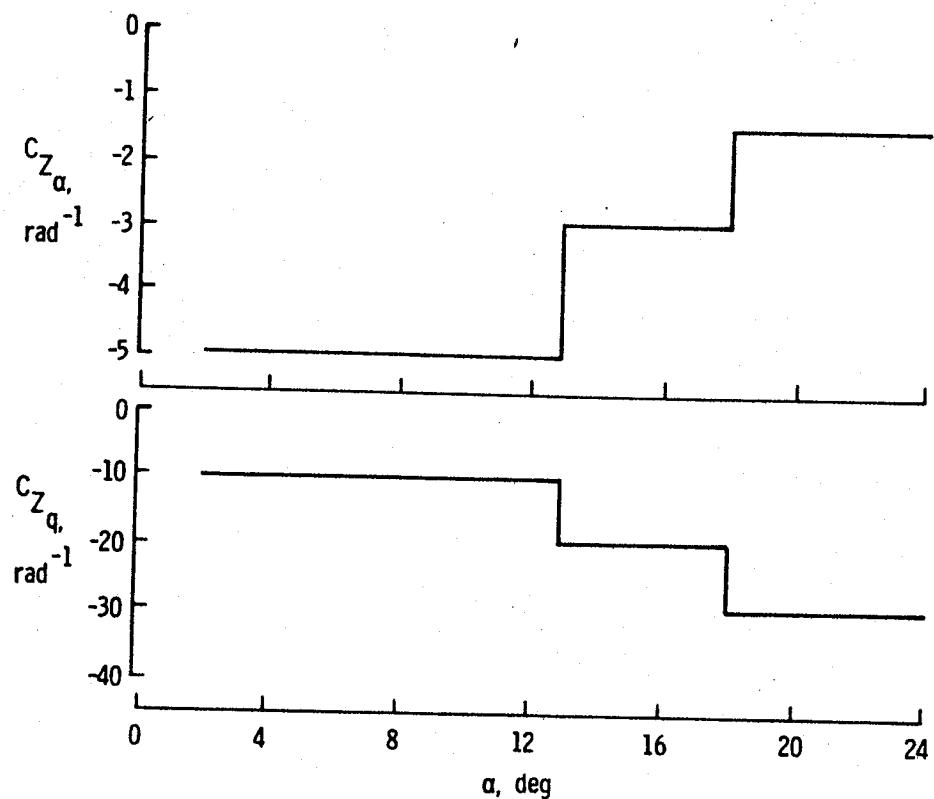
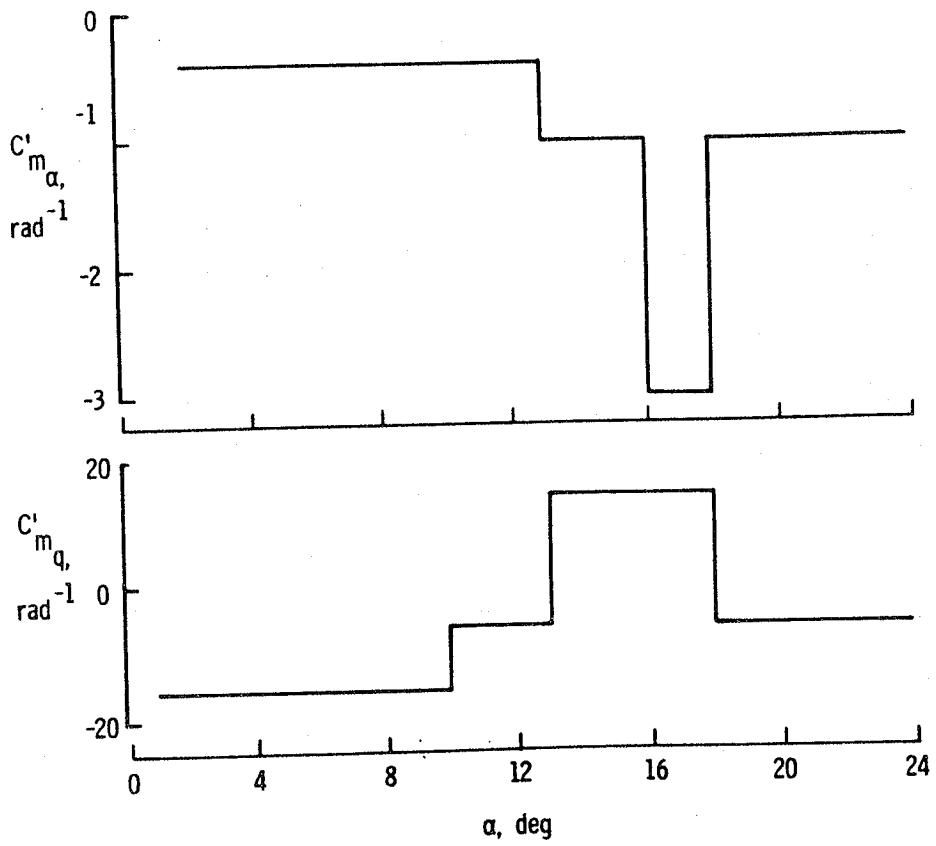


Figure 1.- Illustration of regions of support for spline "plus" function.



(a) Z-force derivatives.

Figure 2.- Aerodynamic math model for example 1.



(b) Pitching moment derivatives.

Figure 2.- Concluded.

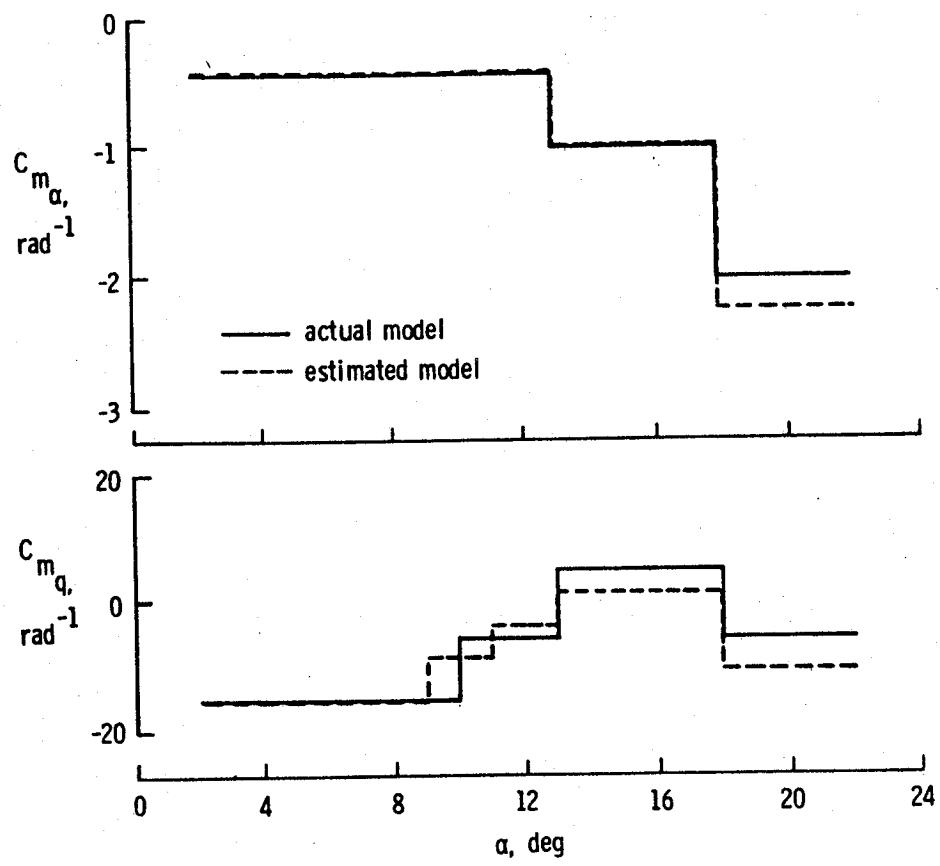
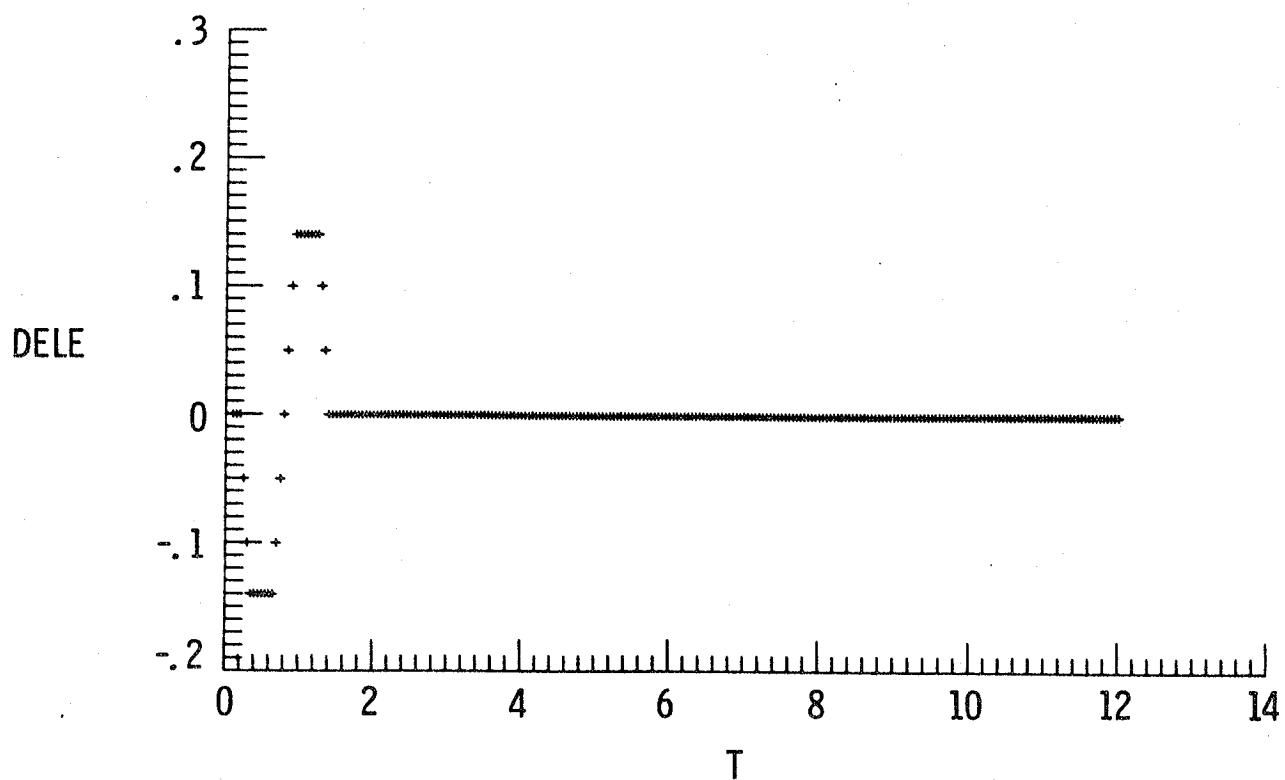
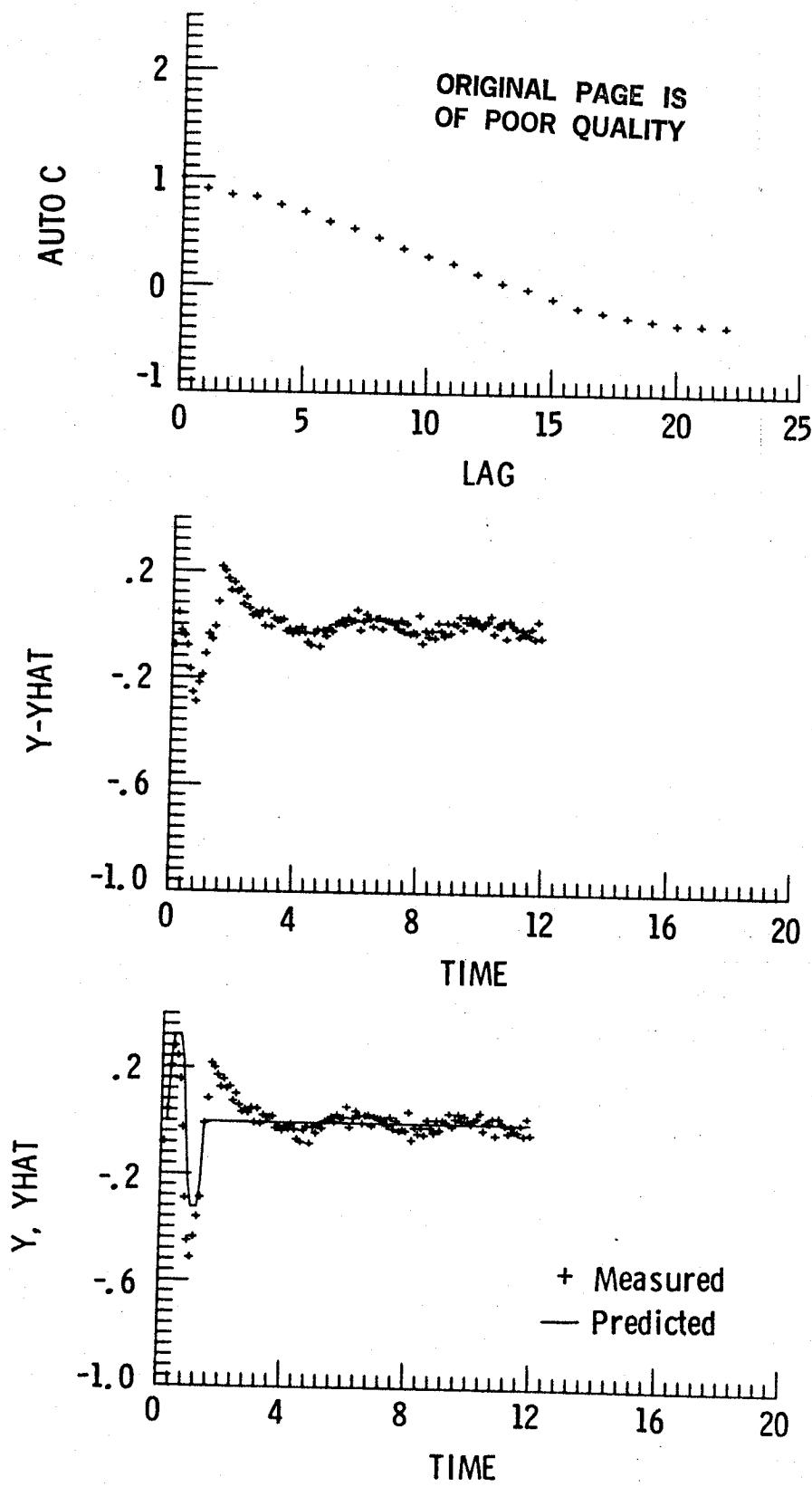


Figure 3.- Results of analysis of noisy pitching moment simulated data compared with true model.



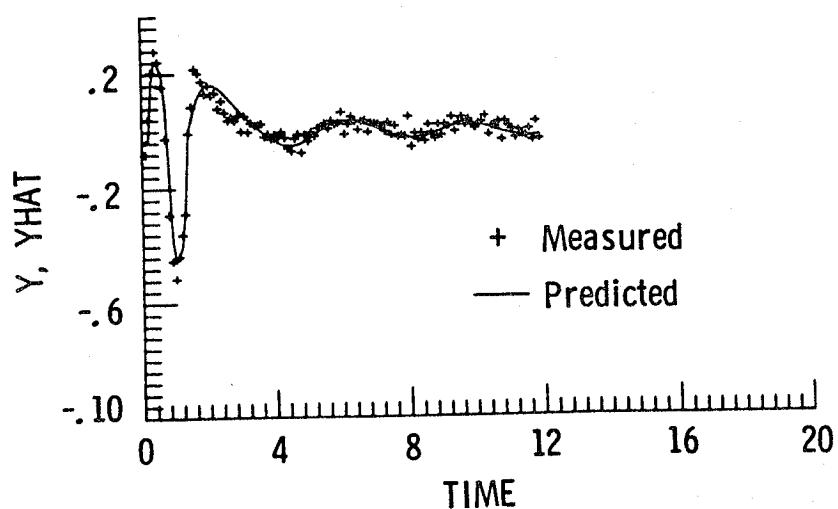
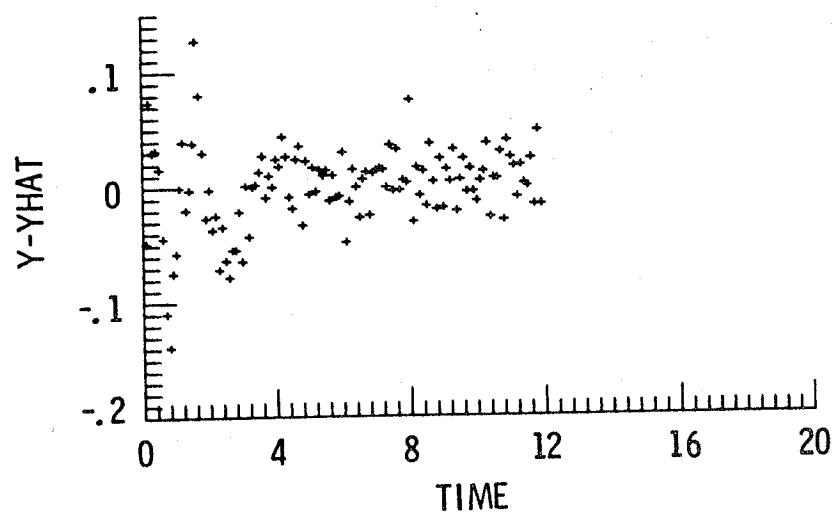
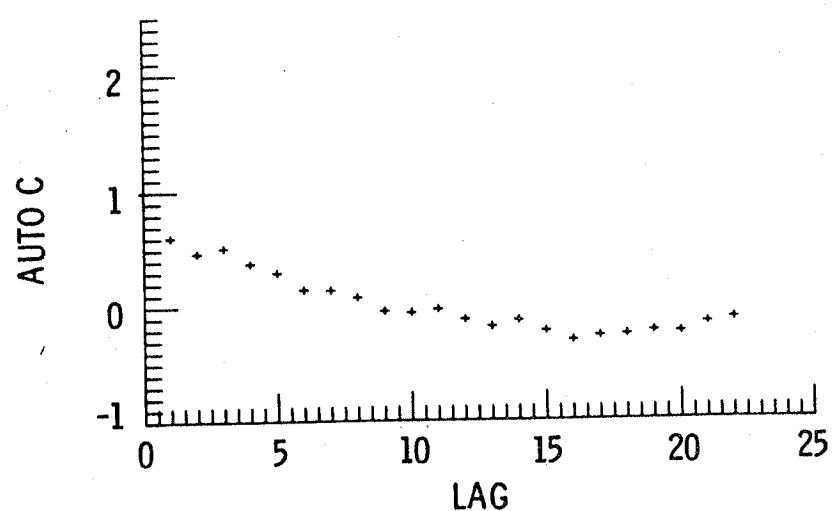
(a) Elevator input.

Figure 4.- Calcomp plotter output for STEPSPL in example 2.

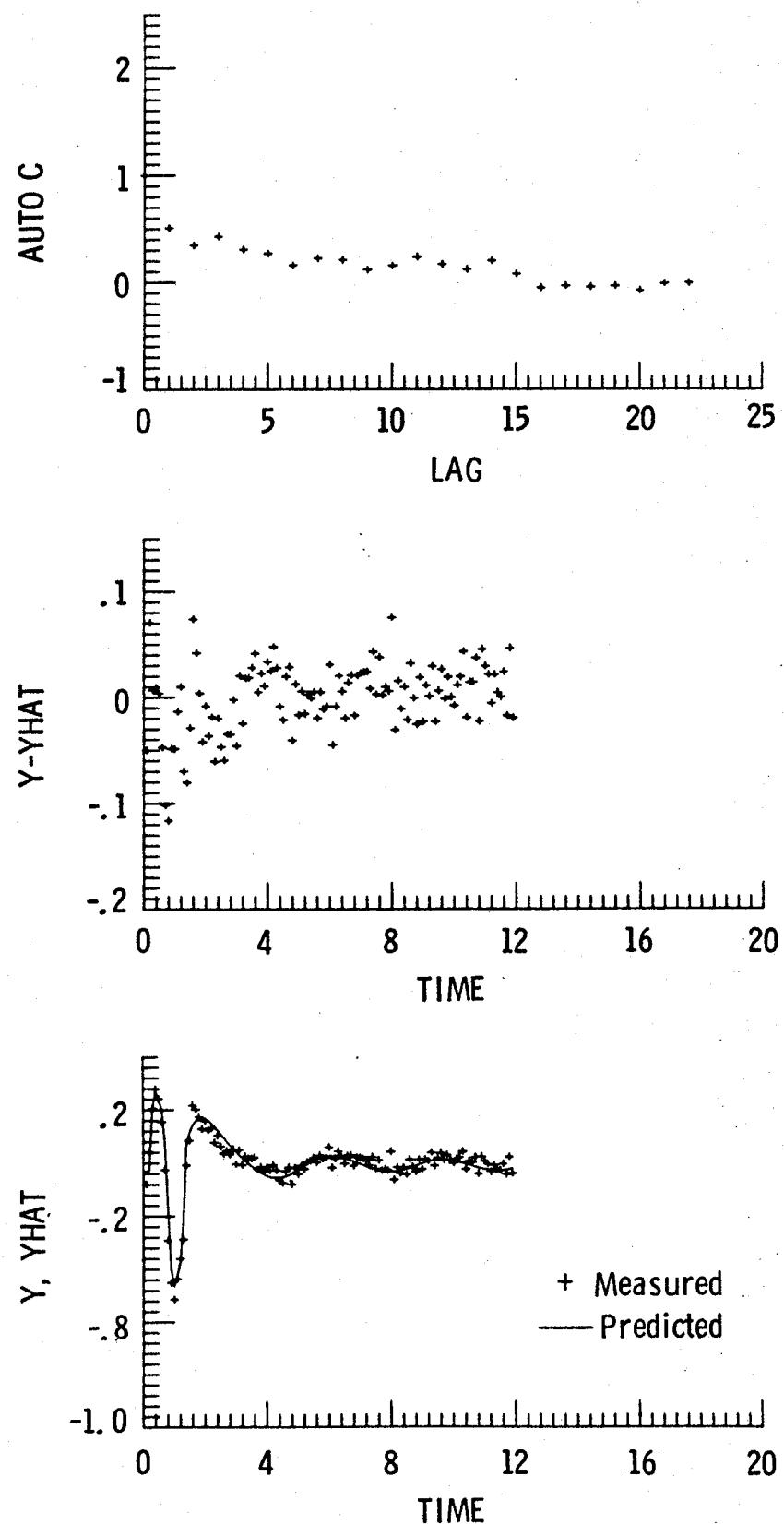


(b) Predicted and estimated pitching moment coefficients, residual sequence, and autocorrelation function for one variable model.

Figure 4.- Continued.

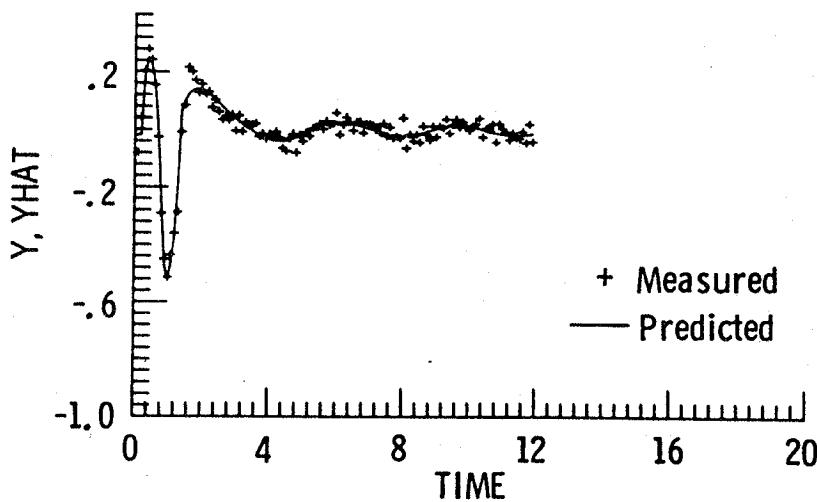
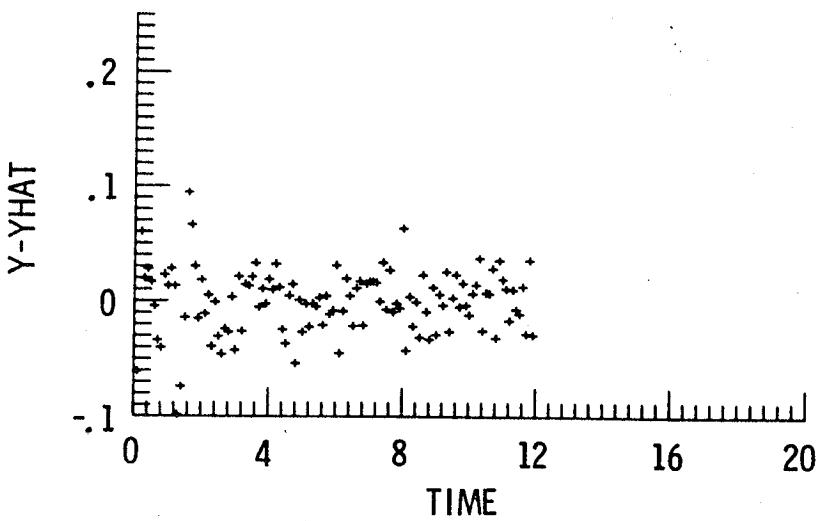
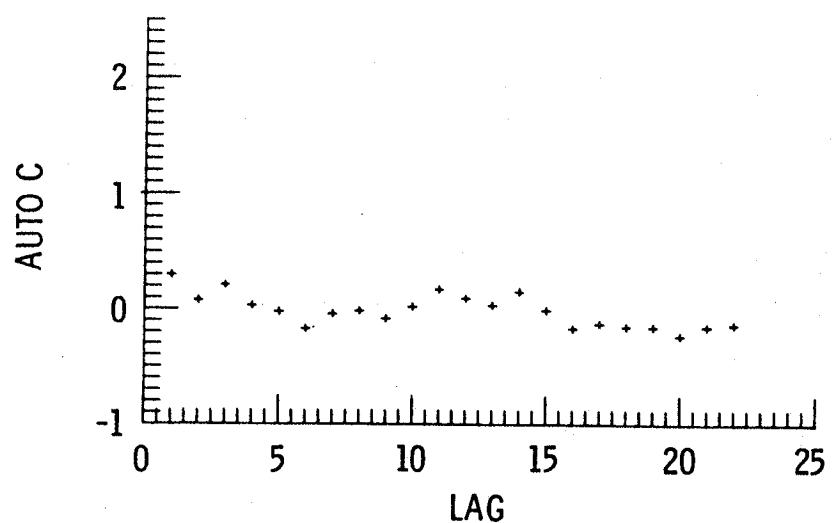


(c) Predicted and estimated pitching moment coefficients,
residual sequence, and autocorrelation function
for two variable model.

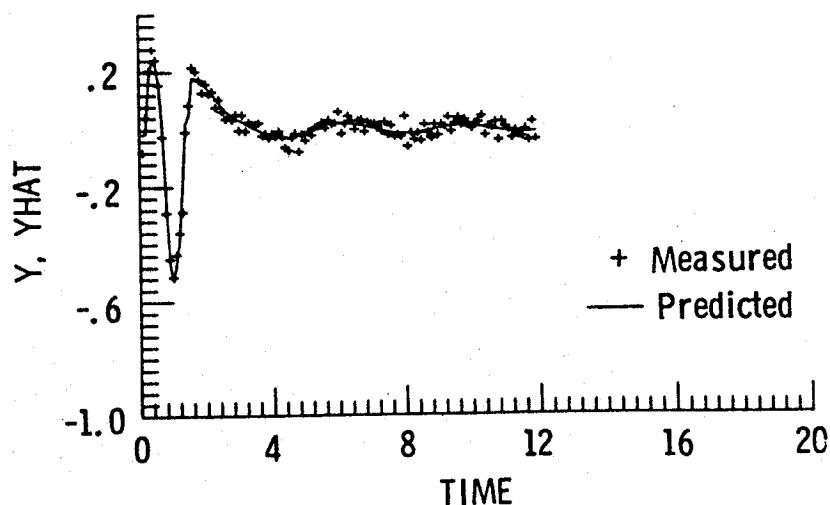
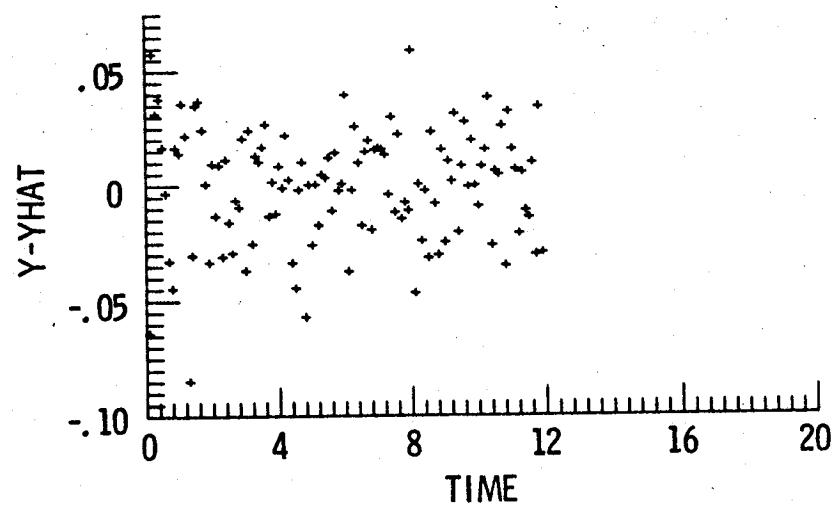
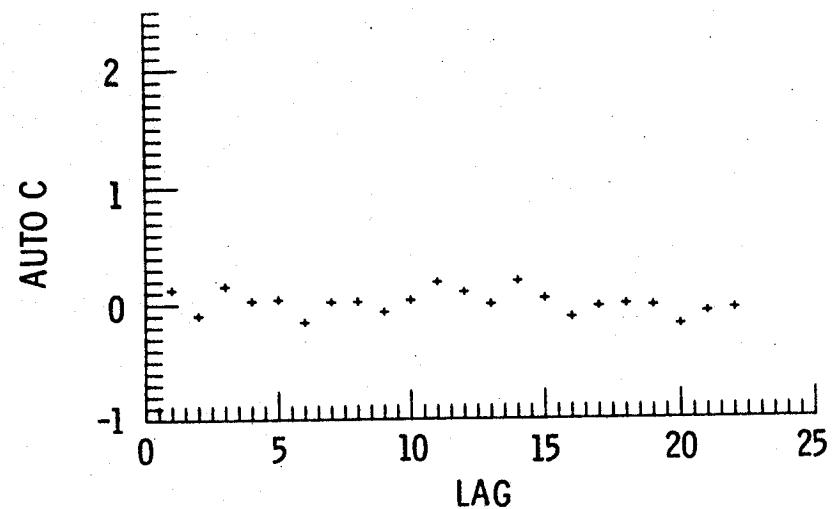


(d) Predicted and estimated pitching moment coefficients residual sequence, and autocorrelation function for three variable model.

Figure 4.- Continued.

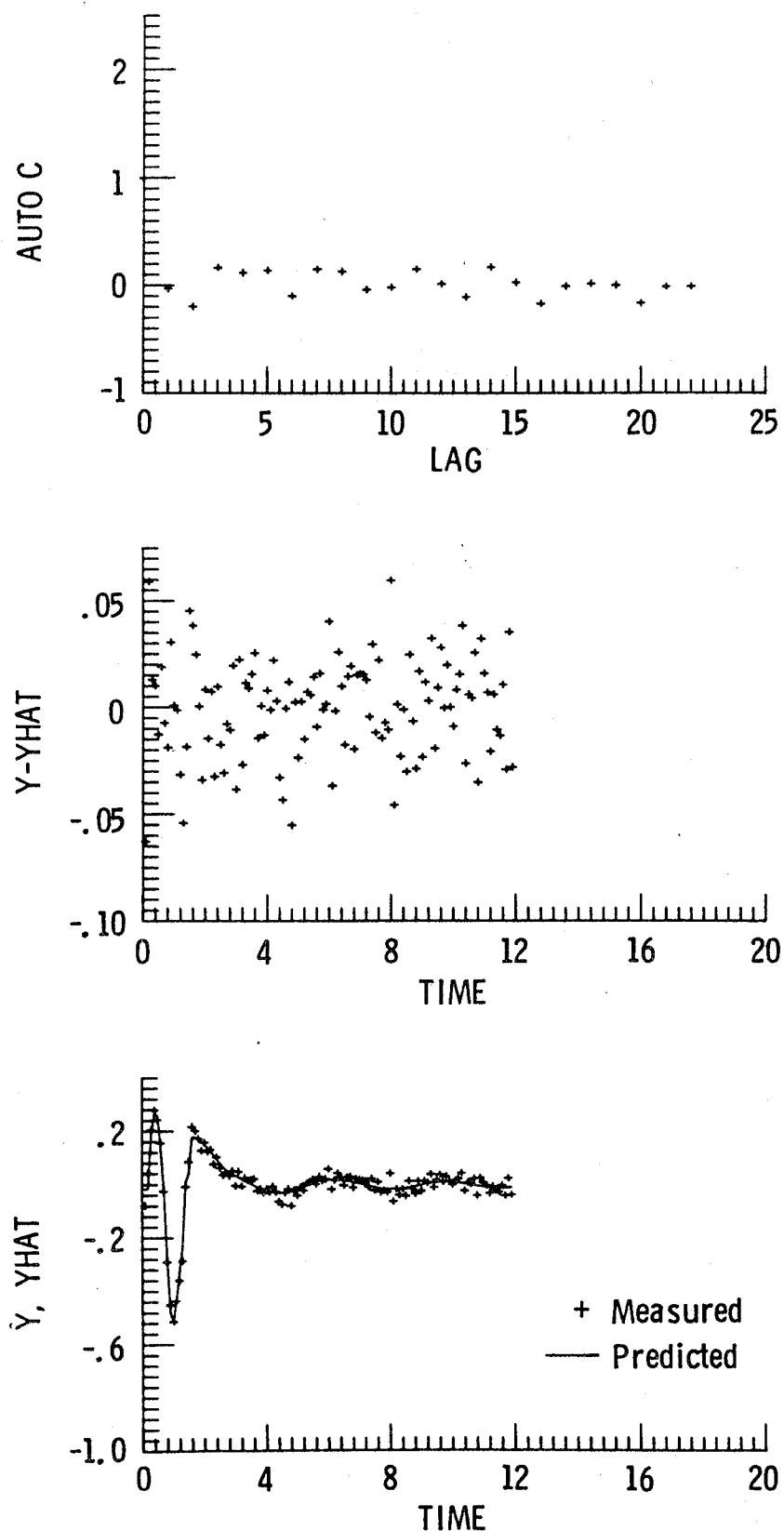


(e) Predicted and estimated pitching moment coefficients,
residual sequence, and autocorrelation function
for four variable model.



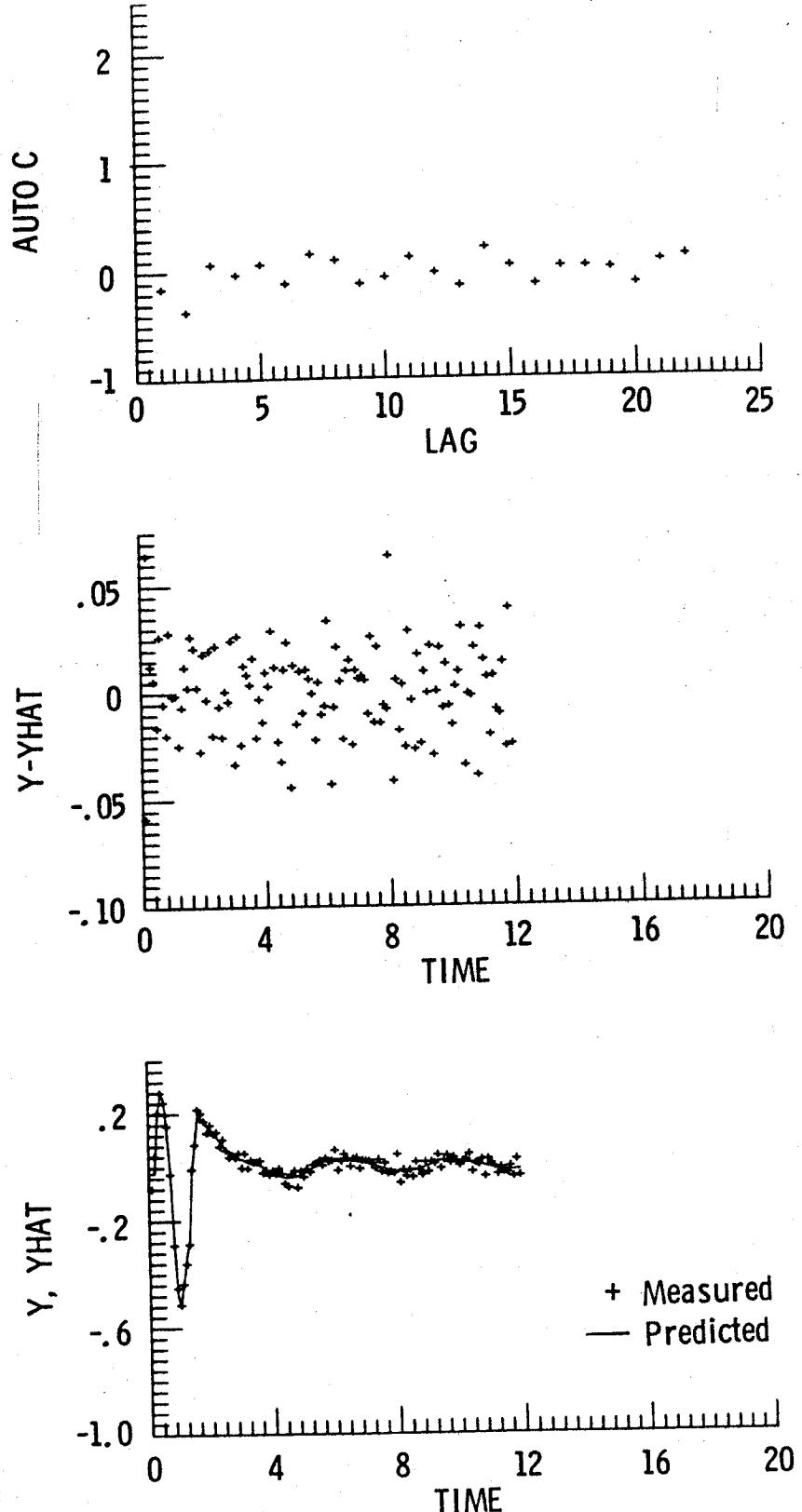
(f) Predicted and estimated pitching moment coefficients, residual sequence, and autocorrelation function for five variable model.

Figure 4.- Continued.



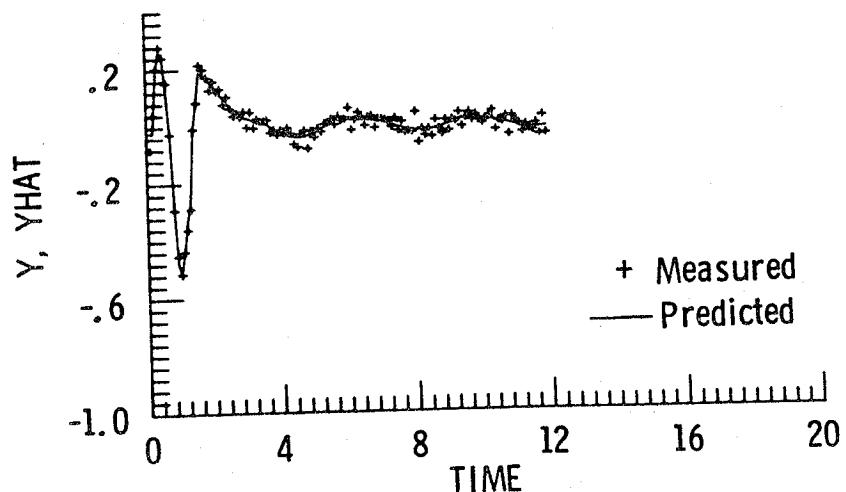
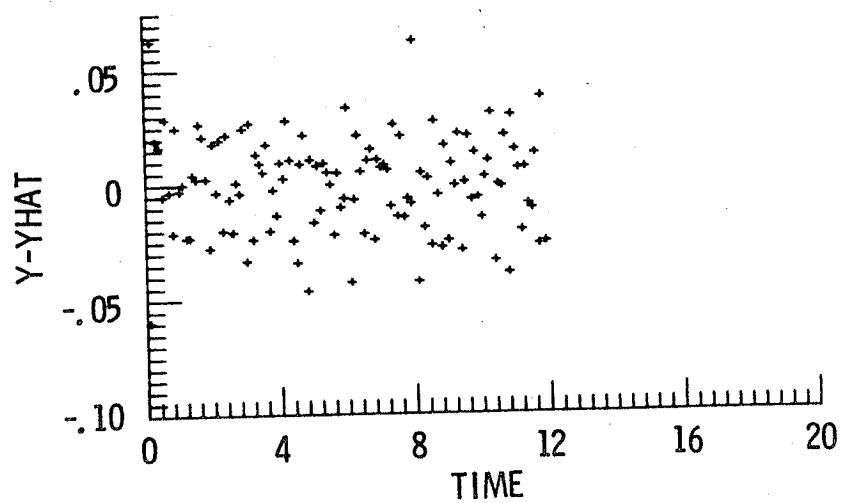
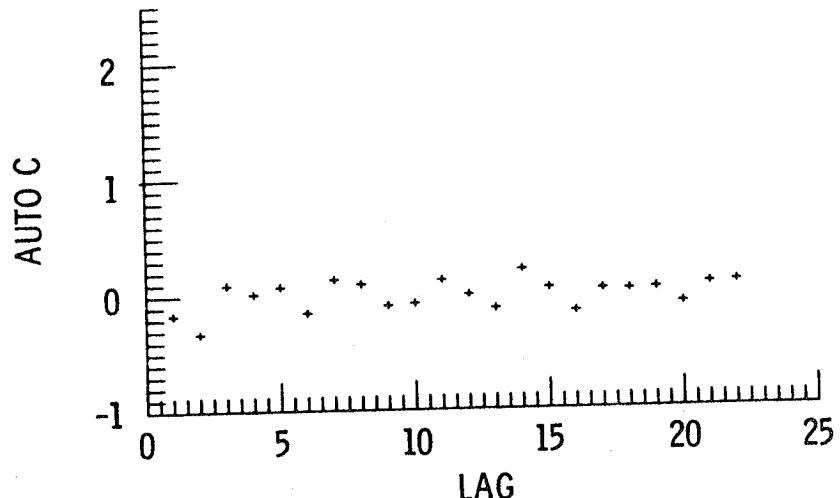
(g) Predicted and estimated pitching moment coefficients,
residual sequence, and autocorrelation function
for six variable model.

Figure 4.- Continued.
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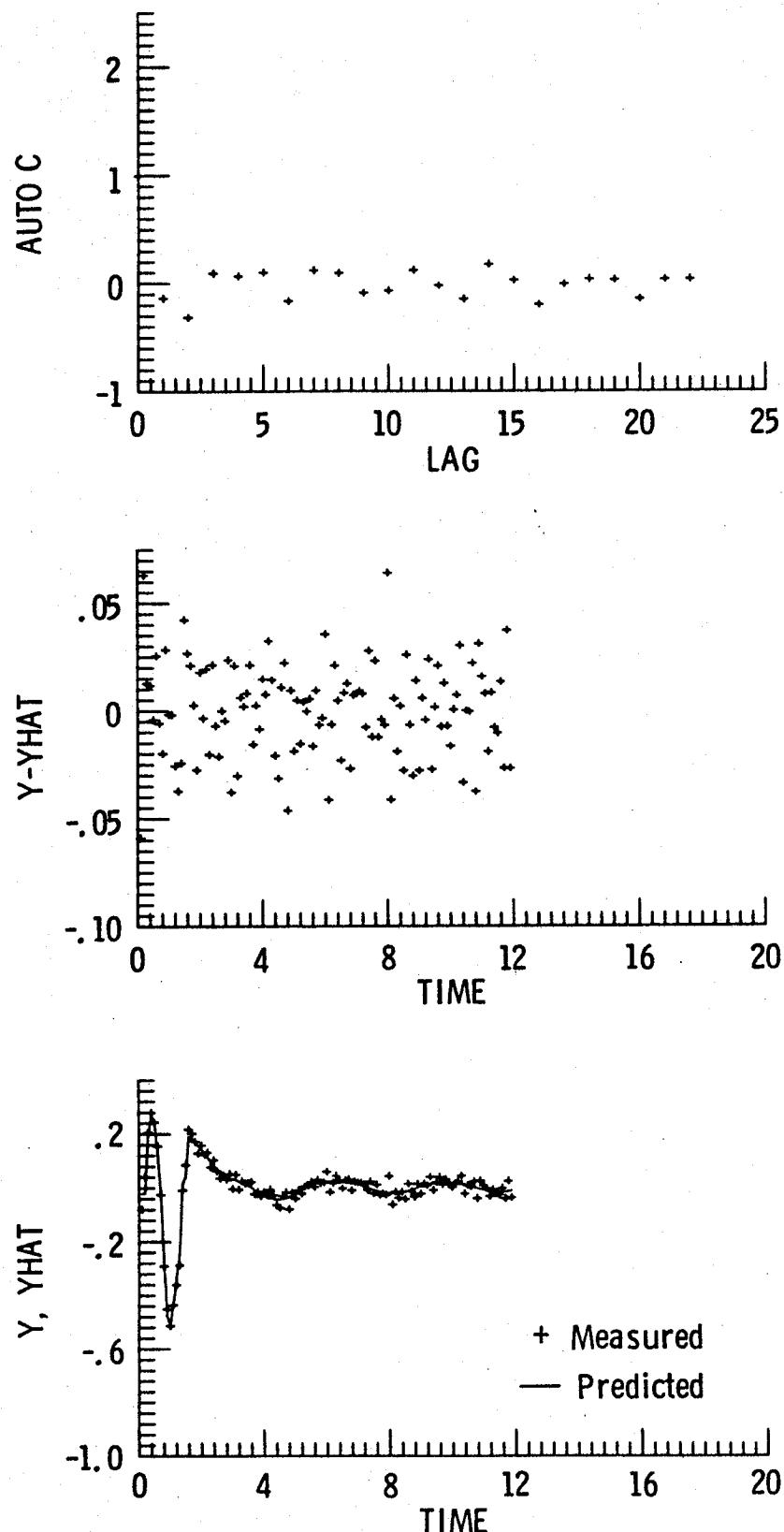


(h) Predicted and estimated pitching moment coefficients,
residual sequence, and autocorrelation function
for seven variable model.

Figure 4.- Continued.

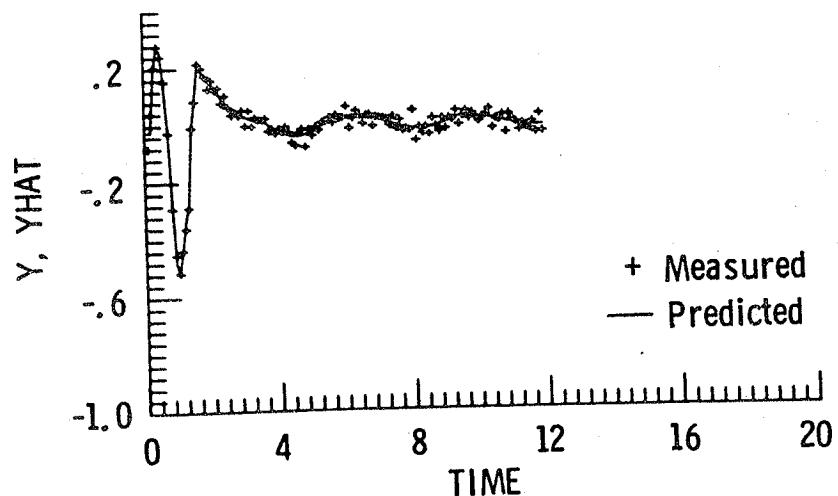
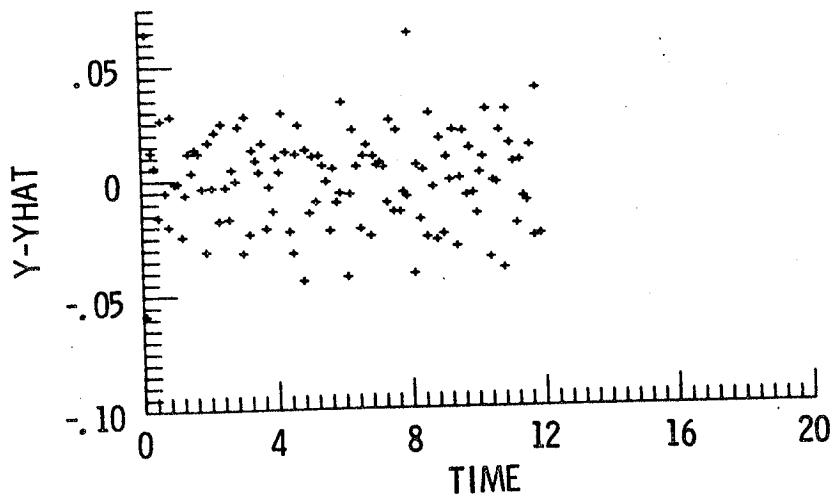
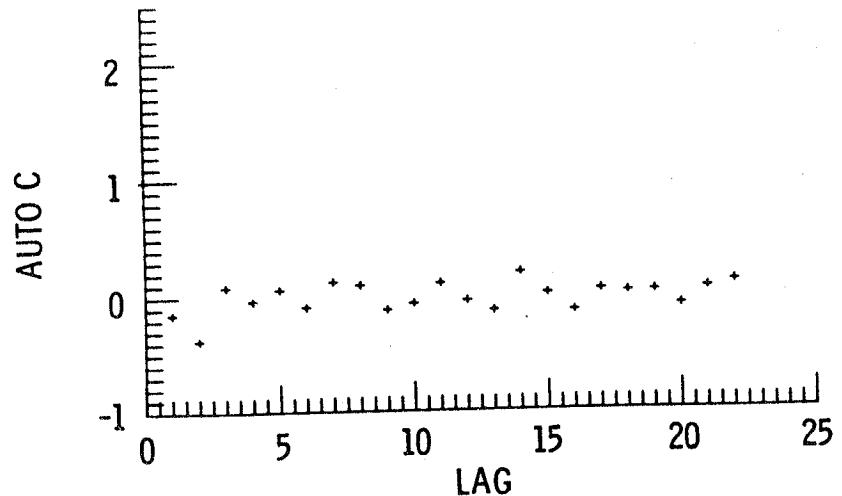


(1) Predicted and estimated pitching moment coefficients, residual sequence, and autocorrelation function for eight variable model.



(j) Predicted and estimated pitching moment coefficients, residual sequence, and autocorrelation function for nine variable model.

Figure 4.- Continued.



(k) Predicted and estimated pitching moment coefficients,
residual sequence, and autocorrelation function
for ten variable model.

Figure 4.- Concluded.

1. Report No. NASA TM-86410	2. Government Accession No.	3. Recipient's Catalog No.	
4. Title and Subtitle STEP and STEPSPL - Computer Programs for Aerodynamic Model Structure Determination and Parameter Estimation		5. Report Date January 1986	
7. Author(s) James G. Batterson		6. Performing Organization Code 505-66-01-04	
9. Performing Organization Name and Address NASA Langley Research Center Hampton, VA 23665-5225		8. Performing Organization Report No.	
12. Sponsoring Agency Name and Address National Aeronautics and Space Administration Washington, DC 20546		10. Work Unit No.	
		11. Contract or Grant No.	
		13. Type of Report and Period Covered Technical Memorandum	
15. Supplementary Notes ORIGINAL PAGE IS OF POOR QUALITY		14. Sponsoring Agency Code	
16. Abstract The successful parametric modeling of the aerodynamics for an airplane operating at high angles of attack or sideslip is performed in two phases. First the aerodynamic model structure must be determined and second the associated aerodynamic parameters (stability and control derivatives) must be estimated for that model. The purpose of this paper is to document two versions of a stepwise regression computer program which were developed for the determination of airplane aerodynamic model structure and to provide two examples of their use on computer generated data. References are provided for the application of the programs to real flight data. The two computer programs that are the subject of this report, STEP and STEPSPL, are written in FORTRAN IV (ANSI 1966) compatible with a CDC FTN4 compiler. Both programs are adaptations of a standard forward stepwise regression algorithm. The purpose of the adaptation is to facilitate the selection of an adequate mathematical model of the aerodynamic force and moment coefficients of an airplane from flight test data. The major difference between STEP and STEPSPL is in the basis for the model. The basis for the model in STEP is the standard polynomial Taylor's series expansion of the aerodynamic function about some steady-state trim condition. Program STEPSPL utilizes a set of spline basis functions.			
17. Key Words (Suggested by Author(s)) system identification parameter estimation stepwise regression equation error		18. Distribution Statement UNCLASSIFIED - UNLIMITED SUBJECT CATEGORY 08	
19. Security Classif. (of this report) UNCLASSIFIED	20. Security Classif. (of this page) UNCLASSIFIED	21. No. of Pages 141	22. Price A07

